

# Introduction to Signal Dependent Transform

*an insertion into Rolands Shavelis presentation*

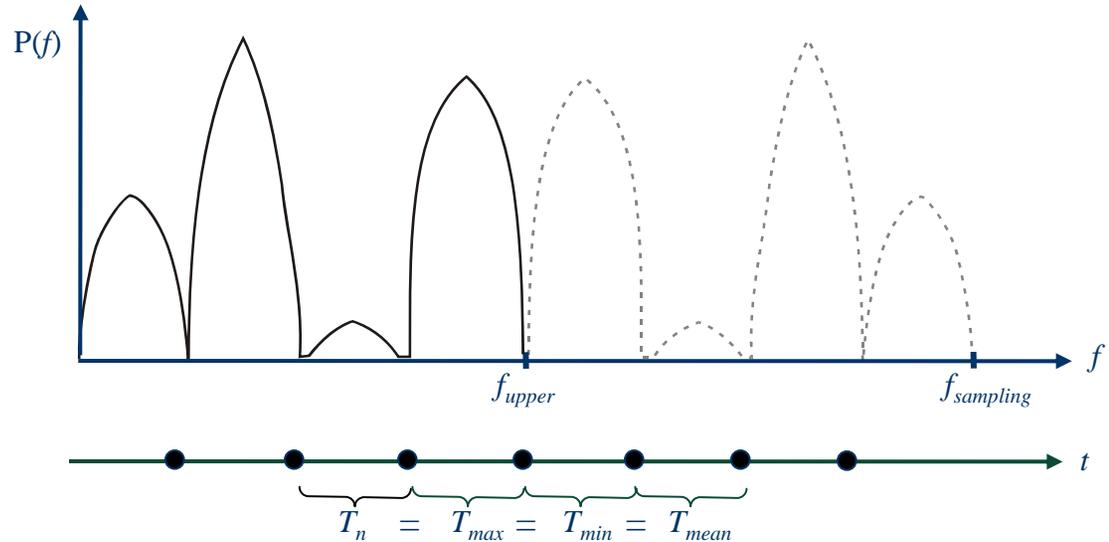
***“Signal dependent sampling and reconstruction”***

# SIGNAL SAMPLING

## □ Uniform sampling

$$f_{\text{sampl}} = 2f_{\text{upper}}$$

$$T = \frac{1}{2f_{\text{upper}}}$$



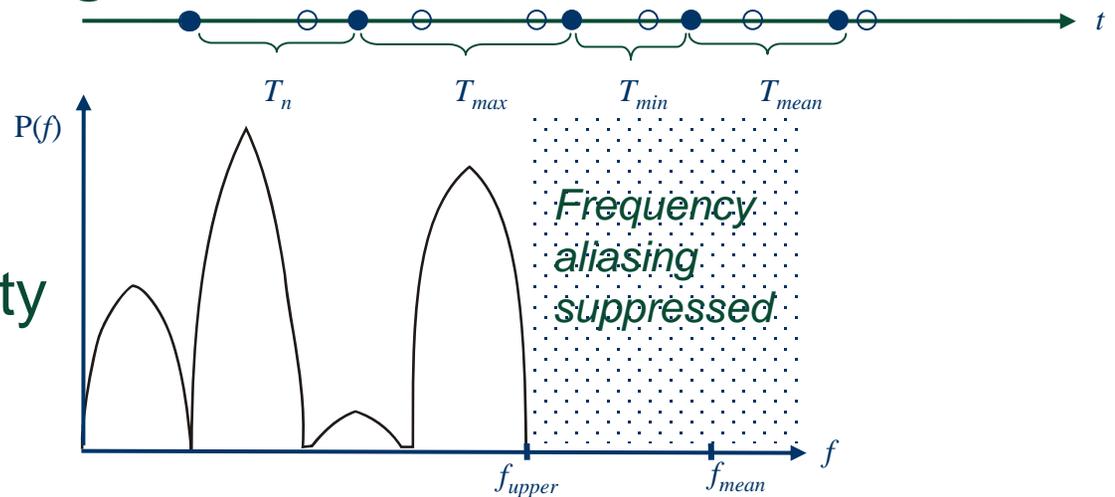
## □ Nonuniform sampling

$T_{\text{max}}$  – maximal gap

$T_{\text{min}}$  – minimal gap

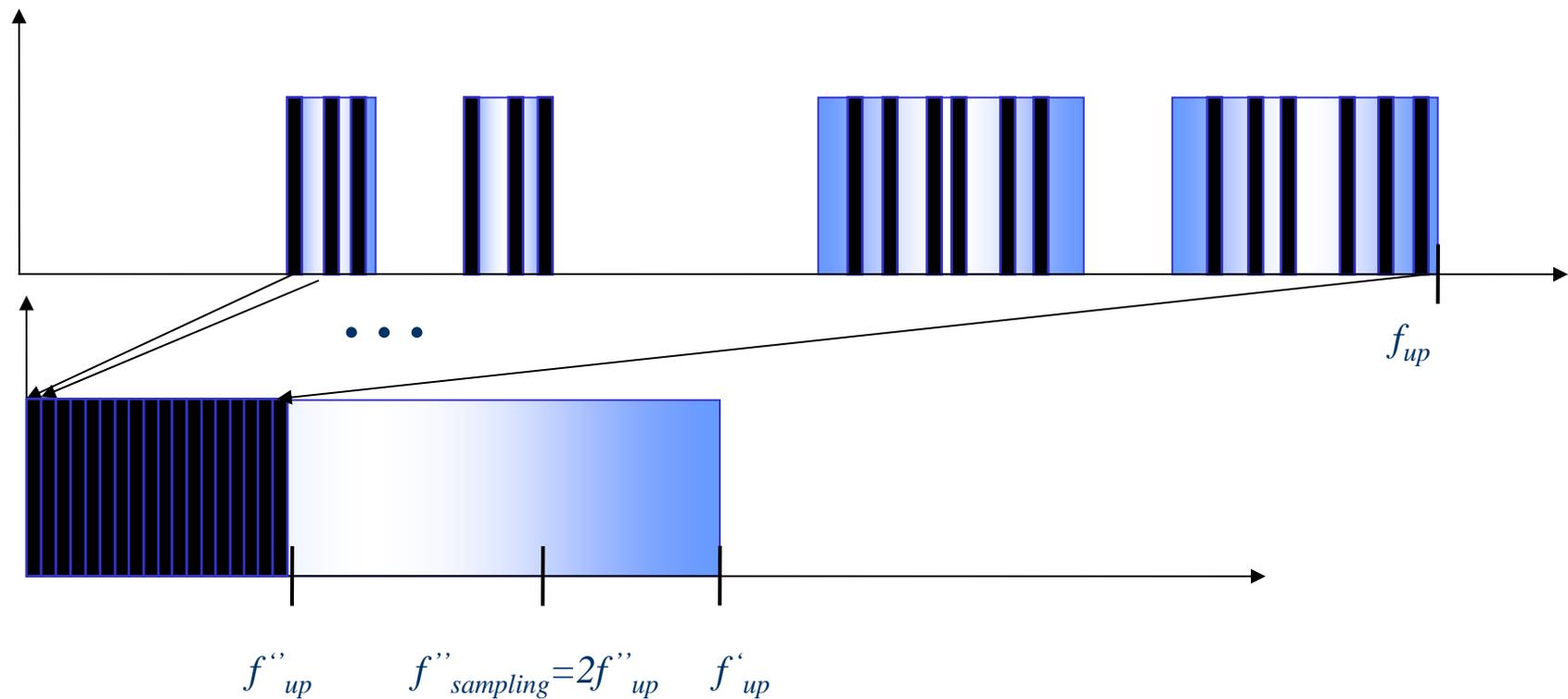
$T_{\text{mean}}$  – sampling density

$$f_{\text{mean}} = \frac{1}{T_{\text{mean}}}$$

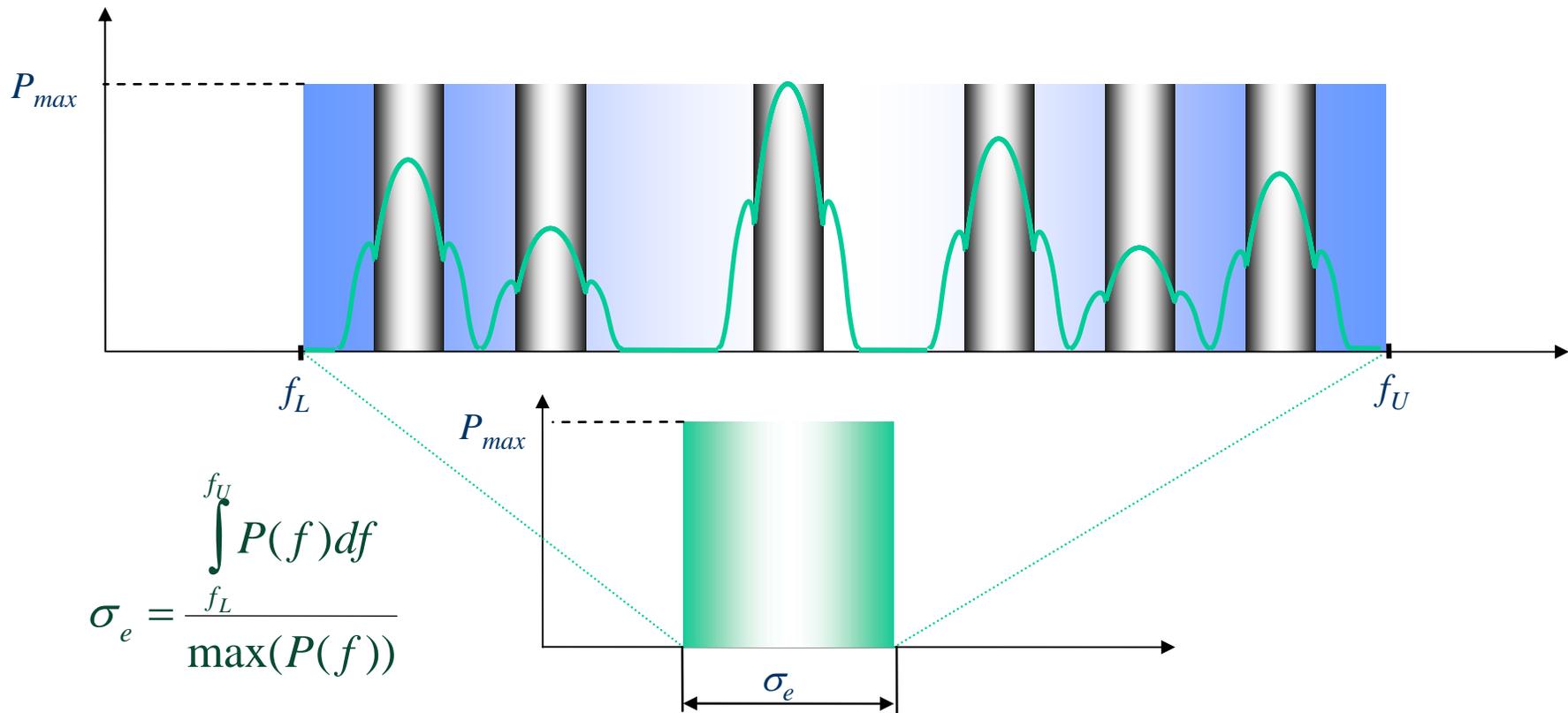


# SIGNAL SAMPLING

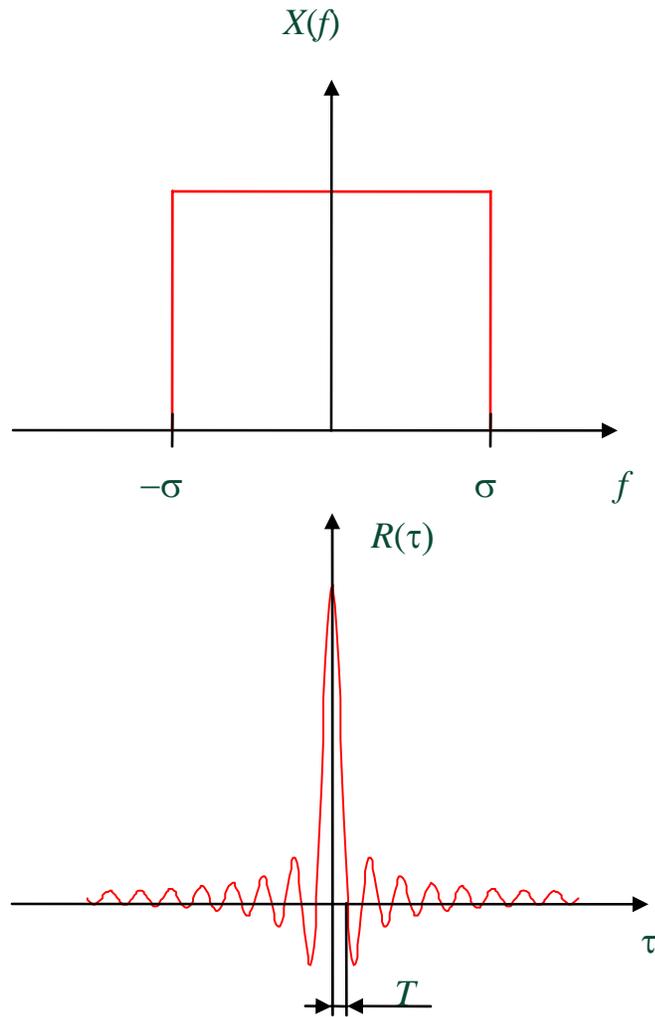
## *Multi-channel multiband signal*



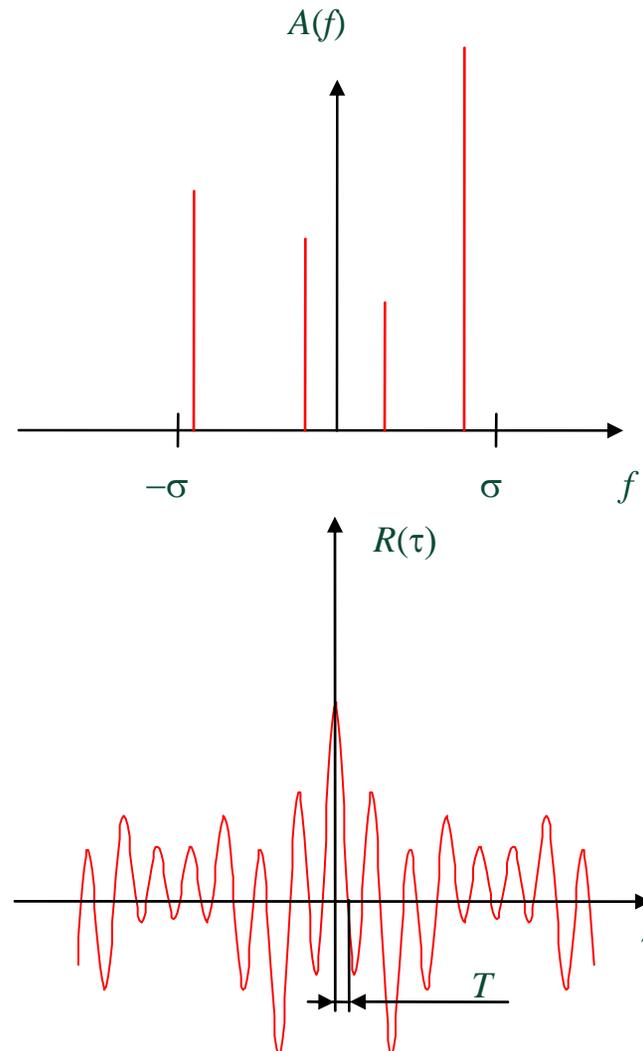
# EQUIVALENT SIGNAL BANDWIDTH



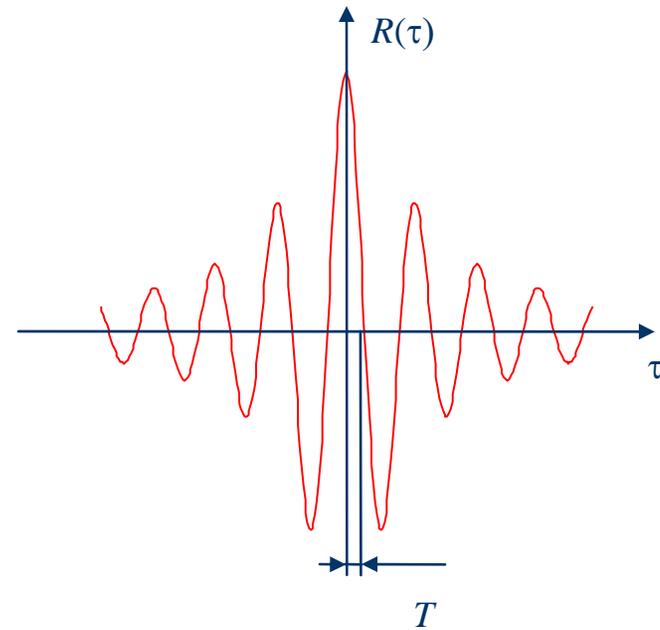
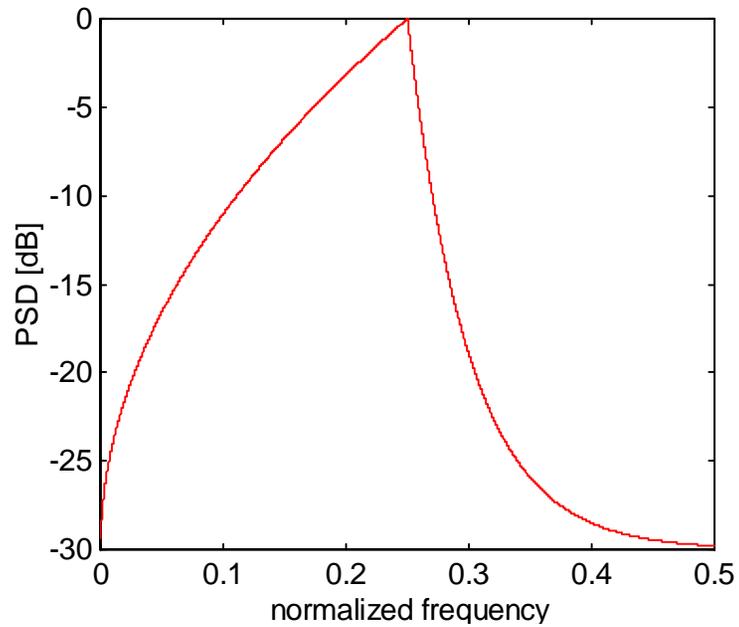
## Signal with a flat PSD function



## Multiple sinusoids signal



## Coloured noise



$$\sigma_e = \frac{\int_{-\sigma}^{\sigma} P(f) df}{\max(P(f))}$$

$$\sigma_e \approx \frac{1}{3} \sigma$$

$$T_e = \frac{1}{\sigma_e}$$

## PROCESSING IN TIME DOMAIN

### □ Signal reconstruction:

$$x(t) = \sum_{n=1}^N c_n s(t - t_n); \quad s(t) - \text{constructing function}$$

### □ WKS theorem:

$$x(t) = \sum_{n=-\infty}^{\infty} x(nT) \text{sinc}([t - nT]/T) \Rightarrow x(t) = \sum_{n=1}^N x_n \text{sinc}(2f_u[t - t_n])$$

$$\Rightarrow s(t) = \text{sinc} 2f_u t = \frac{\sin 2\pi f_u t}{2\pi f_u t}$$

### □ Nonuniform sampling case:

$$x(t) = \sum_{n=1}^N c_n \text{sinc}(2f_u[t - t_n]); \quad \mathbf{Sc} = \mathbf{x}; \quad S_{mn} = s(t_m - t_n)$$

**TIME DOMAIN**



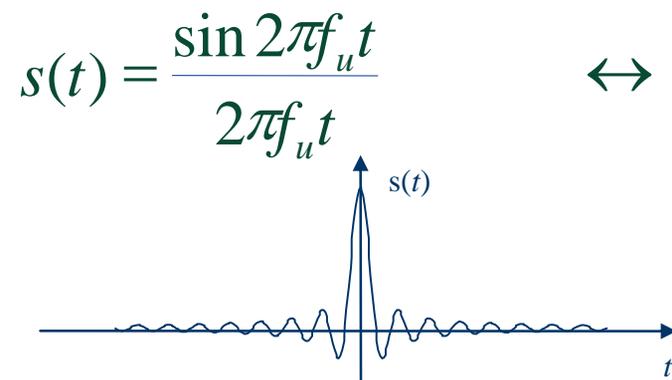
**FREQUENCY DOMAIN**

**Fourier transform:**

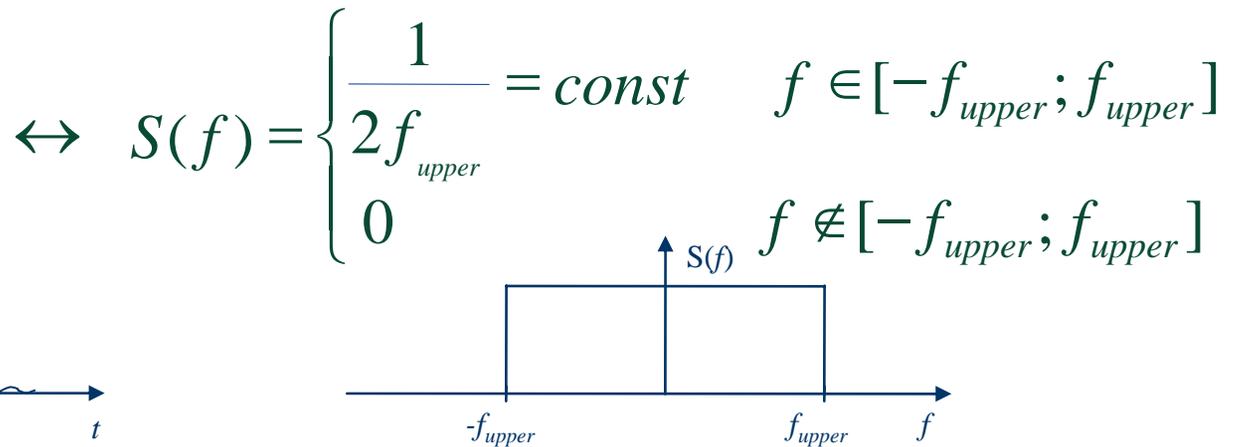
$$X(f) = \int_{-\infty}^{\infty} x(t) \exp(-i2\pi ft) dt = F(x(t))$$

$$x(t) = \int_{-\infty}^{\infty} X(f) \exp(i2\pi ft) df = F^{-1}(X(f))$$

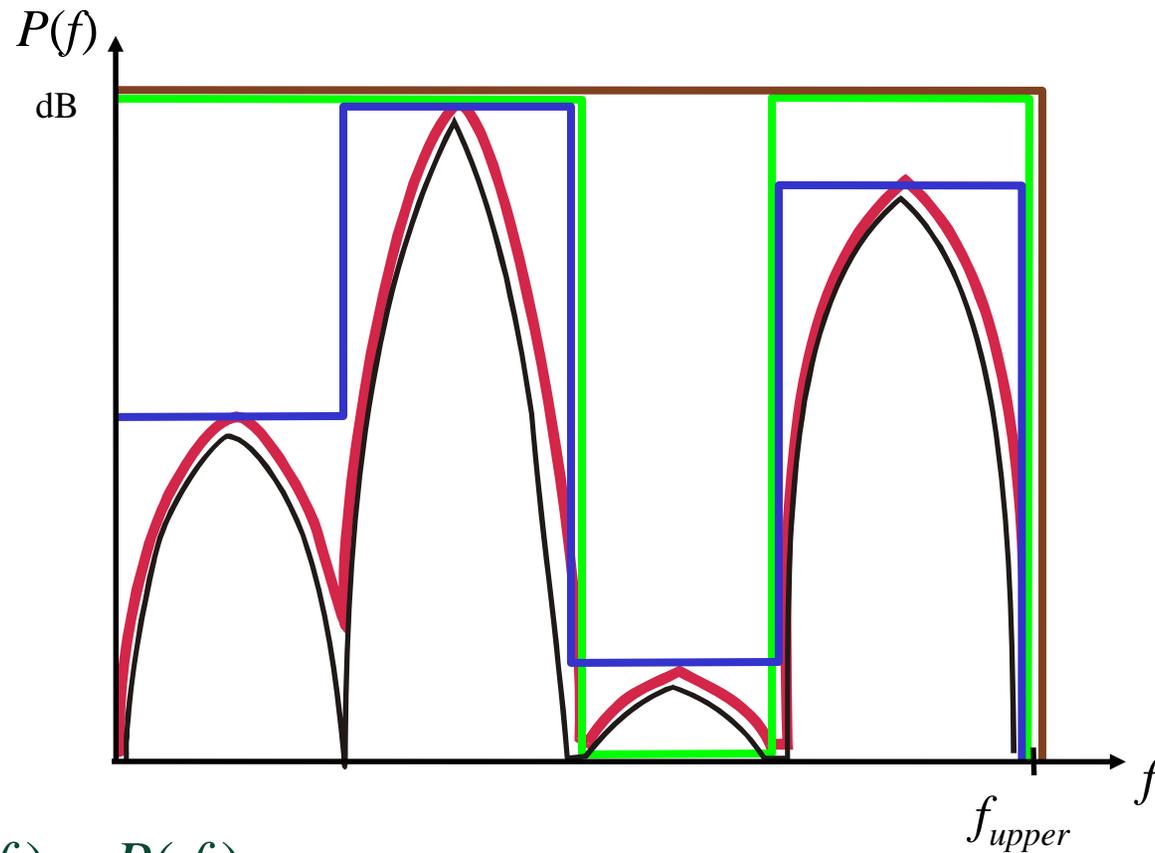
**Constructing function**



**Spectral support function**



# SPECTRAL SUPPORT FUNCTION



$$S(f) = P(f)$$

$$s(t) = F^{-1}(S(f)) = r(t) \quad - \quad \text{autocorrelation function}$$

## ACF-based RECONSTRUCTION

- Signal waveform reconstruction:

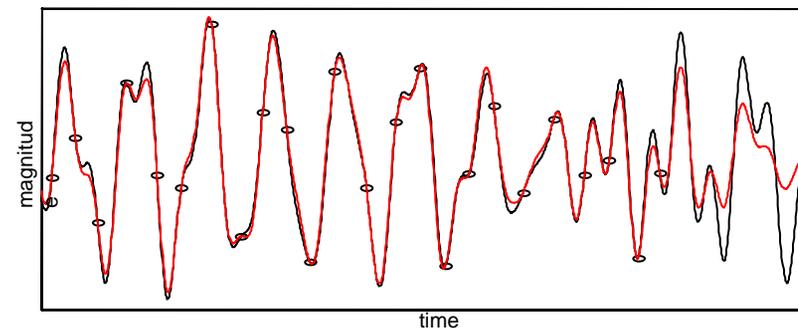
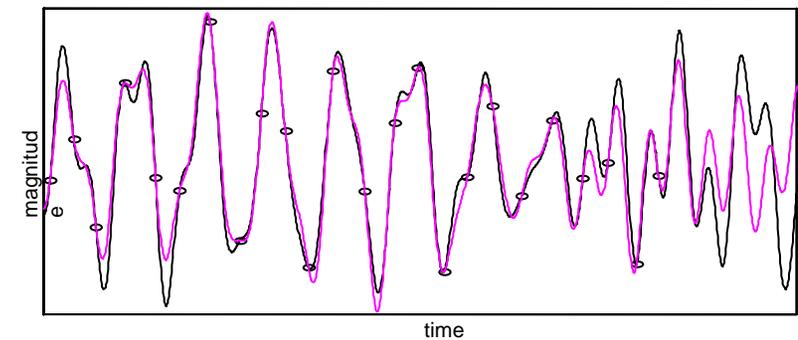
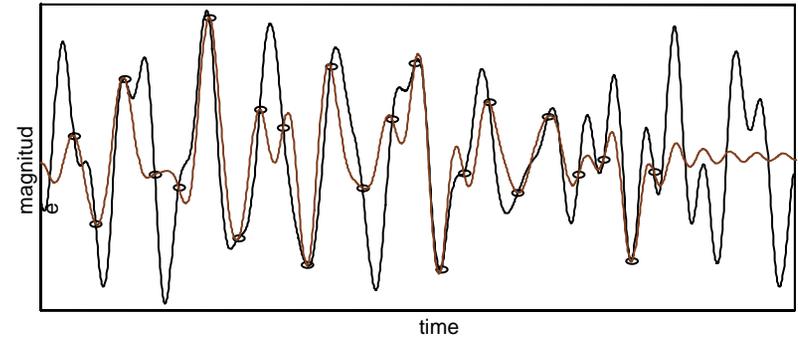
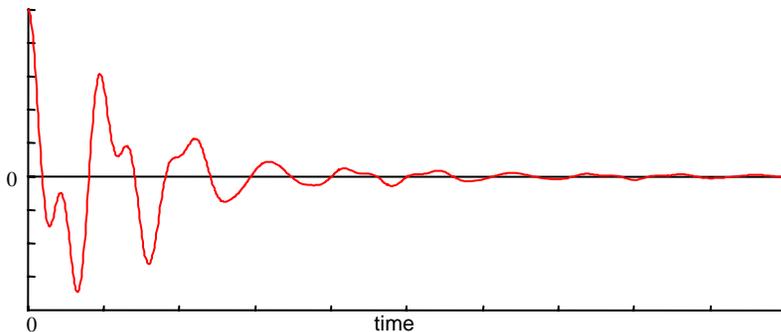
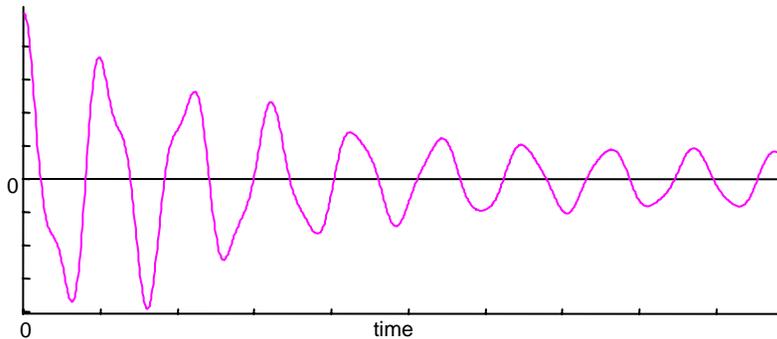
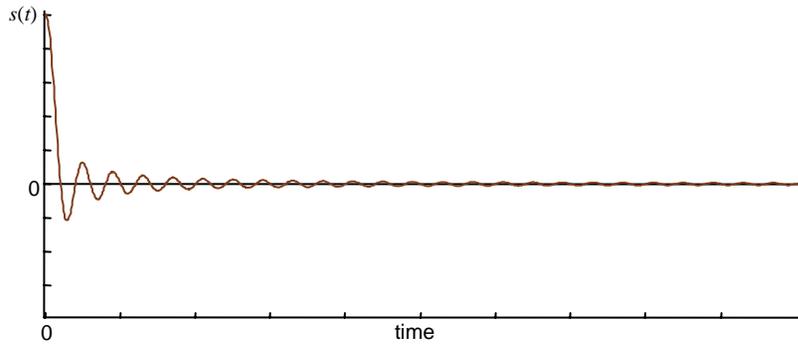
$$x_r(t) = \sum_{n=1}^N c_n r(t - t_n); \quad c_n \rightarrow \mathbf{Rc} = \mathbf{x}; \quad R_{mn} = r(t_m - t_n)$$

$r(t)$  - autocorrelation function  $\leftarrow$  a priori  
iteratively

- Signal spectral analysis:

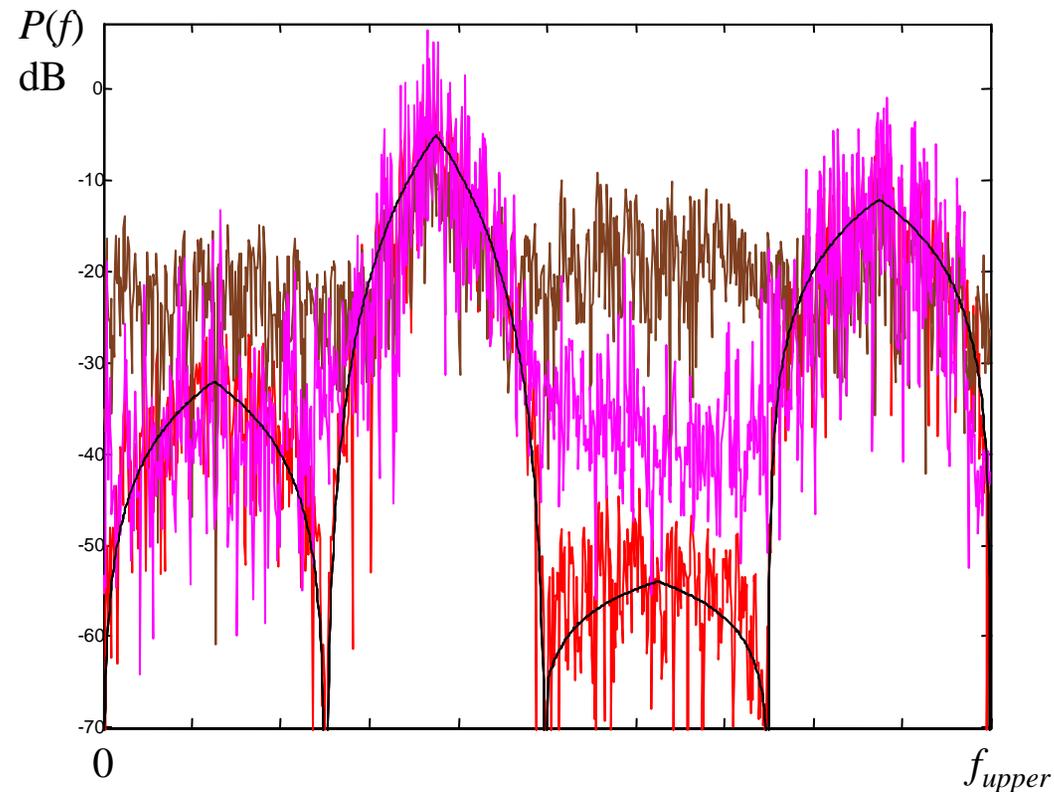
$$X_r(f) = \int_{-\infty}^{\infty} x_r(t) \exp(-i2\pi ft) dt = \int_{-\infty}^{\infty} \sum_{n=1}^N c_n r(t - t_n) \exp(-i2\pi ft) dt$$

# EXAMPLE: WAVEFORM RECONSTRUCTION



$$N = 256; \quad T_{min} = 1.5T; \quad T_{max} = 2.5T; \quad T_{mean} = 2T$$

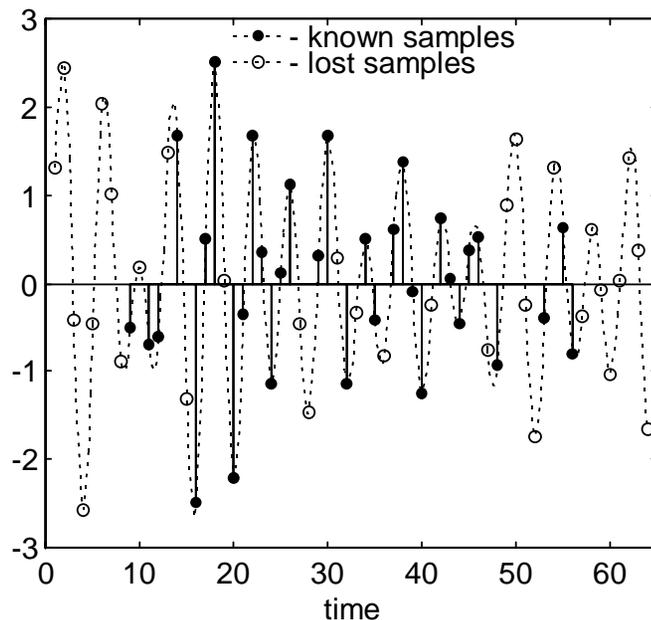
## EXAMPLE: PSD FROM RECONSTRUCTED SIGNAL



$$N = 256; \quad T_{min} = 1.5T; \quad T_{max} = 2.5T; \quad T_{mean} = 2T$$

## RECONSTRUCTION OF LOST SAMPLES

- Data vector  $\mathbf{x}$  is obtained from band-limited to  $\sigma$  function  $x(t)$  by uniform sampling according to Whittaker-Kotelnikov-Shannon theorem without oversampling.

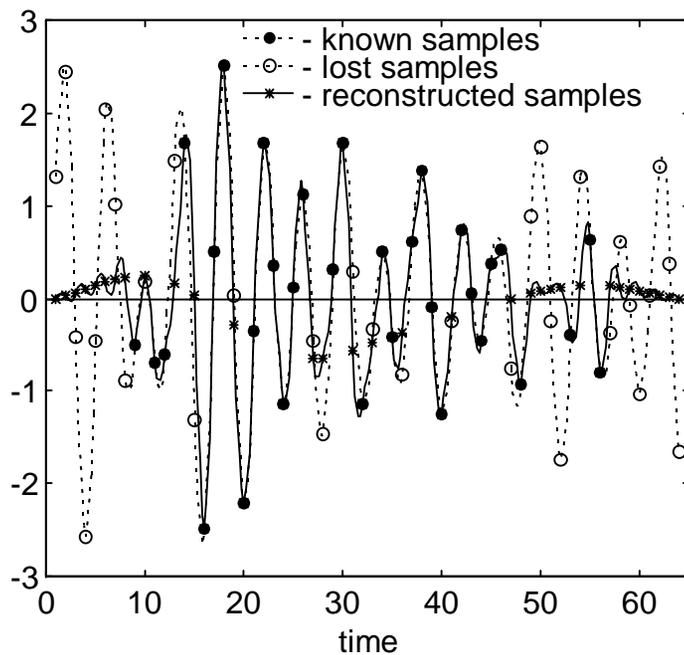


- The frame of  $N=64$  signal samples is taken.
- The  $N_l=32$  signal samples are lost.
- The  $N_k=32$  signal samples are known.
- $L = \{l_1, \dots, l_{N_l}\}$  – set of subscripts of the lost samples.
- $K = \{k_1, \dots, k_{N_k}\}$  – set of subscripts of known samples.
- $\mathbf{y} = \mathbf{x}(K)$  – the vector of known samples
- The problem is to recover the lost samples  $\mathbf{z} = \mathbf{x}(L)$

## Minimum Norm Least Squares (MNLS) solution

$$\mathbf{z} = \mathbf{A}\mathbf{v}, \quad A_{m,n} = \frac{\sin 2\pi(l_m - k_n)T\sigma}{\pi(l_m - k_n)T}$$

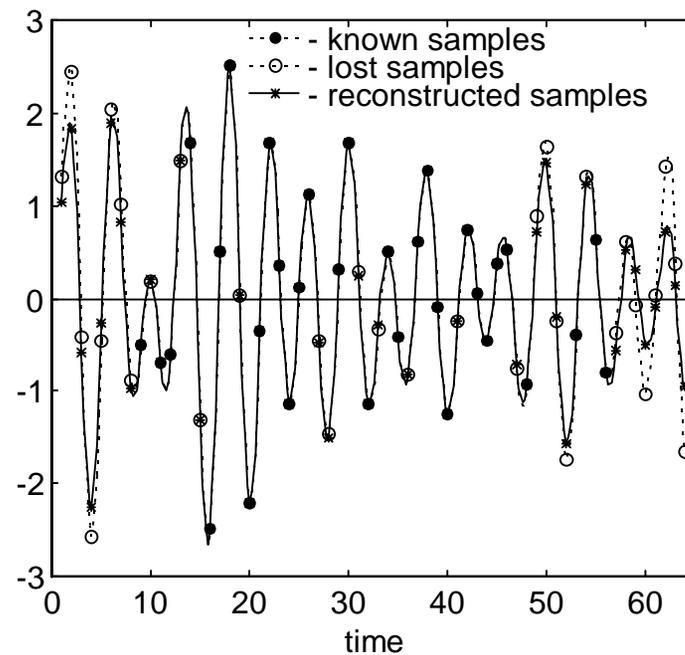
$$\mathbf{B}\mathbf{v} = \mathbf{y}, \quad B_{m,n} = \frac{\sin 2\pi(k_m - k_n)T\sigma}{\pi(k_m - k_n)T}$$



## Minimum mean-square (Wiener filter) solution

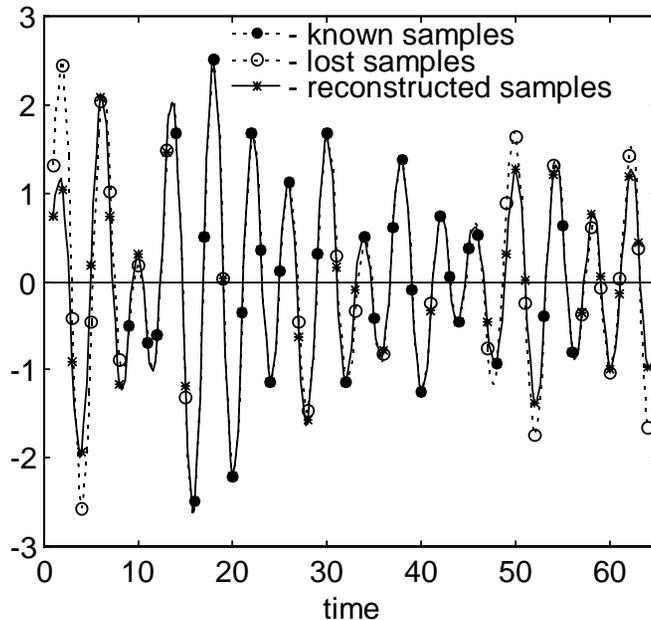
$$\mathbf{z} = \mathbf{C}\mathbf{w}, \quad C_{mn} = R((l_m - k_n)T)$$

$$\mathbf{R}\mathbf{w} = \mathbf{y}, \quad R_{mn} = R((k_m - k_n)T)$$



## Proposed approach to recovering of lost samples

In absence of any additional information



$$\hat{\mathbf{R}}^{(0)} = \left| \frac{\hat{\mathbf{x}}^{(0)} \mathbf{E}}{N} \right|^2 \mathbf{E}, \quad E_{m,n} = \exp(-j2\pi mn/N)$$

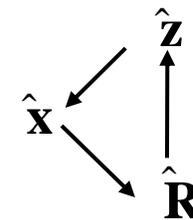
$$\hat{\mathbf{x}}^{(0)} = [\mathbf{y} \ \mathbf{z}^{(0)}], \quad \mathbf{z}^{(0)} = 0 \text{ or MNLS solution}$$

$$\begin{cases} \mathbf{z}^{(i)} = \mathbf{C}^{(i)} \mathbf{w}^{(i)} \\ \hat{\mathbf{R}}^{(i)} \mathbf{w}^{(i)} = \mathbf{y} \end{cases}$$

$$\hat{\mathbf{x}}^{(i)} = [\mathbf{y} \ \mathbf{z}^{(i)}]$$

$$\hat{\mathbf{R}}^{(i+1)} = \left| \frac{\hat{\mathbf{x}}^{(i)} \mathbf{E}}{N} \right|^2 \mathbf{E}$$

$$\Delta = \left\| \mathbf{z}^{(i+1)} - \mathbf{z}^{(i)} \right\|$$



# PROCESSING IN FREQUENCY DOMAIN

## □ Spectral analysis:

$$X(f) = \sum_{n=1}^N x_n W(f, t_n);$$

$W(f, t_n)$  - transformation kernel

## □ Fourier transform:

$$X(f) = \sum_{n=1}^N x_n \exp(-i2\pi f t_n)$$
$$W(f, t_n) = \{ \exp(-i2\pi f t_n) \}$$

# ACF-based SPECTRAL ANALYSIS

## □ Spectrum:

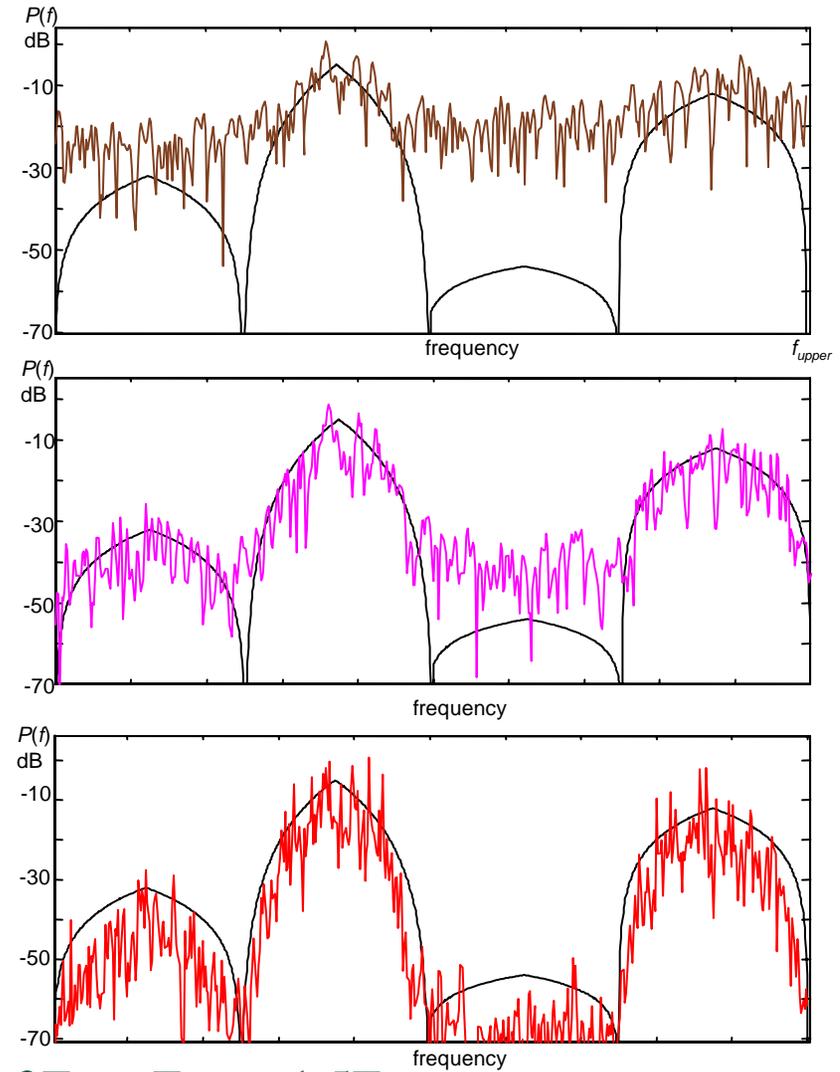
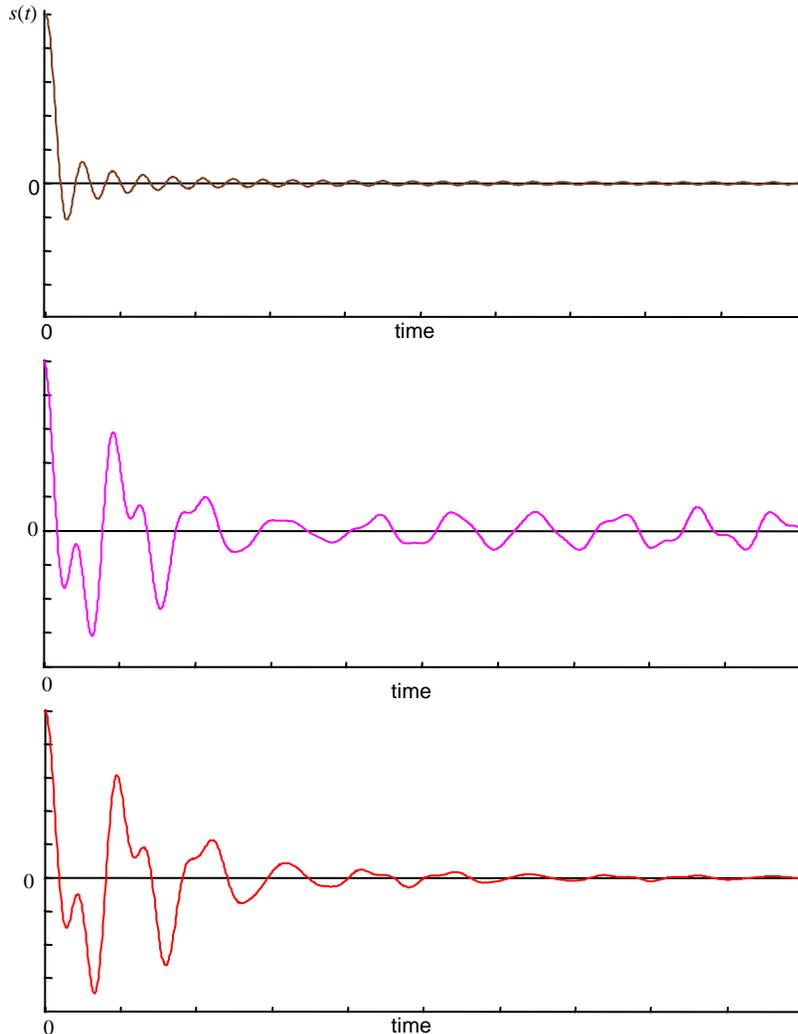
$$X_r(f) = \sum_{n=1}^N x_n \sum_{m=1}^N R_{nm}^{-1} \exp(-i2\pi f t_n);$$

$$R_{nm}^{-1} = (\mathbf{R}^{-1})_{nm}; \quad R_{mn} = r(t_m - t_n)$$

## □ Waveform:

$$x(t) = F^{-1}(X_r(f)) = \int_{-\infty}^{\infty} \left( \sum_{n=1}^N x_n \sum_{m=1}^N R_{nm}^{-1} \exp(-i2\pi f t_n) \right) \exp(i2\pi f t) df;$$

# EXAMPLES: SPECTRAL ANALYSIS



$$N = 256; \quad T_{min} = T; \quad T_{max} = 2T; \quad T_{mean} = 1.5T$$

## SIGNAL DEPENDENT TRANSFORM

- **Narrowband filter -** 
$$y_n = \sum_{k=1}^K a_k x_{n-k}$$
- **Variance of the output process -** 
$$\rho = \mathbf{a}^H \mathbf{R} \mathbf{a}$$
- **Additional condition -** 
$$\sum_{k=1}^K a_k \exp(-j2\pi f_0 t_k) = \mathbf{e}^H(f_0) \mathbf{a} = 1$$
- **Coefficients of Minimum Variance (MV) filter -** 
$$\mathbf{a}(f_0) = \frac{\mathbf{R}^{-1} \mathbf{e}(f_0)}{\mathbf{e}^H(f_0) \mathbf{R}^{-1} \mathbf{e}(f_0)}$$

### *Features:*

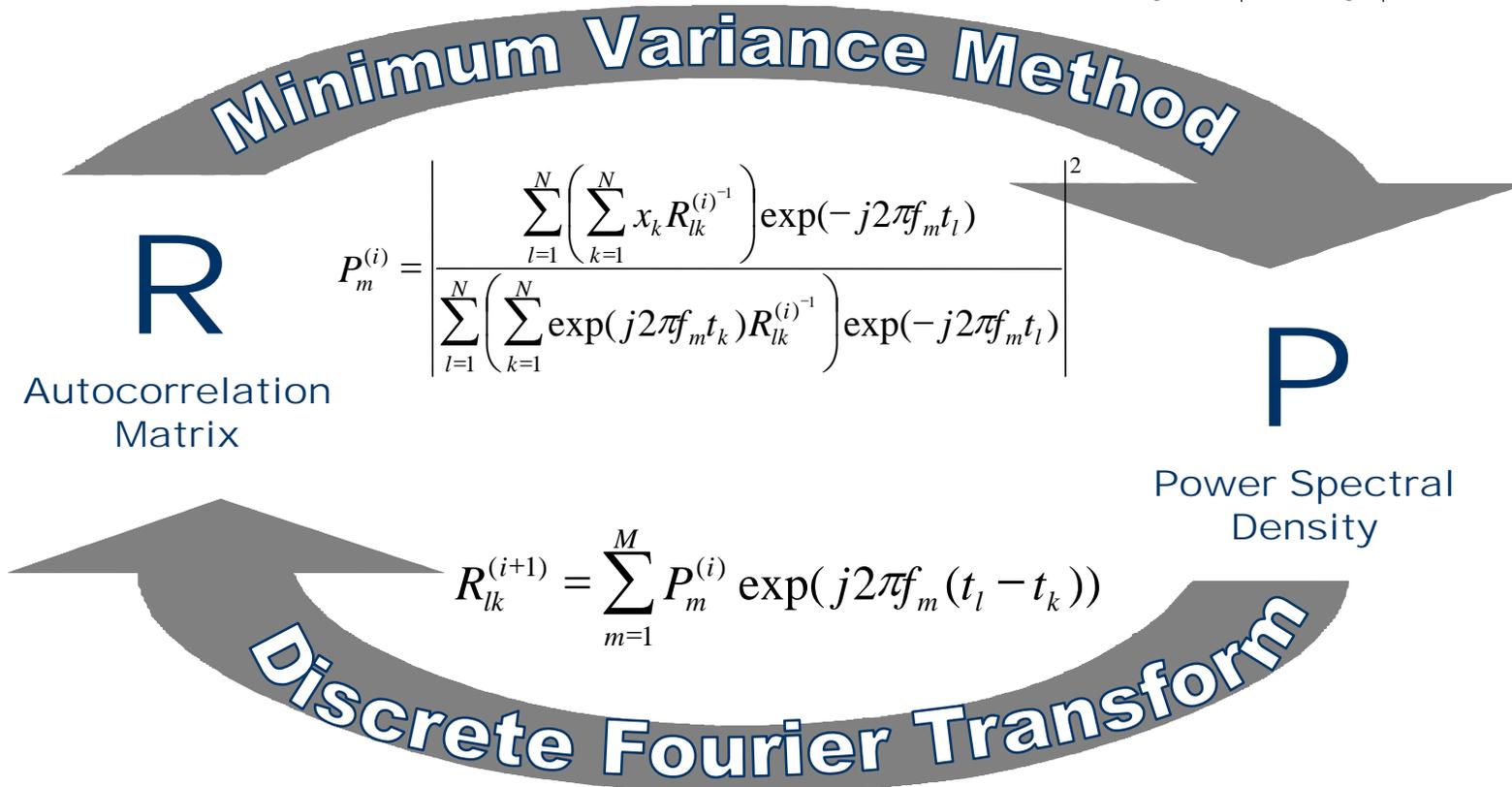
- **Processing at determined frequencies**
- **Complex spectral value (similarity to DFT -  $\mathbf{a}^{(F)}(f_0) = \exp(2\pi f_0 t)$ )**
- **Adaptation to the signal on each frequency (use of autocorrelation matrix)**

# ITERATIVE UPDATING OF R MATRIX

- Averaging of mutual products of samples not applicable -  $t_k - t_n \neq t_{k+i} - t_{n+i}$

- Relation of SAF and PSD -  $R(\tau) = \int_{f_L}^{f_U} P(f) \exp(j2\pi f \tau) df$

- Power spectral density (PSD) -  $P(f_0) = |\mathbf{xa}(f_0)|^2$

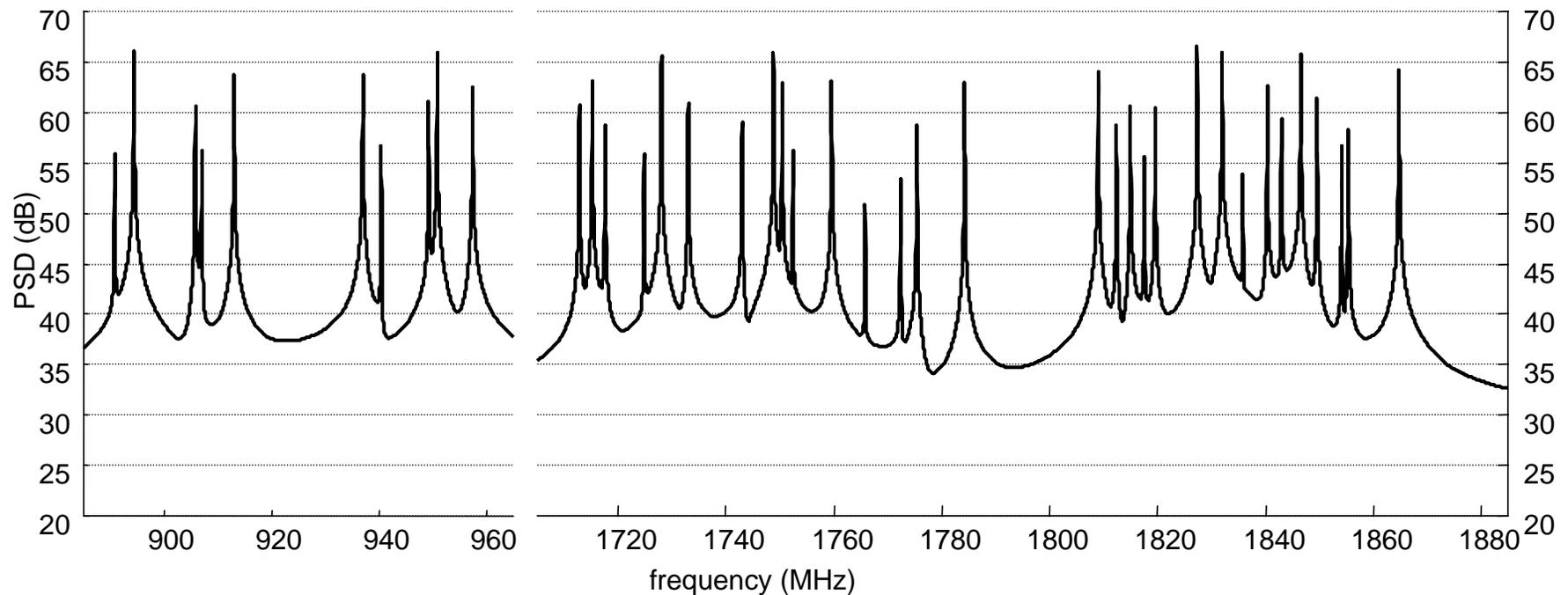


# GSM SIGNAL EXAMPLE

## *Simulation parameters:*

40 frequency slots in 4 bands: 890-915 MHz, 935-960 MHz, 1710-1785 MHz, 1805-1880 MHz are used.

Total bandwidth – 200 MHz, equivalent – 20 MHz.



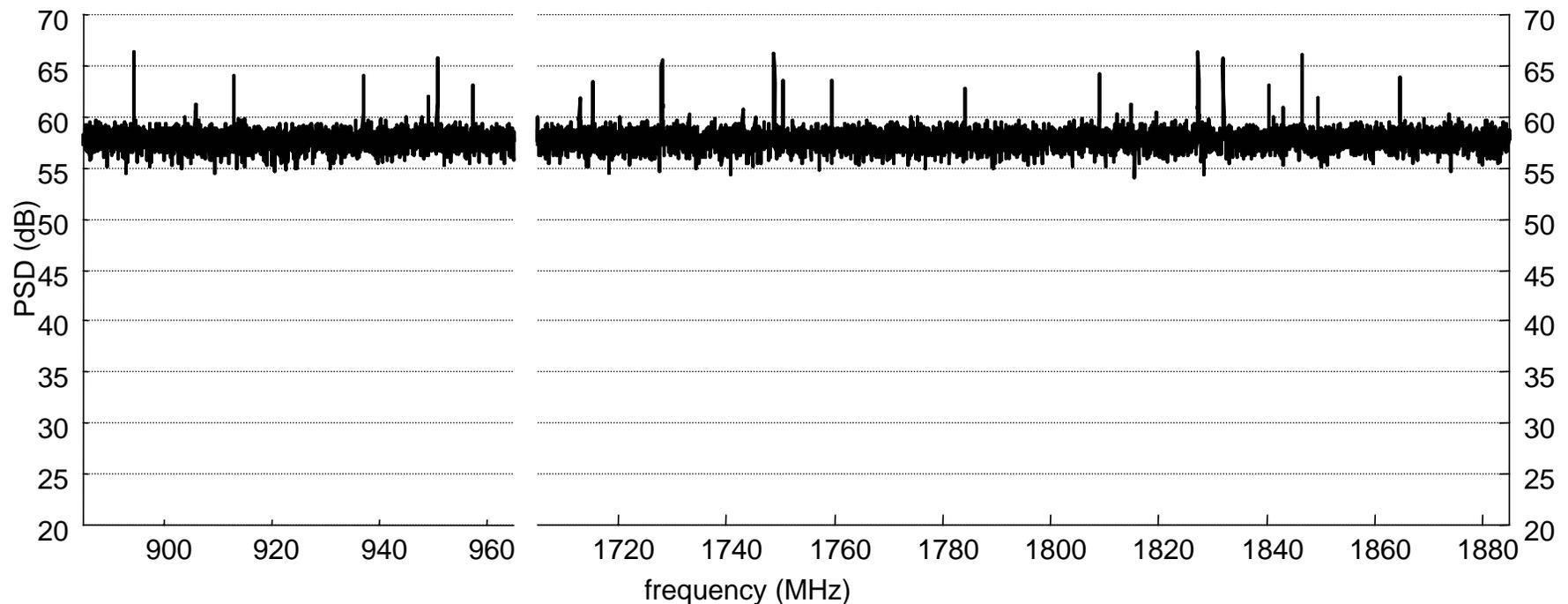
**Uniform 4GHz sampling, DFT**

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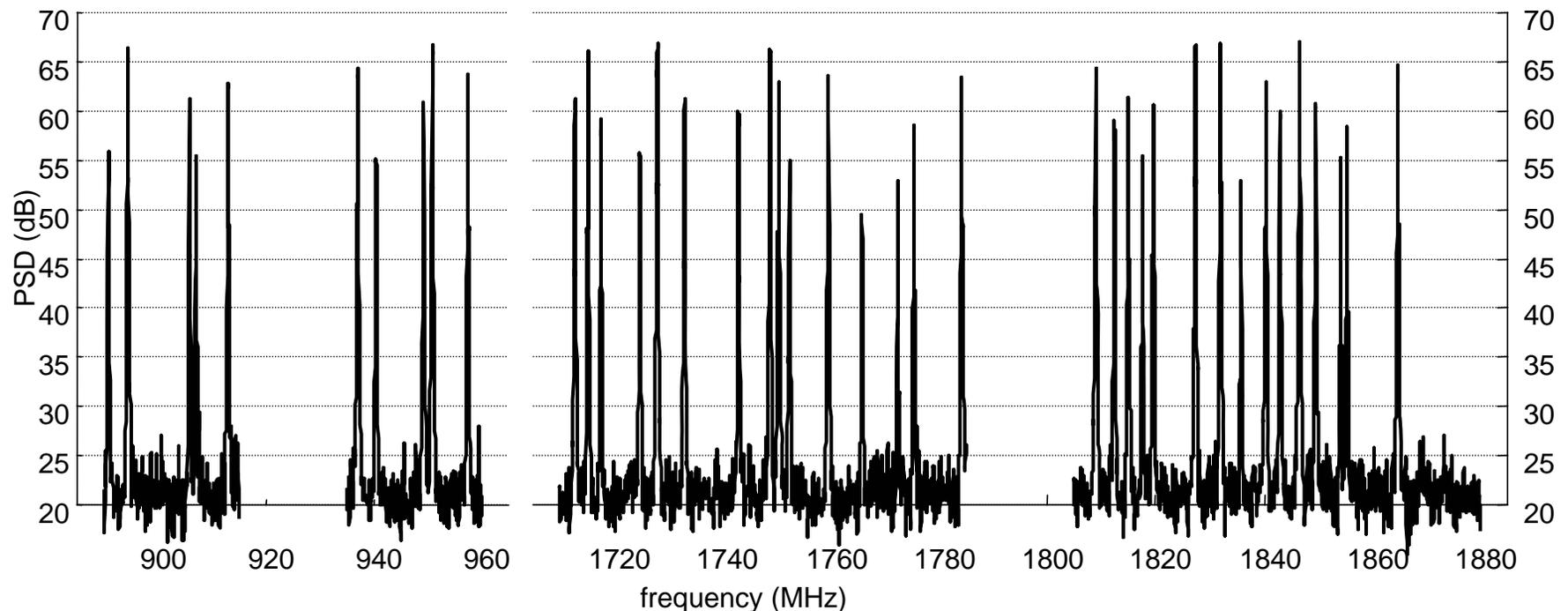
**Nonuniform sampling 62.5 MSamples/s is obtained from uniform sampling 4GHz ( $\approx 1.56\%$  from all samples are left), DFT**

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**Nonuniform sampling 62.5 MSamples/s is obtained from uniform sampling 4GHz ( $\approx$  1.56% from all samples are left), iterative MV**

# RECONSTRUCTION RELIABILITY

Reliability in logarithmical form:

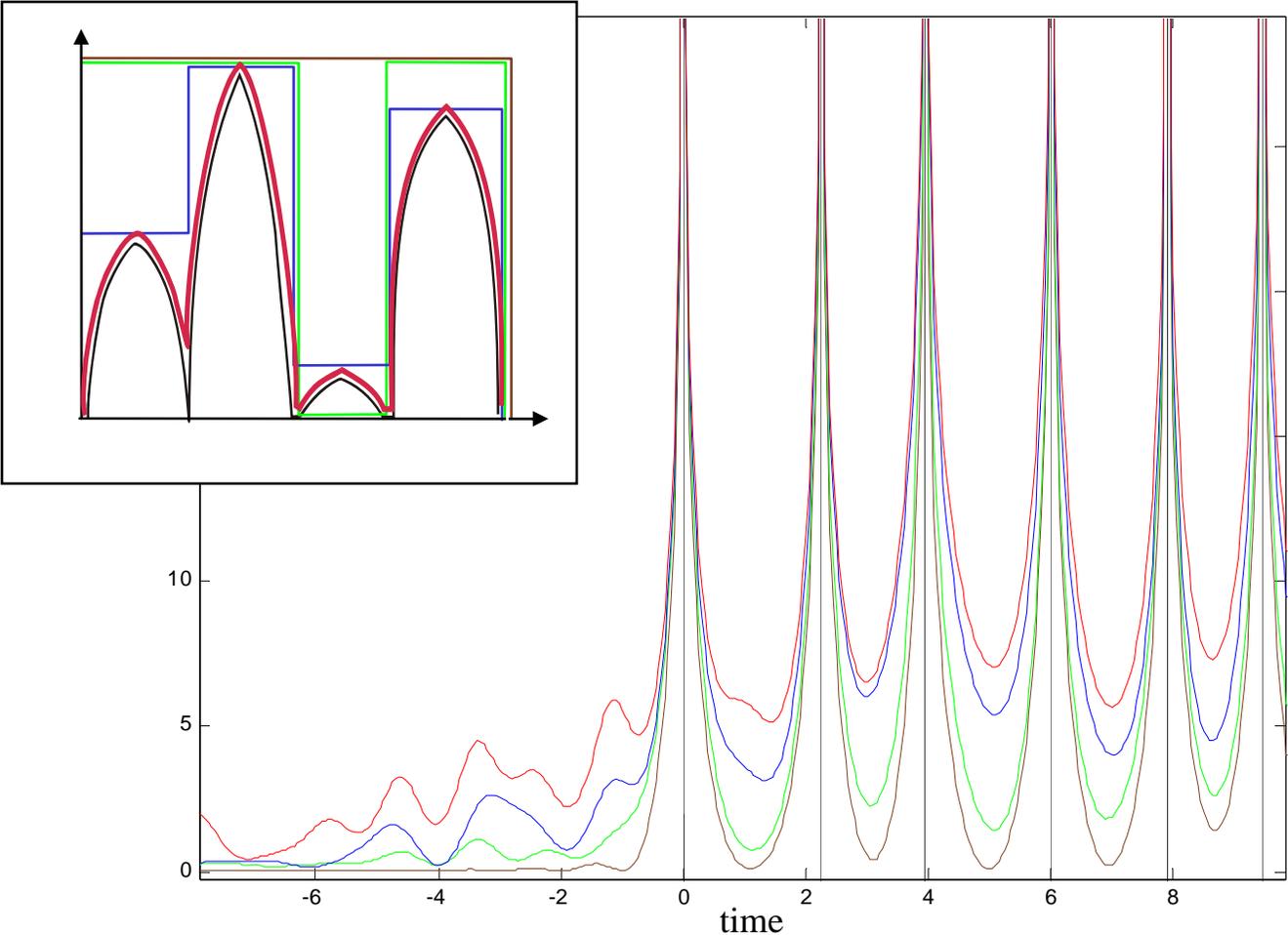
$$Q(t_0) = 10 \log_{10} \left( \frac{s(0)}{s(0) - \mathbf{s}(t_0)^T \mathbf{S}^{-1} \mathbf{s}(t_0)} \right)$$

$$s(t_0)_n = s(t_0 - t_n) \quad S_{mn} = s(t_m - t_n)$$

Reliability of SDT reconstruction:

$$Q_r(t_0) = 10 \log_{10} \left( \frac{r(0)}{r(0) - \mathbf{r}(t_0)^T \mathbf{R}^{-1} \mathbf{r}(t_0)} \right)$$

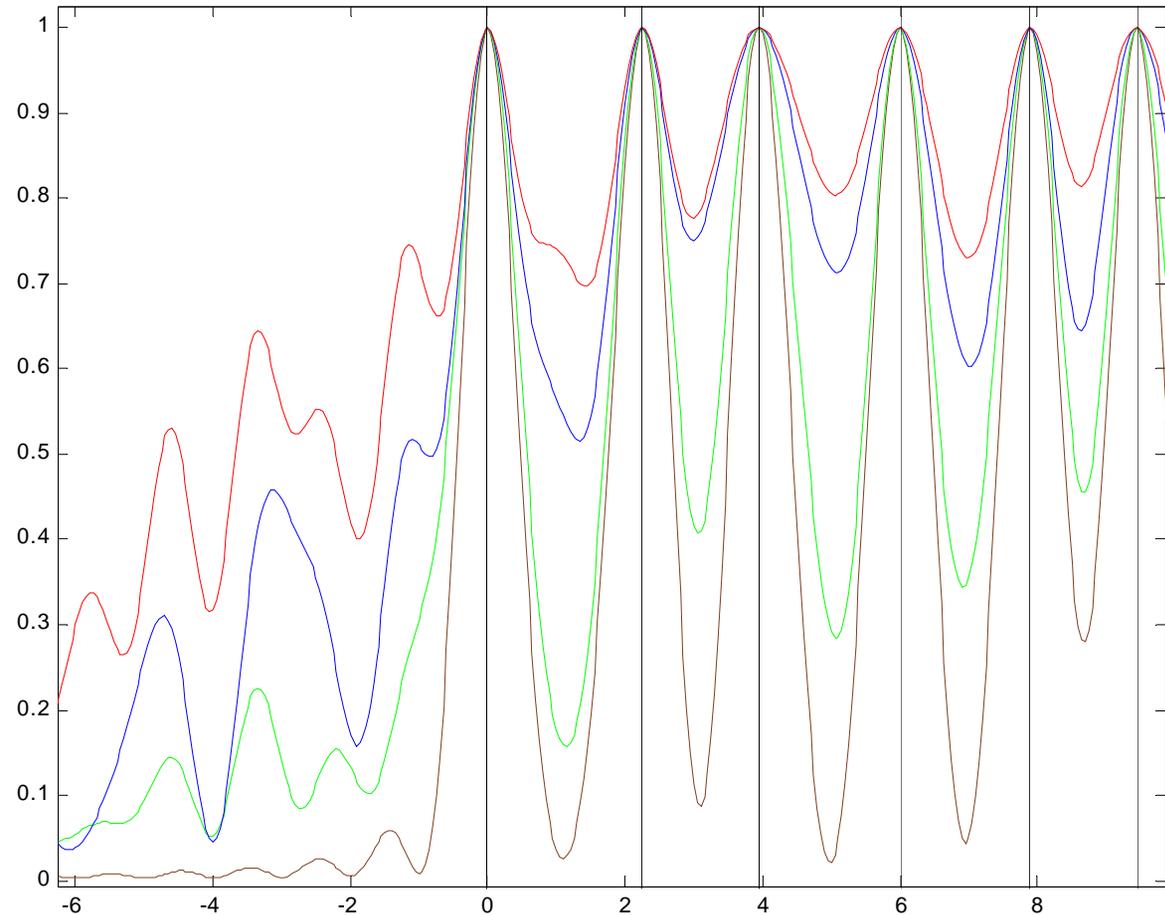
# EXAMPLE OF RELIABILITY FUNCTIONS



## EXAMPLE OF RELIABILITY FUNCTIONS (cont.)

$$q(t_0) = \mathbf{s}(t_0)^T \mathbf{S}^{-1} \mathbf{s}(t_0)$$

$$q_r(t_0) = \mathbf{r}(t_0)^T \mathbf{R}^{-1} \mathbf{r}(t_0)$$



## ABILITIES OF PROPOSED APPROACH

- Spectral analysis
  - Complex spectral values (amplitudes and phases)
  - PSD function values
- Correlation analysis
- Signal reconstruction
  - Inverse DFT from complex spectrum
- Filtering

## ADVANTAGES OF PROPOSED APPROACH

- Applicability to various kinds of samplings (deals with less samples than required by Nyquist)
- Sampling independent from actual frequency boundaries of signal
- Limitation of side-loop effect
- Limitation of noise floor from nonuniform sampling

# CONCLUSIONS

- Uniform sampling can be characterized by one value – sampling period  $T$ , while nonuniform sampling have to be characterized by several parameters
- Significant is maximal interval between two consequent samples  $T_{\max}$
- Typically PSD function of band-limited signal is characterized by one value – bandwidth, while signal spectral characteristics can differ substantially
- Traditional DSP methods support whole frequency range of analysis equally
- Presented approach is based on an idea **not to support whole frequency range equally, but to concentrate processing on the powerful components**
- Autocorrelation function is used as constructing function for signal reconstruction  $\Leftrightarrow$  Power spectral density function is used as spectral support function
- Information about autocorrelation function can be known “a priori” or obtained in an iterative way
- Reliability function demonstrates the eventual enhancement of signal processing results
- In combination with nonuniform sampling (to suppress frequency aliasing) proposed approach enhances signal processing in time and frequency domains also for case if  $T_{\max} \geq T$

# DISCUSSIONS

- **Characterization of signal bandwidth and autocorrelation function**
- **Parameters of nonuniform sampling**
- **Convergence of iterations**
- **Reducing of required mathematical calculations**