



INSTITUTE OF  
ELECTRONICS AND  
COMPUTER SCIENCE

NATIONAL  
DEVELOPMENT  
PLAN 2020



EUROPEAN UNION  
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Eiropas Reģionālās attīstības fonda līdzfinansēts projekts Nr.1.1.1.1/16/A/174  
„Laika sinhronizācija ar augstu precizitāti  
sadalītai zinātnisku mērījumu sistēmai (DaLaS)”.  
Projekta zinātniskais vadītājs Dr.comp. Ints Mednieks

## *Projekta ietvaros izstrādātā aparātūra, laboratorijas eksperimentu rezultāti*

*referents Jevgeņijs Buls*



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J. Buls Projekta ietvaros izstrādātā aparātūra, laboratorijas eksperimentu rezultāti

- 1. Examples of spatially distributed timing systems**
- 2. Two synchronization approaches**
- 3. Event Timing Based Synchronization (ETBS)**
- 4. Precise Event Timer A040-ET with synchronization functionality**
- 5. Multifunctional True Event Timer for wide applications**
- 6. True Event Timer not requiring the maintenance**
- 7. Implementation and main components of the ETBS**
- 8. Connection cable impact estimation**
- 9. Estimation of Time and Frequency Standards**
- 10. Estimation of the synchronization output of the A040-ET**
- 11. Estimation of the accuracy and precision of the ETBS**



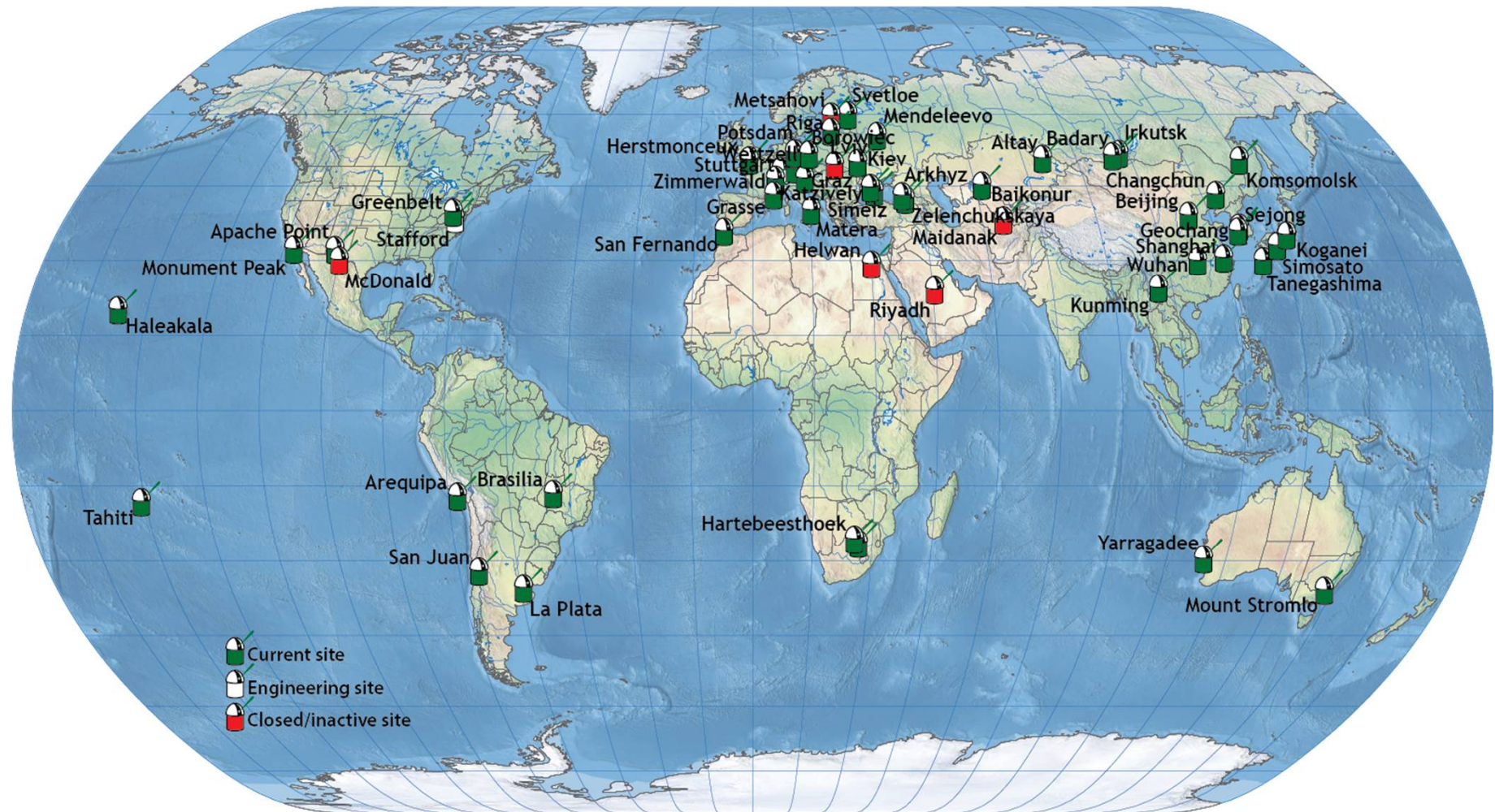
## *Examples of spatially distributed timing systems*

- The Large Hadron Collider (LHC) is the world's largest and highest-energy particle collider and the largest machine in the world.
- Satellite Laser Ranging (SLR) stations around the world organized under International Laser Ranging Service (ILRS) and providing the precise data for geodetic and geophysical research activities by mean of satellite and Lunar ranging
- Satellite constellation is a group of artificial satellites working together as a system (navigation, communication, observation etc.)



## Examples of spatially distributed timing systems

Satellite Laser Ranging stations around the world organized under International Laser Ranging Service providing the precise data for geodetic and geophysical research activities by mean of satellite and Lunar ranging



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## Two synchronization approaches

White Rabbit approach (CERN) –

Special devices providing the precise time and frequency transfer via Ethernet

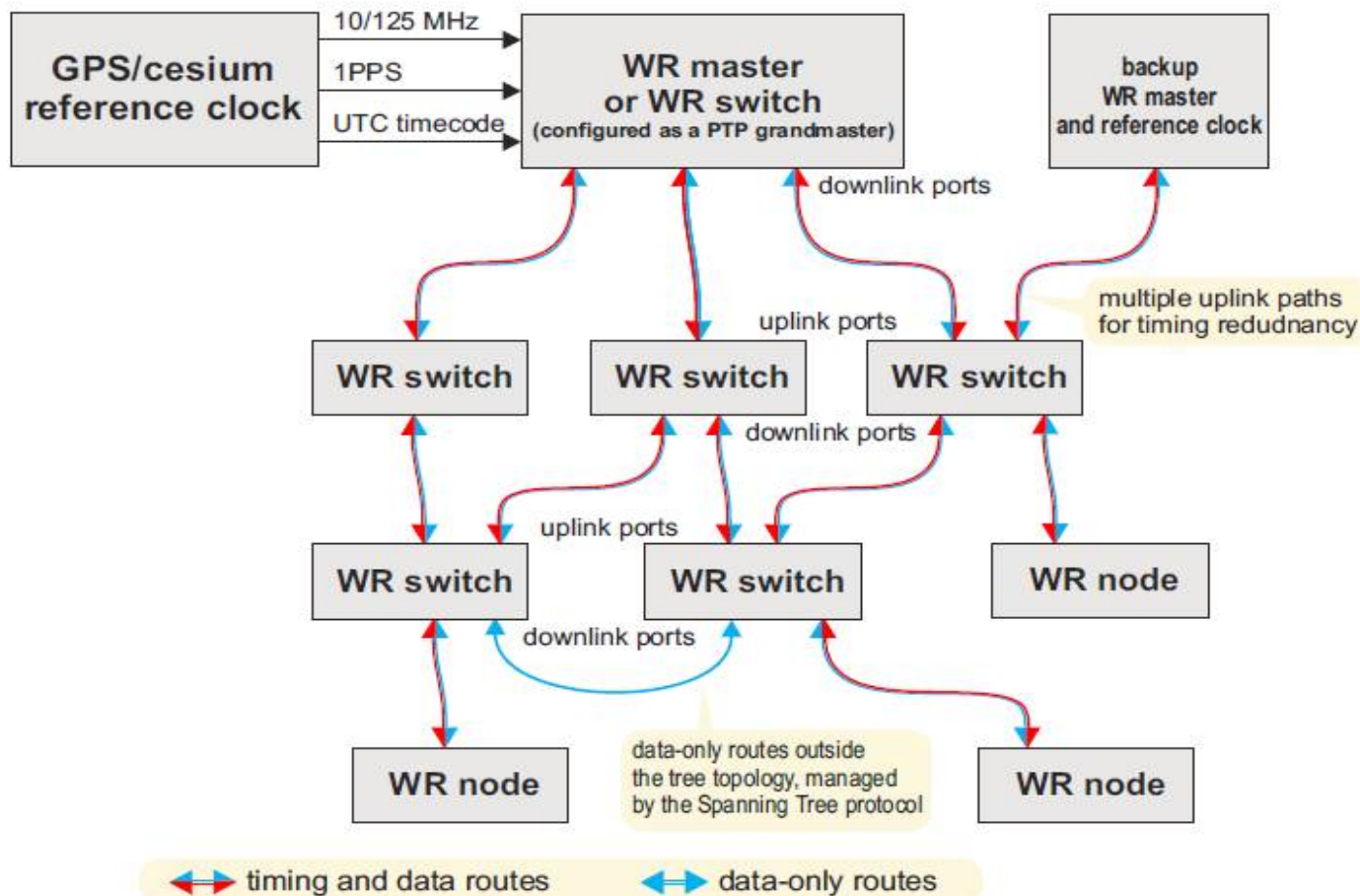
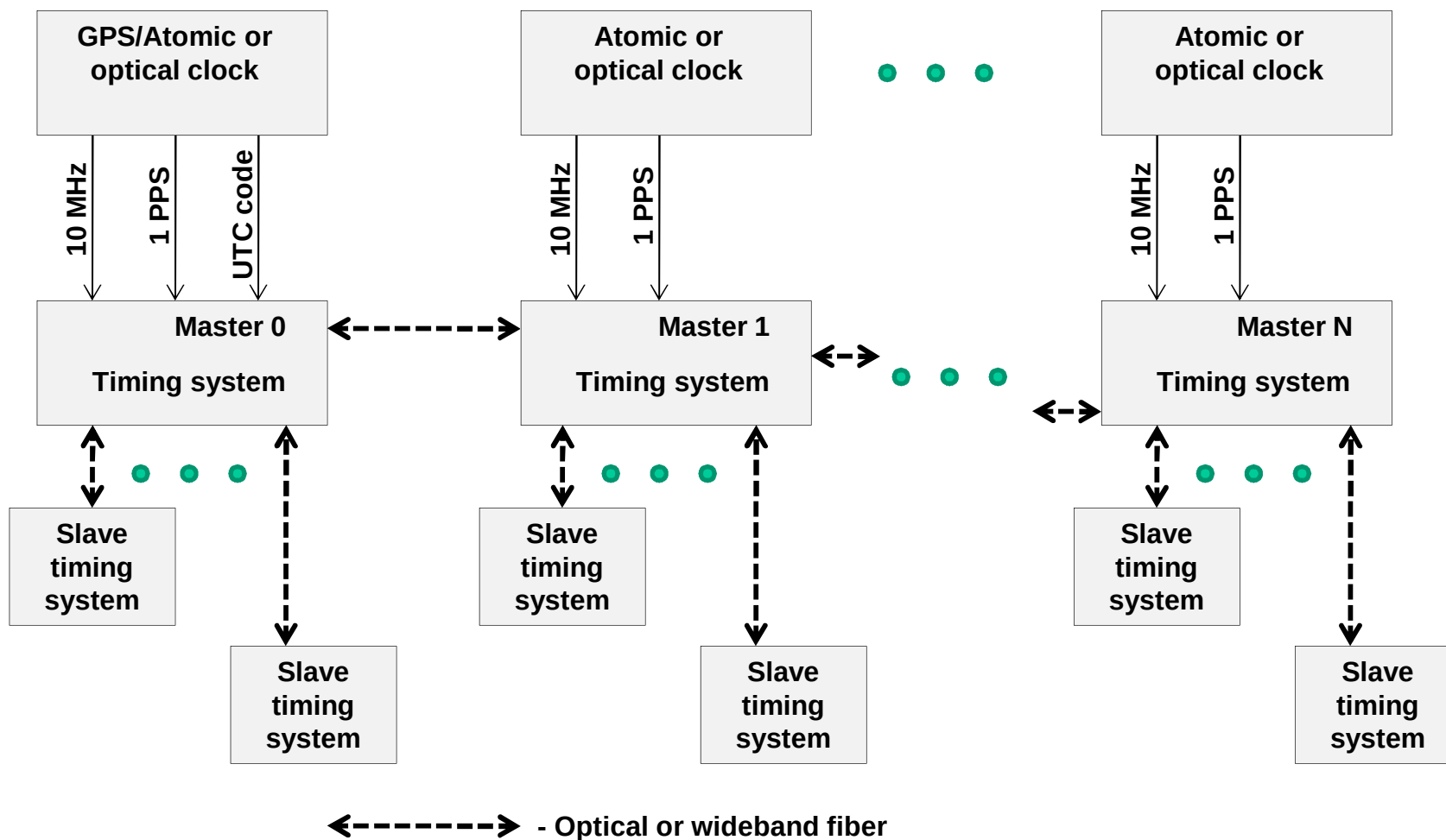


Figure from: Tomasz Włostowski. Precise time and frequency transfer in a White Rabbit network. Master of Science thesis. Warsaw University of Technology. 2011, 98 p



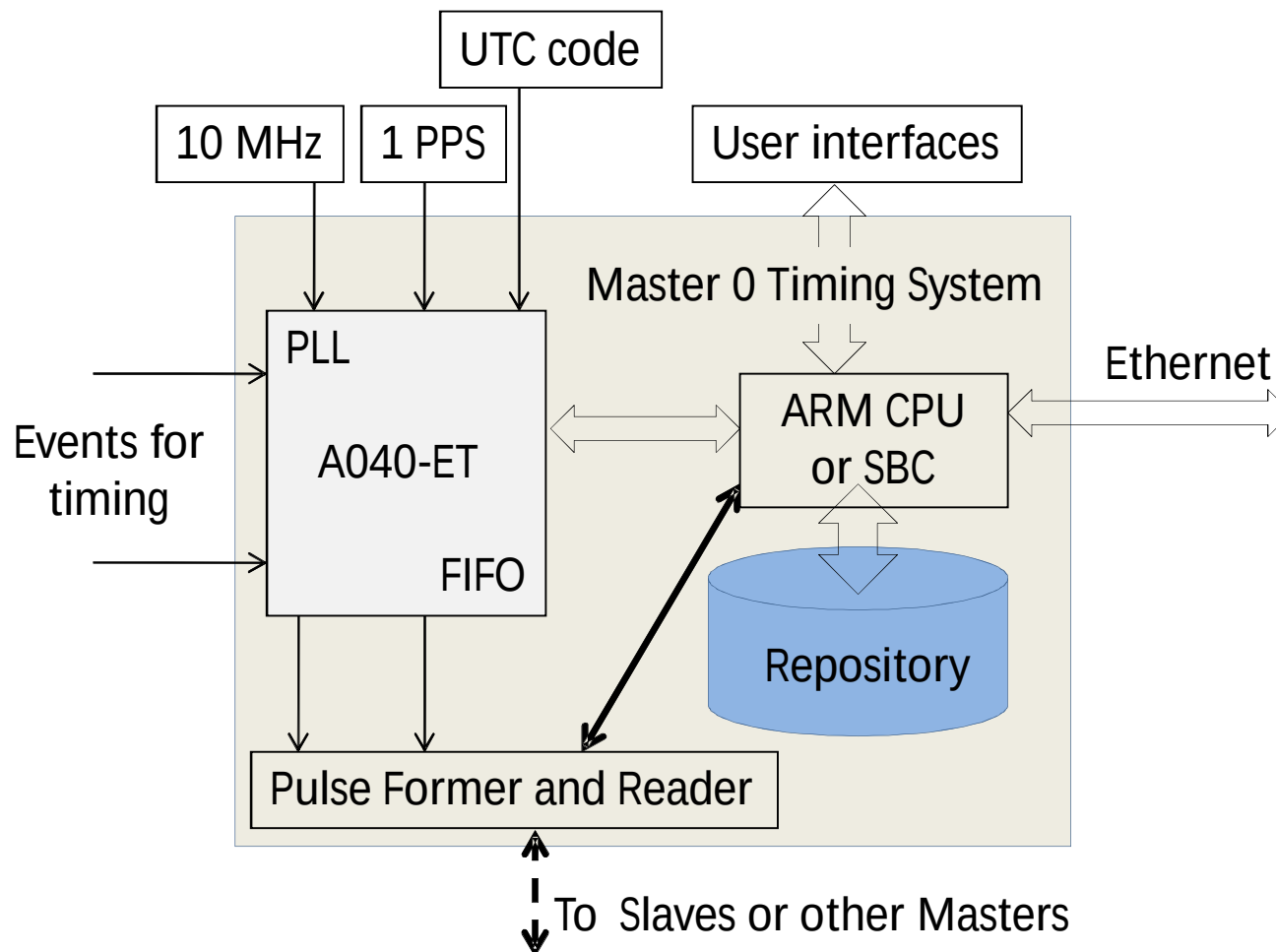
## Two synchronization approaches

Event Timing based approach – synchronization of Networked Timing System using their own functionality



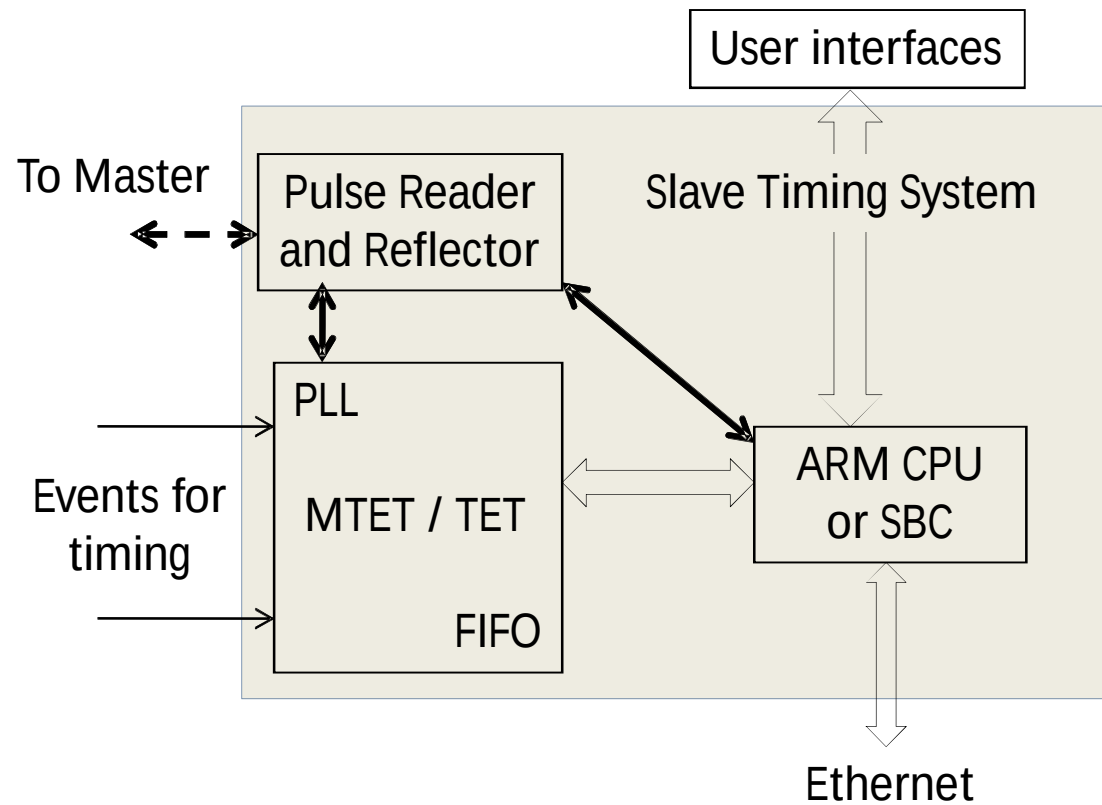
# Event Timing Based Synchronization

## Master Timing System



# Event Timing Based Synchronization

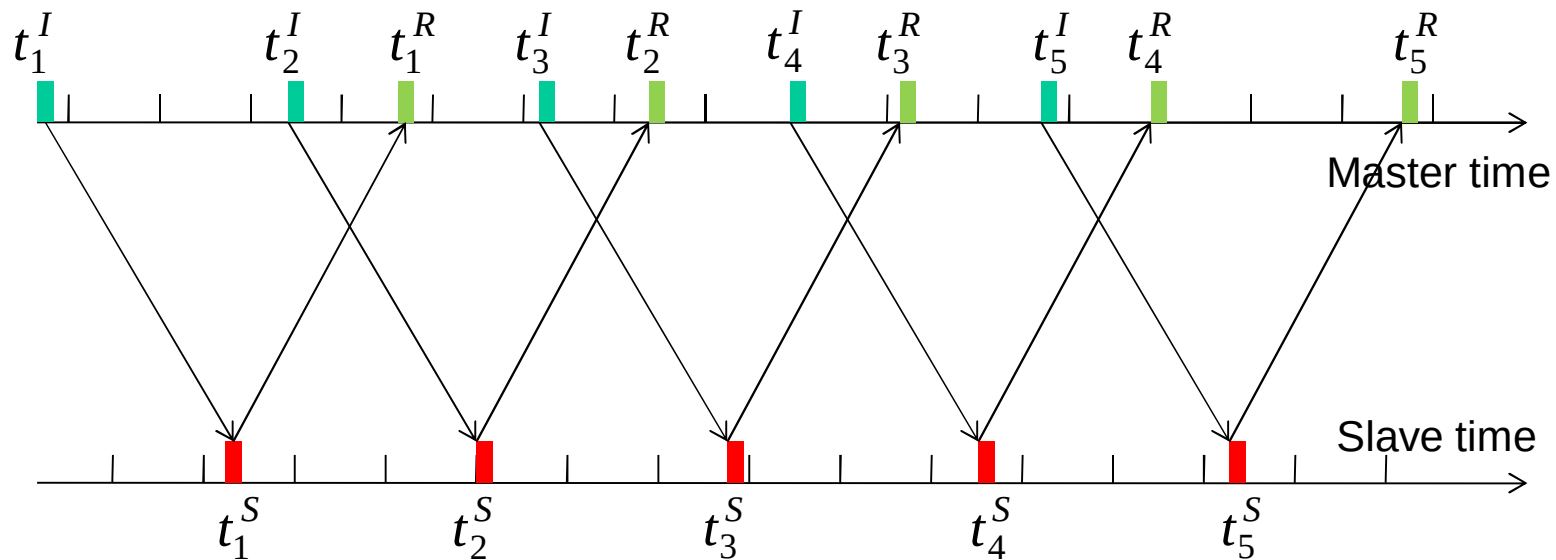
## Slave Timing system





# Event Timing Based Synchronization

## Time Offset calculation



$$\delta_1 = \frac{t_1^I + t_1^R}{2}$$

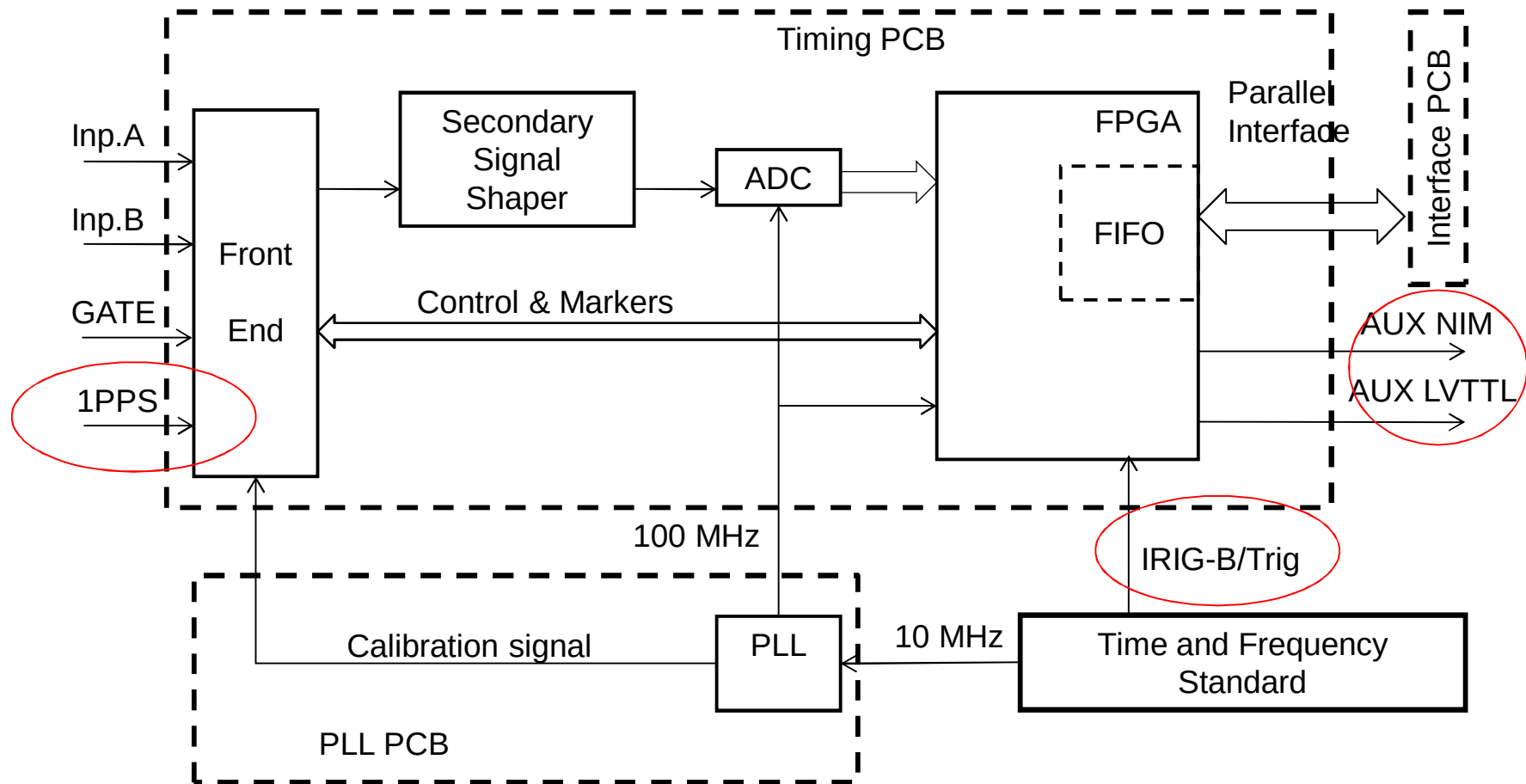
$$t_1^I + \Delta_1 + \delta_1 = t_1^S$$

$$\Delta_1 = t_1^S - \frac{t_1^I + t_1^R}{2}$$



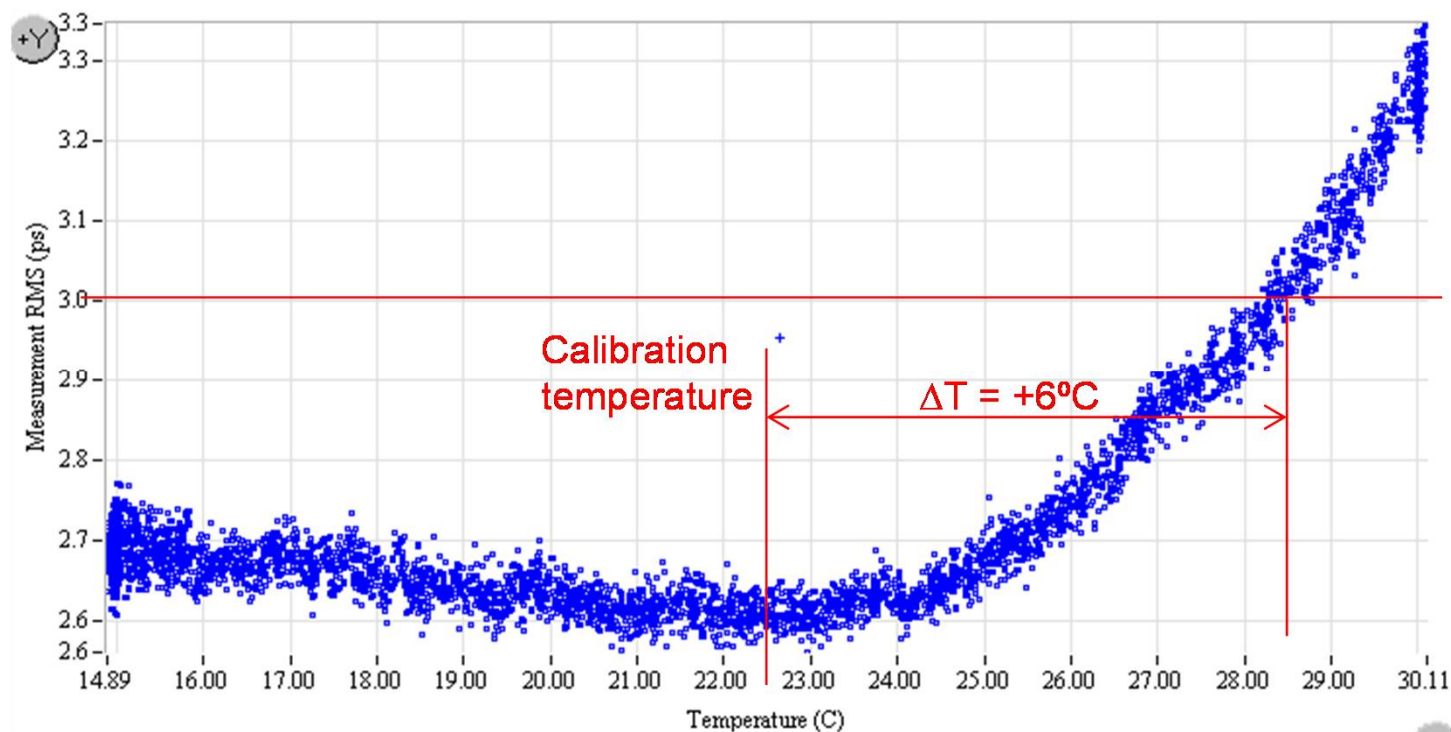
## Precise Event Timer A040-ET with synchronization functionality

Block diagram of the A040-ET



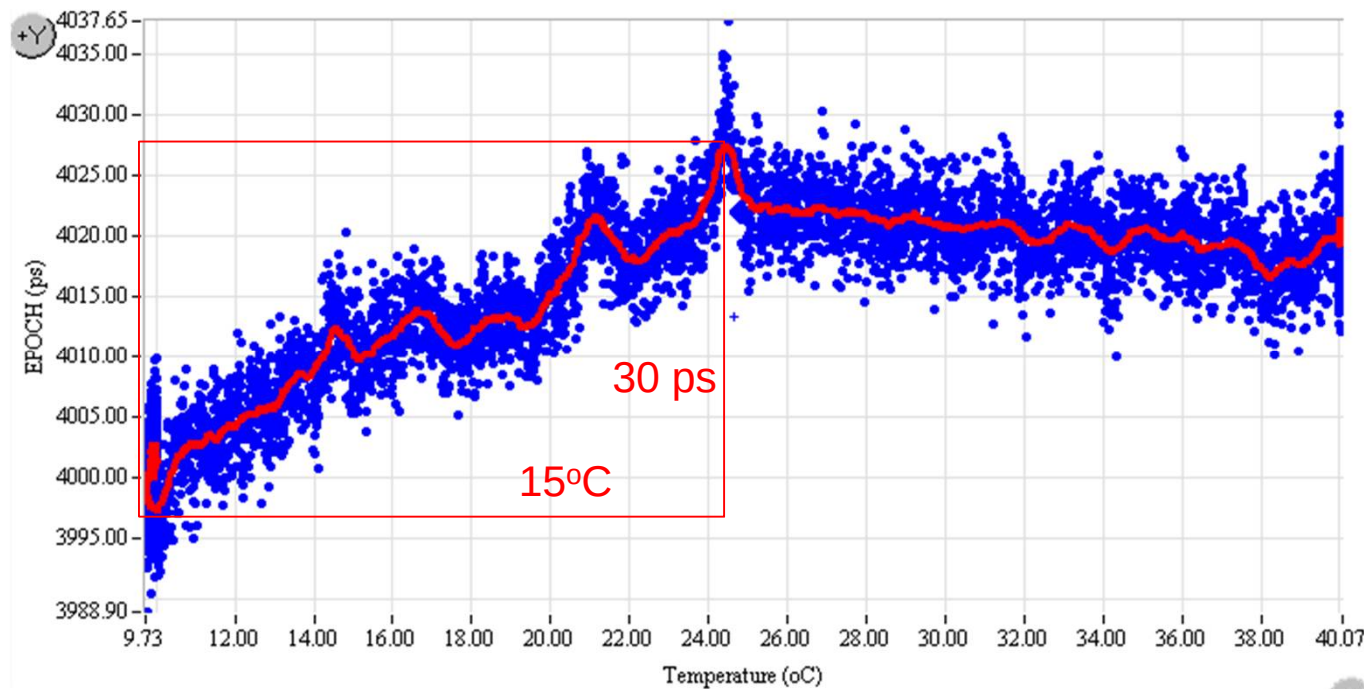
## Precise Event Timer A040-ET with synchronization functionality

### Precision in temperature



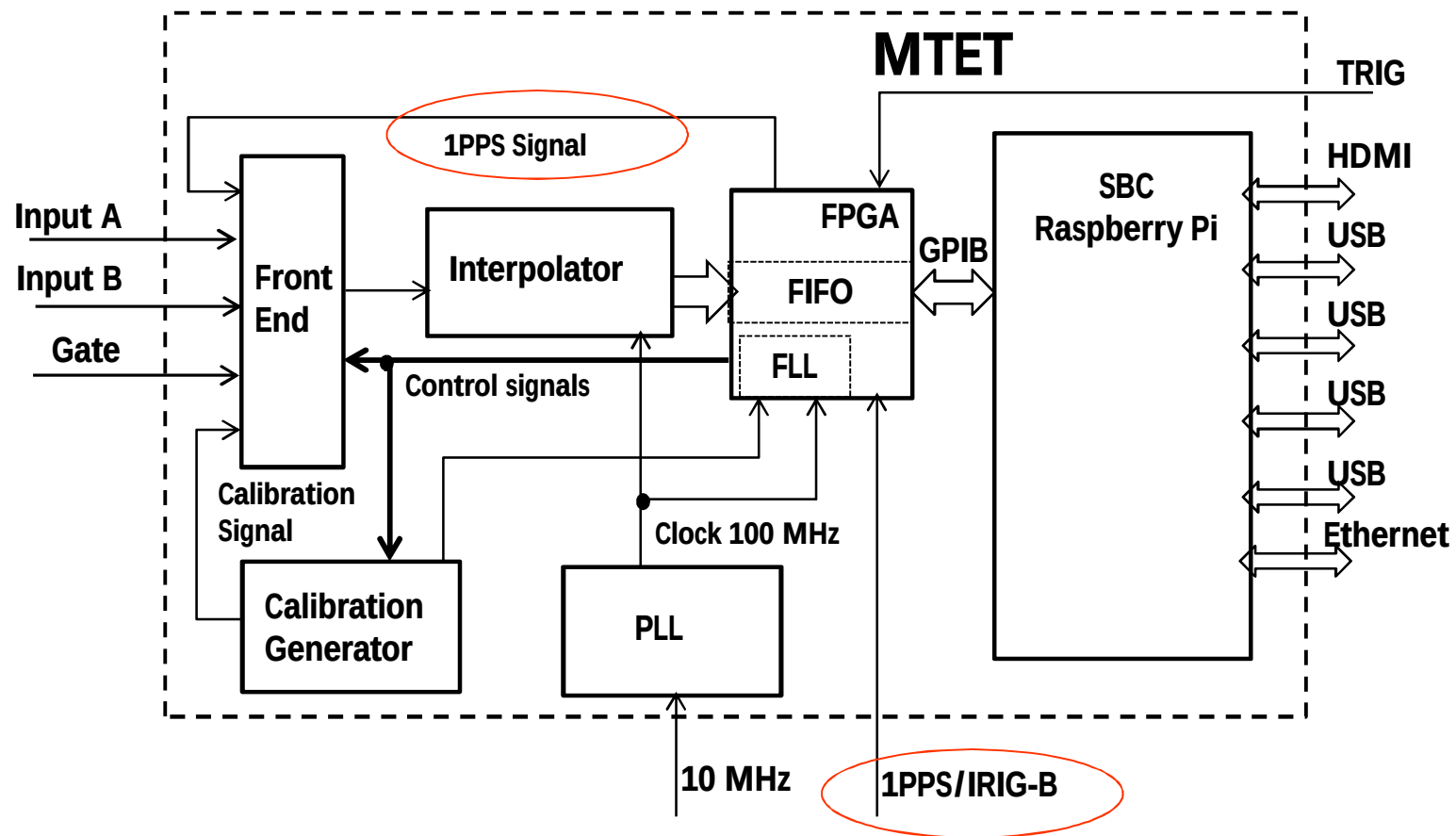
## Precise Event Timer A040-ET with synchronization functionality

Time scale offset in temperature =  $2 \text{ ps}/^{\circ}\text{C}$



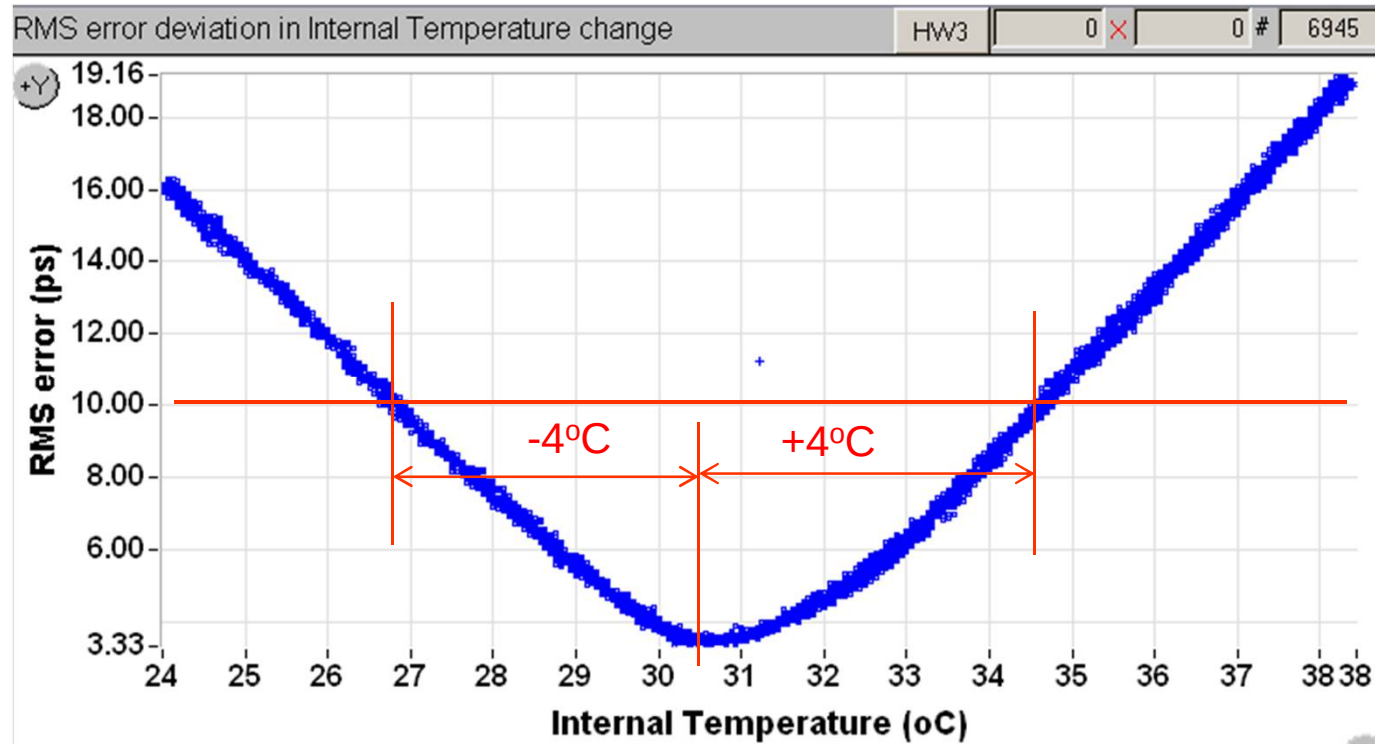
# Multifunctional True Event Timer for wide applications

Block diagram of the MTET



# Multifunctional True Event Timer for wide applications

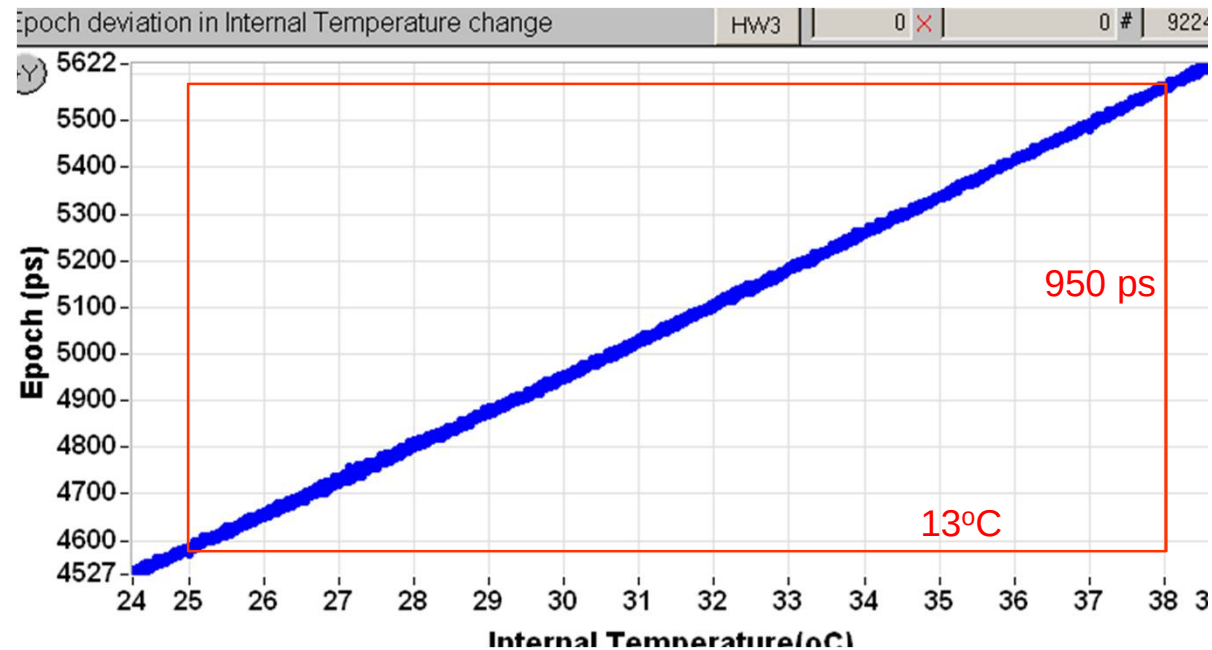
## Precision in temperature





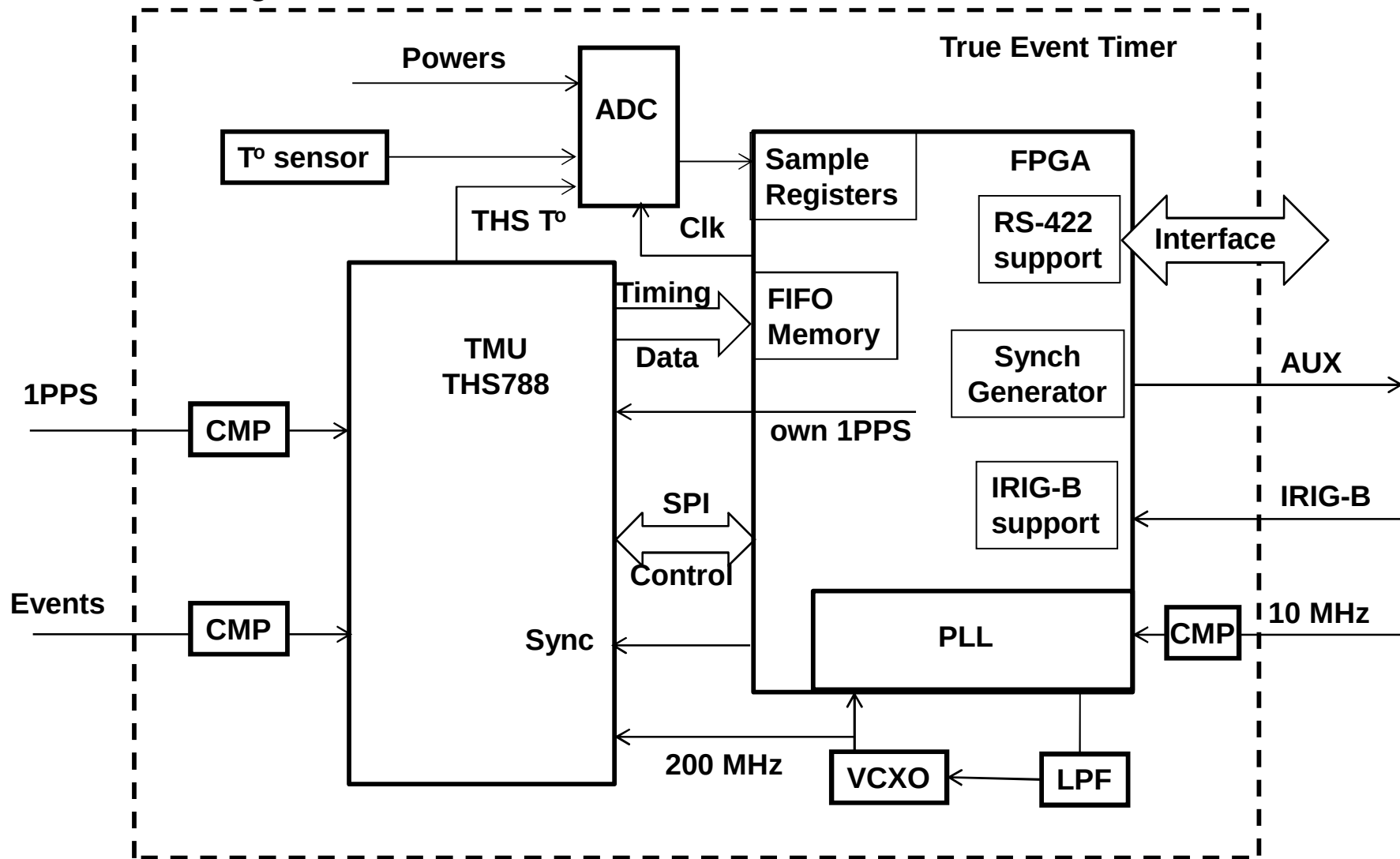
## Multifunctional True Event Timer for wide applications

Time scale offset in temperature =  $73 \text{ ps}/^{\circ}\text{C}$



## True Event Timer not requiring the maintenance

Block diagram of the TET



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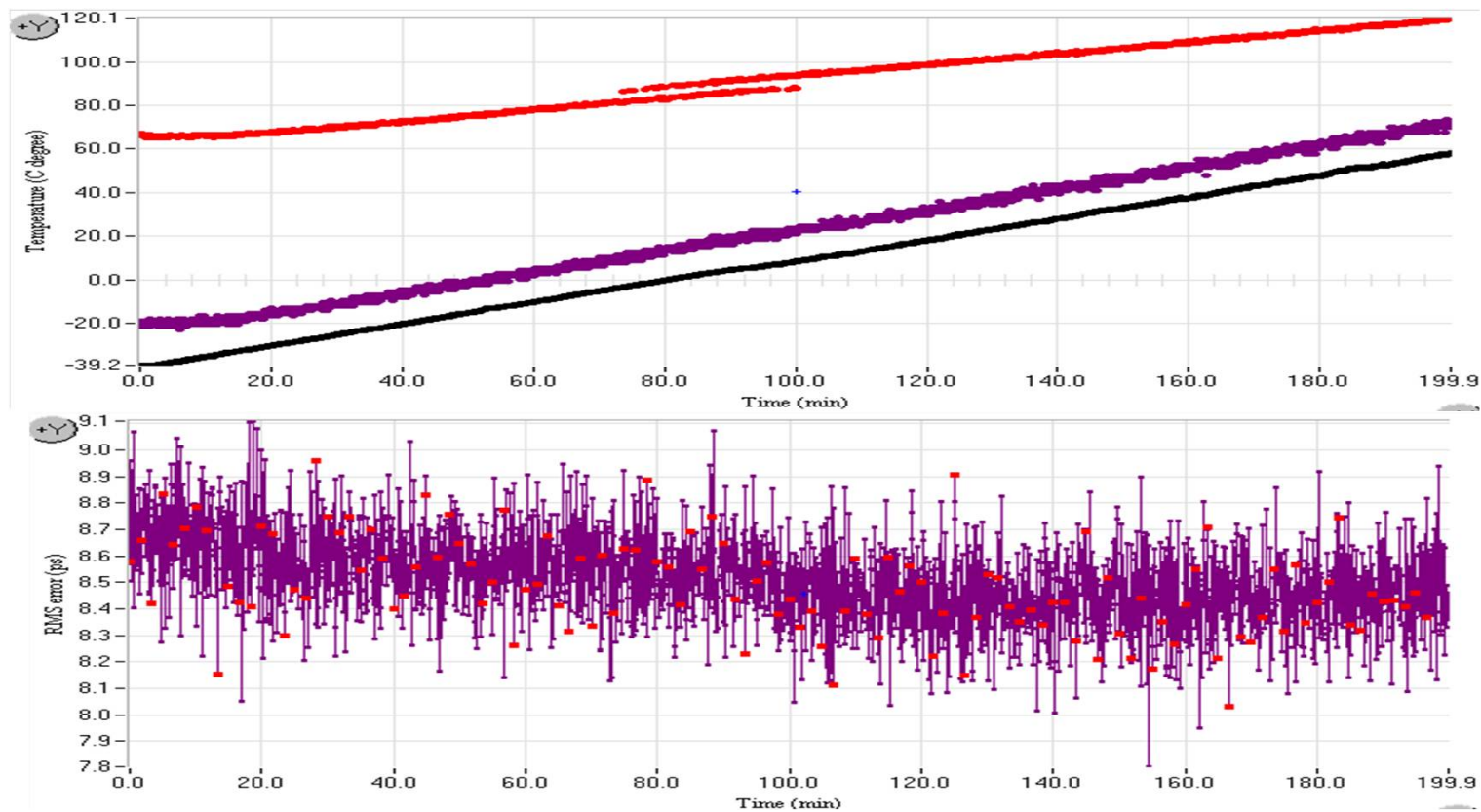


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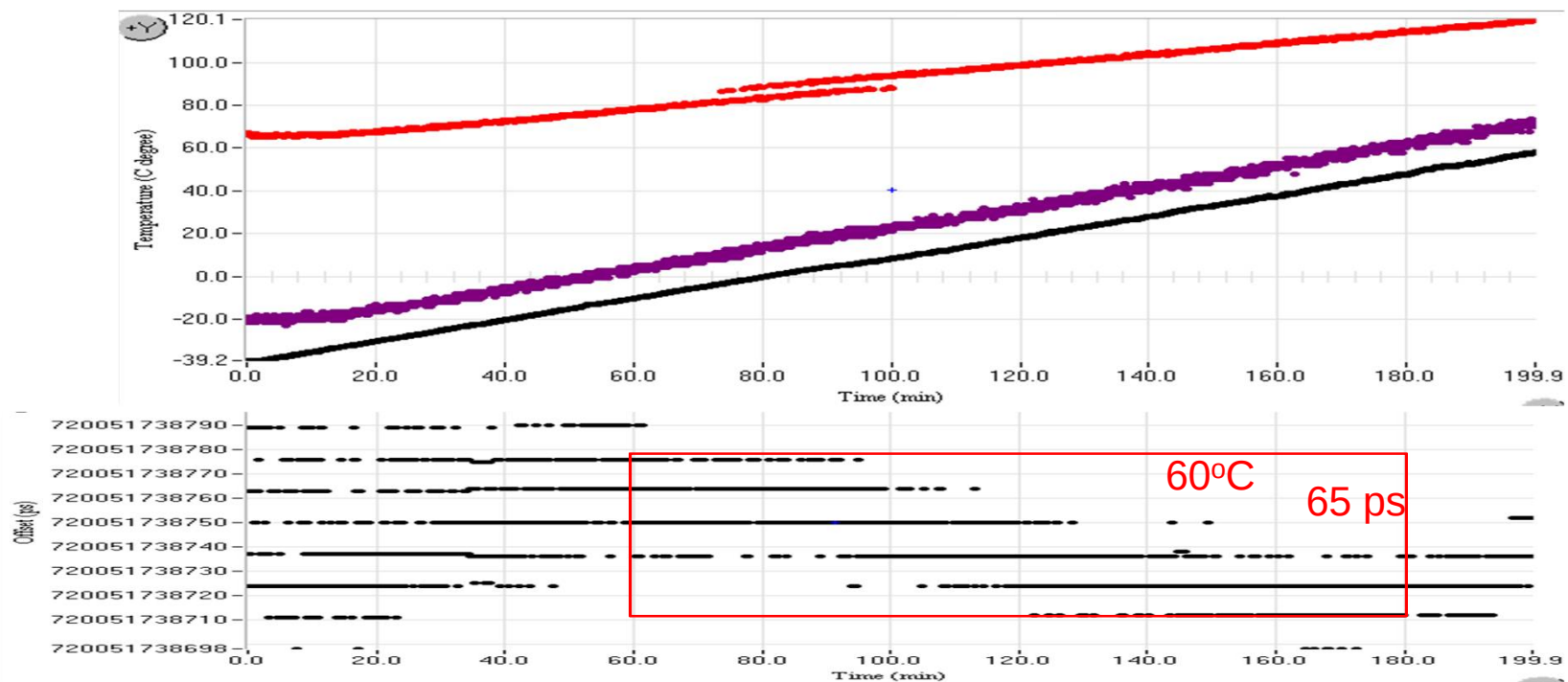
# True Event Timer not requiring the maintenance

## Precision in Temperature

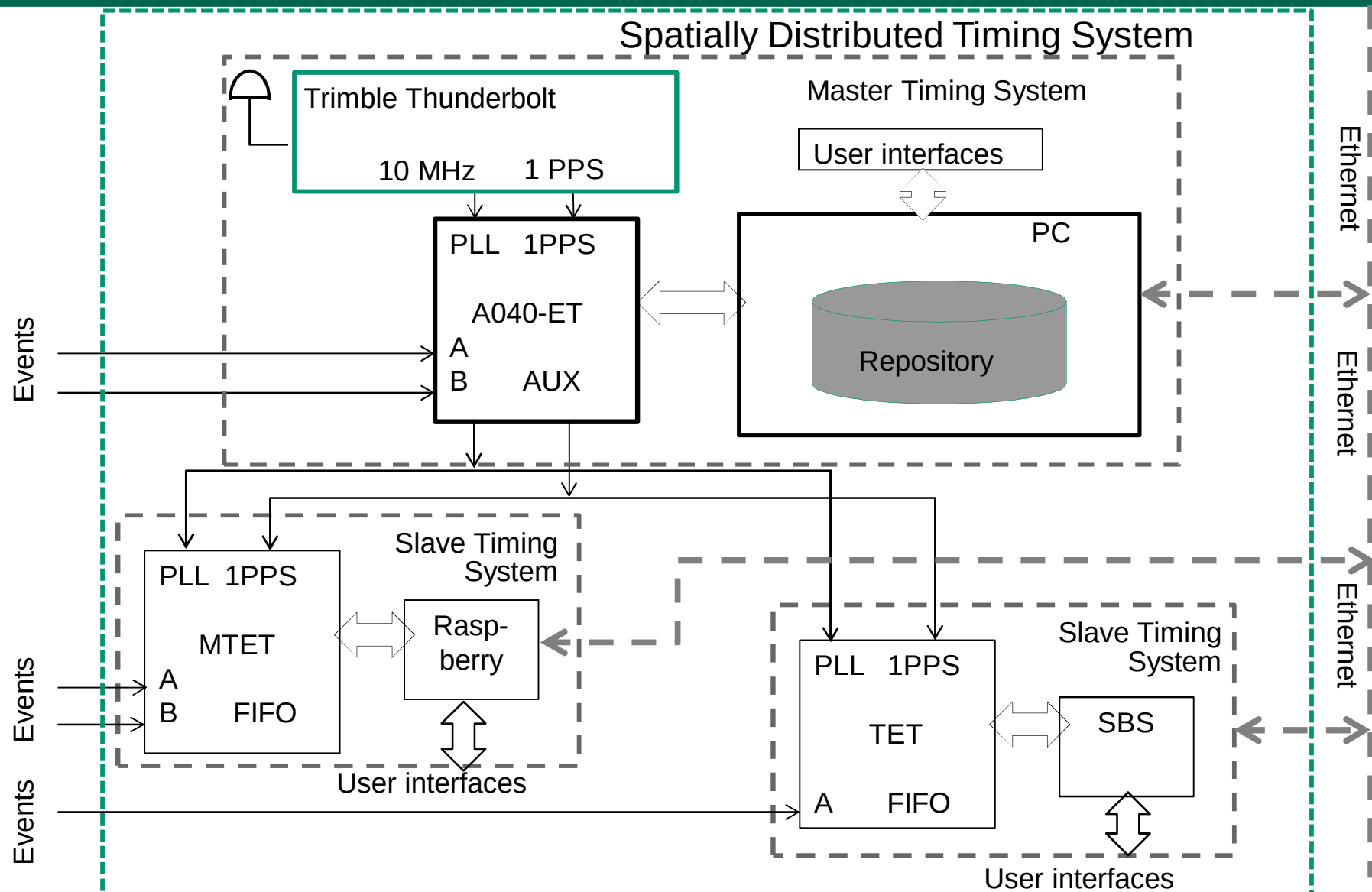


## True Event Timer not requiring the maintenance

Time scale offset in temperature =  $1.1 \text{ ps}/^{\circ}\text{C}$



# Implementation and main components of the ETBS

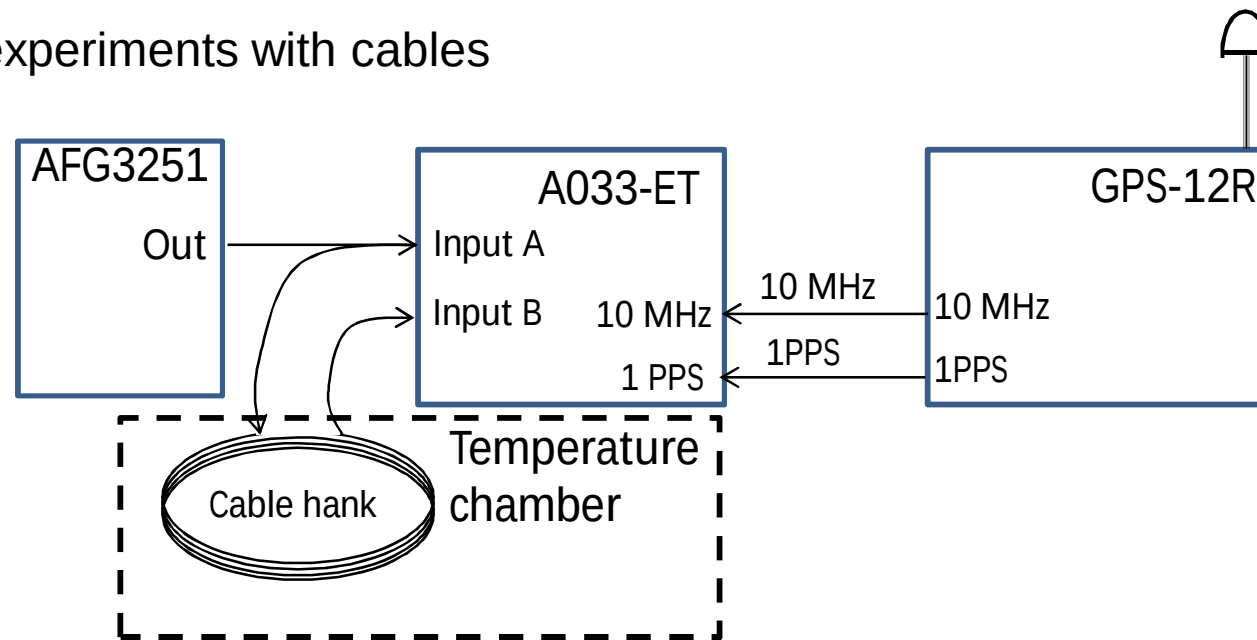


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## Connection cable impact estimation

Laboratory experiments with cables

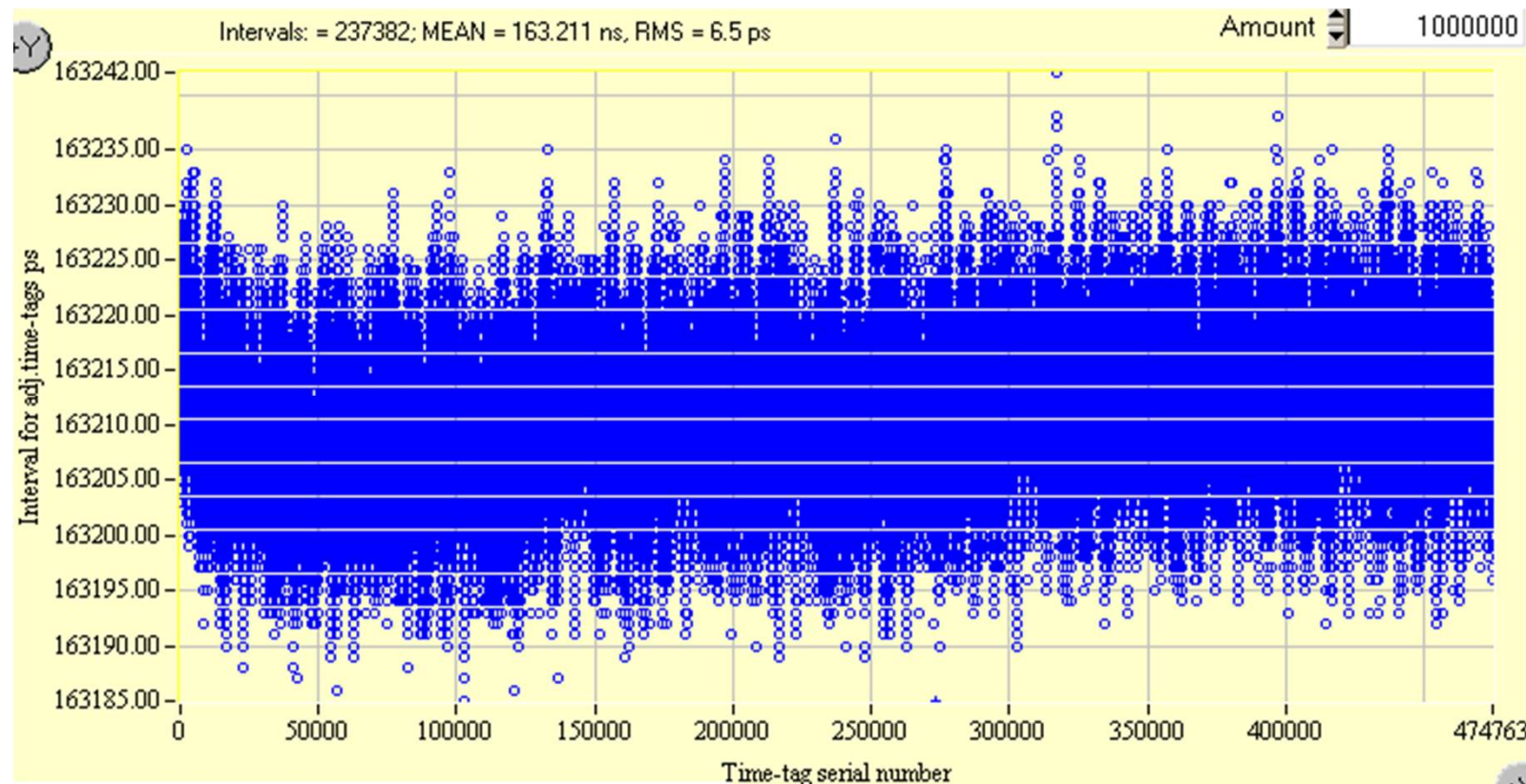


| Cable     | Length, m | Conductor (mm) | Diameter, mm | Attenuation, db/m | RMS, ps | Delay, ps | Temperature drift, ps/°C |
|-----------|-----------|----------------|--------------|-------------------|---------|-----------|--------------------------|
| RG58C-U   | 3         | 19x0.18        | 4.95         | 0.65              | 2.7     | 50715     | 4.5                      |
| PK50-2-16 | 10        | 7x0.24         | 3.2          | 0.8               | 18.7    | 193778    | 8.7                      |
| PK50-7-21 | 30        | 7x0.83         | 8.9          | 0.32              | 6.5     | 163221    | 0.4                      |



## Connection cable impact estimation

### Laboratory experiments with cables



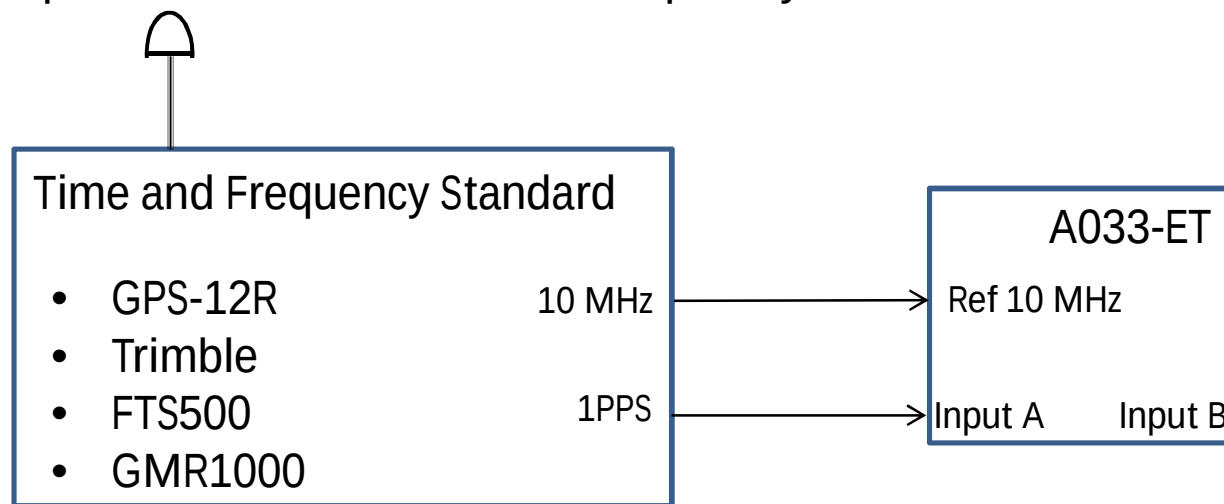
Estimation of cable delay and introduced uncertainty at constant temperature 40°C





## Estimation of Time and Frequency Standards

Laboratory experiments with Time and Frequency Standards

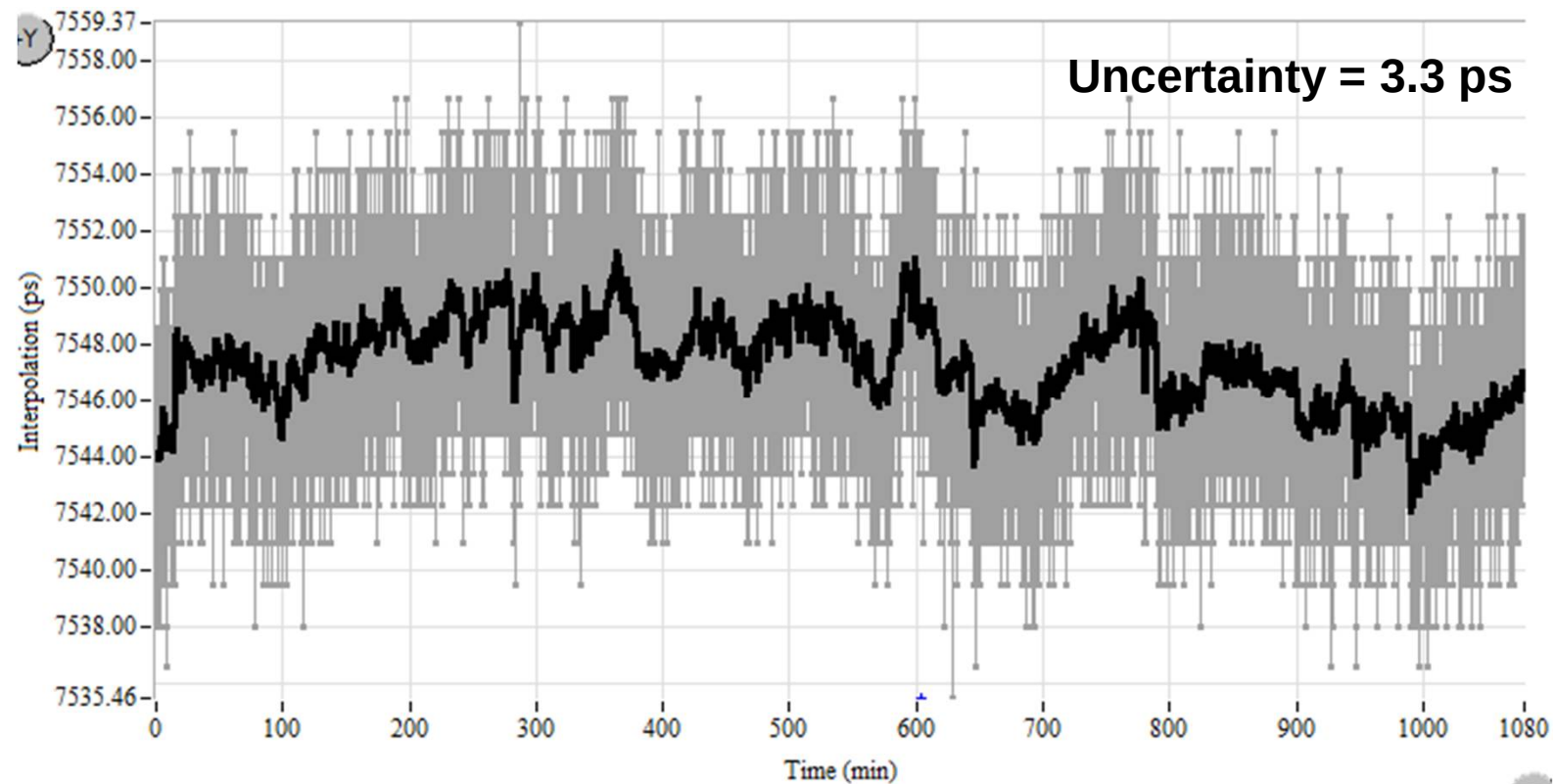


| TFS     | Own 1 PPS accuracy | 1 PPS pulse period precision (RMS) |
|---------|--------------------|------------------------------------|
| GPS-12R | 26 ps              | 5.0 ps                             |
| Trimble | 24 ps              | 3.3 ps                             |
| FTS500  | 22 ps              | 3.3 ps                             |
| GMR1000 | 252 ps             | 78 ps                              |



## Estimation of Time and Frequency Standards

### Laboratory experiments with Time and Frequency Standards

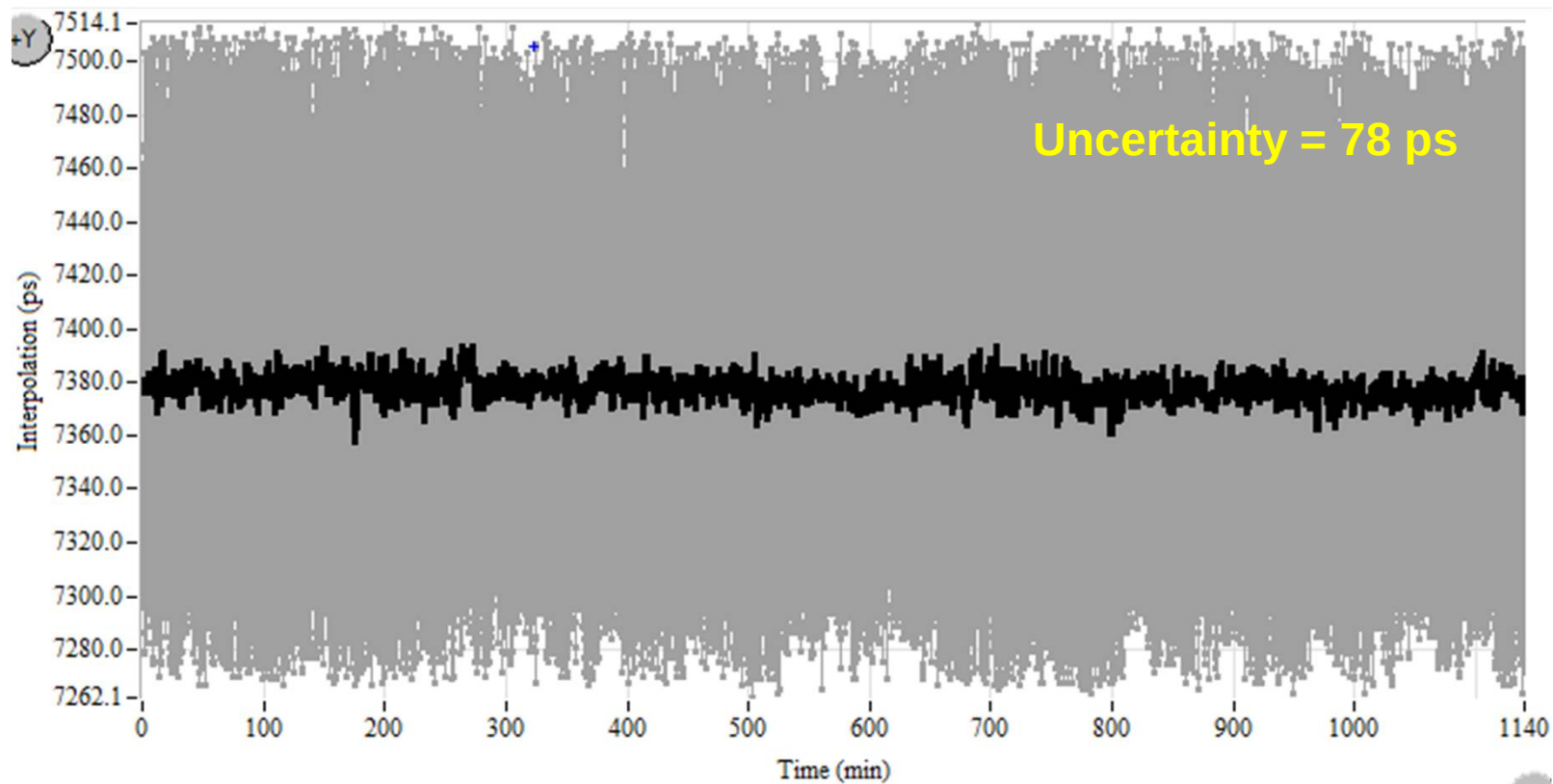


Trimble 1 PPS pulse position in the time scale of the ET



## Estimation of Time and Frequency Standards

### Laboratory experiments with Time and Frequency Standards

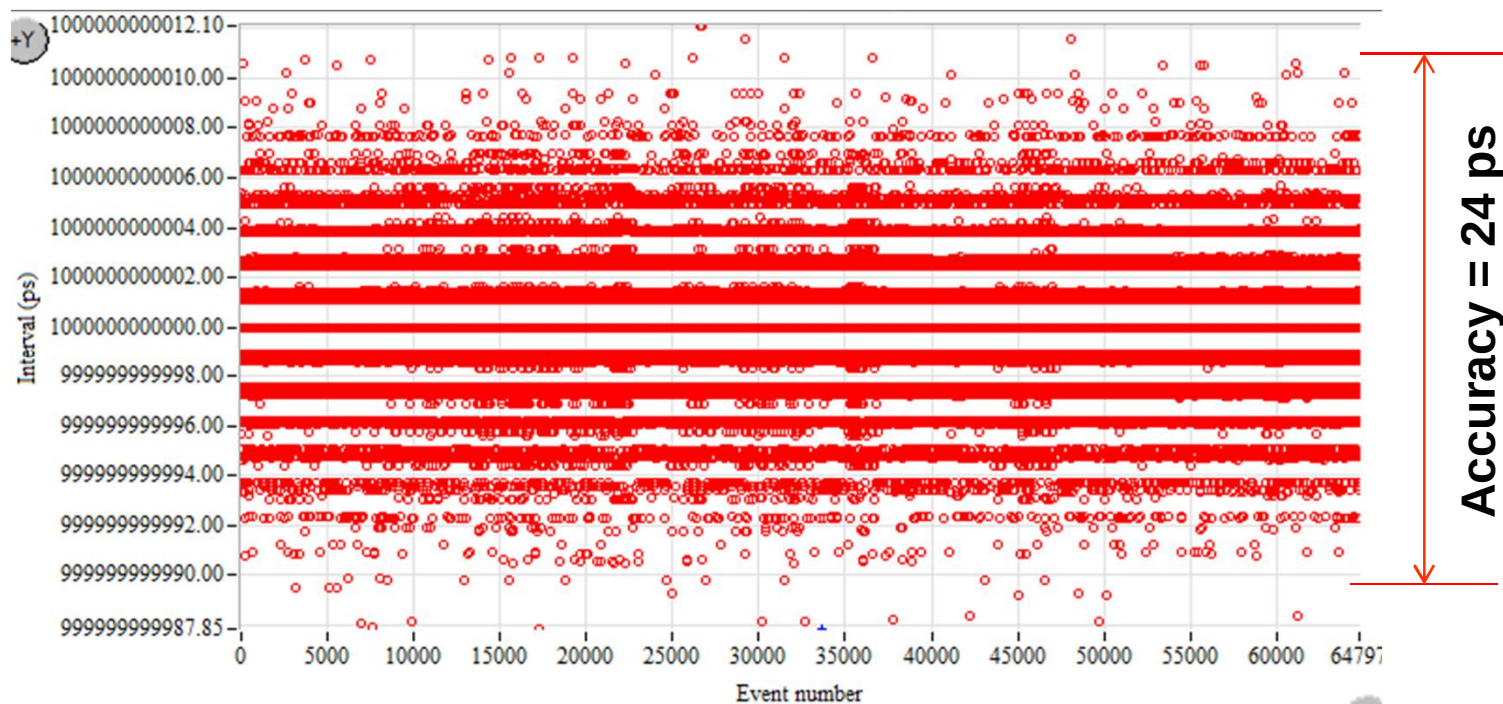


GMR1000 1 PPS pulse position in the time scale of the ET



# Estimation of Time and Frequency Standards

## Laboratory experiments with Time and Frequency Standards



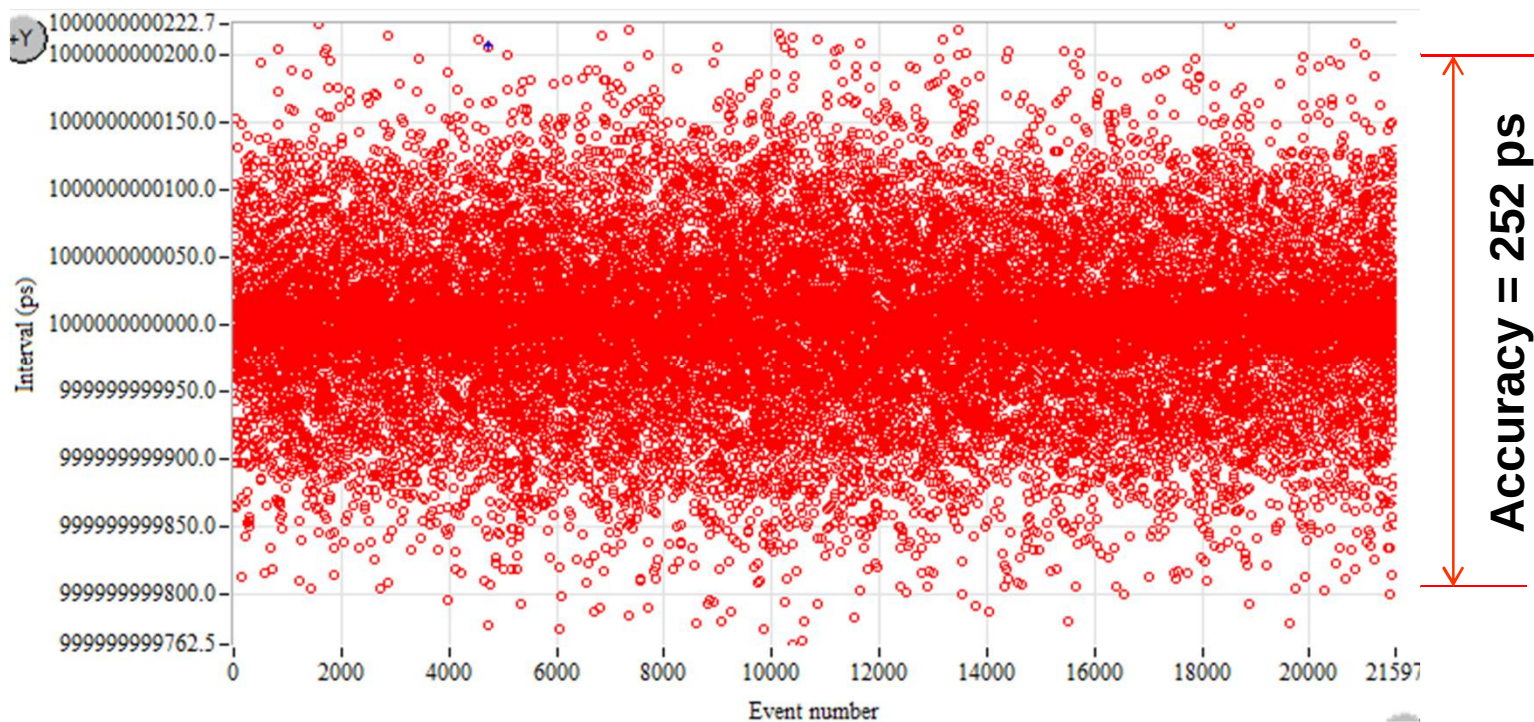
Trimble 1 PPS pulse period estimations





# Estimation of Time and Frequency Standards

## Laboratory experiments with Time and Frequency Standards

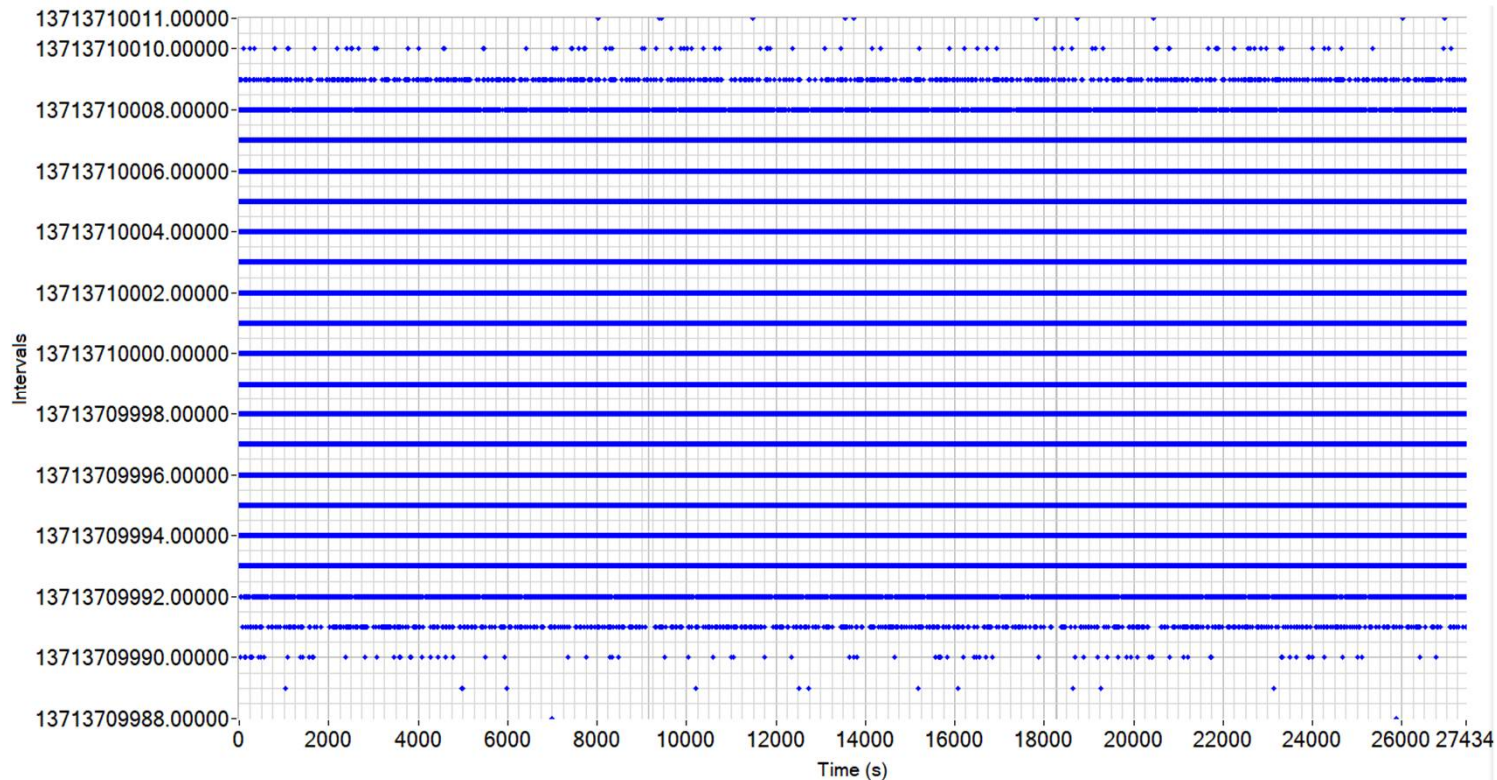


GMR1000 1 PPS pulse period estimations



## Estimation of the synchronization output of the A040-ET

Using of A040-ET output AUX for time scales synchronization



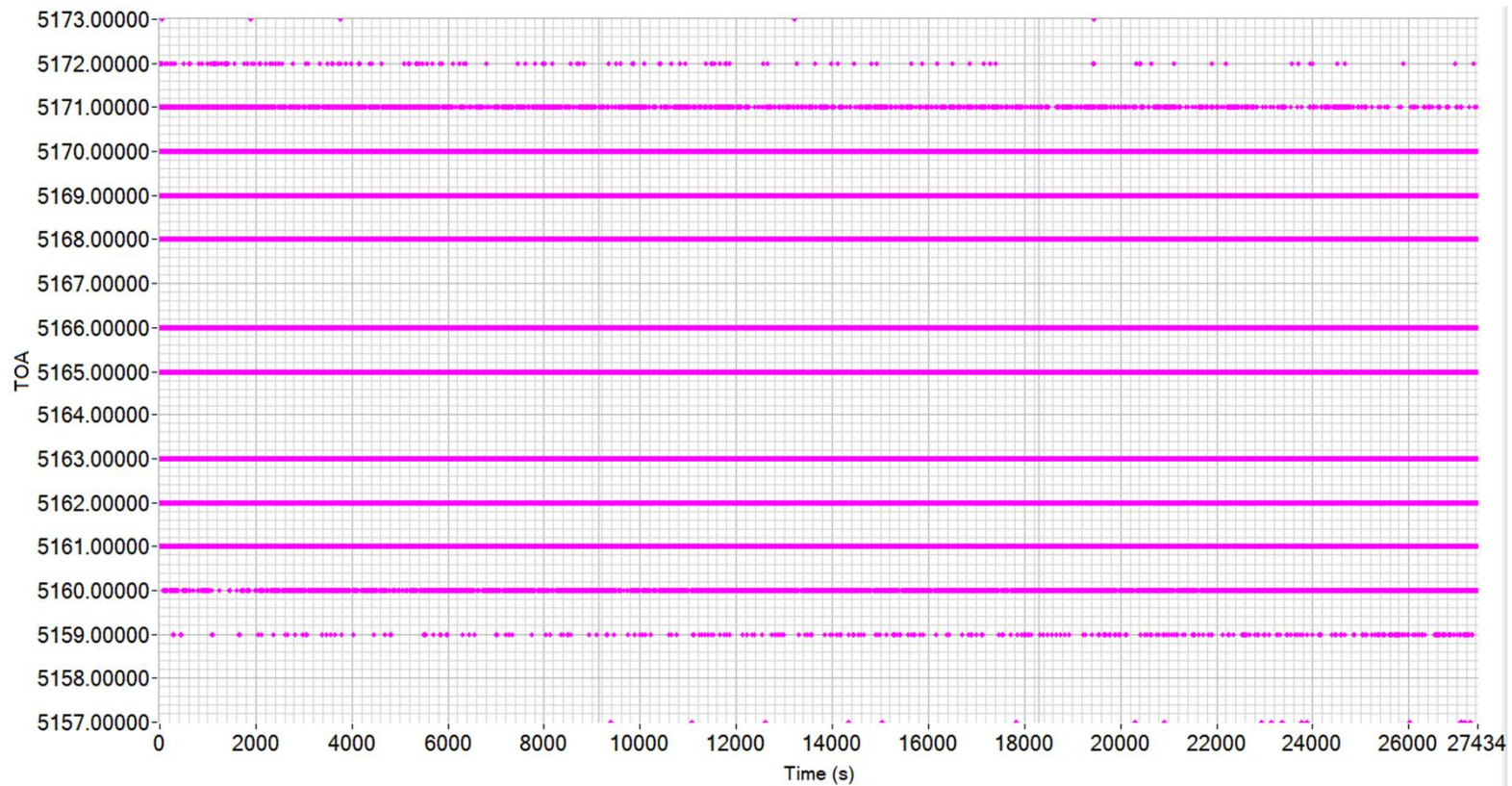
Measurement results for AUX signal period during 7.4 hours





## Estimation of the synchronization output of the A040-ET

Using of A040-ET output AUX for time scales synchronization



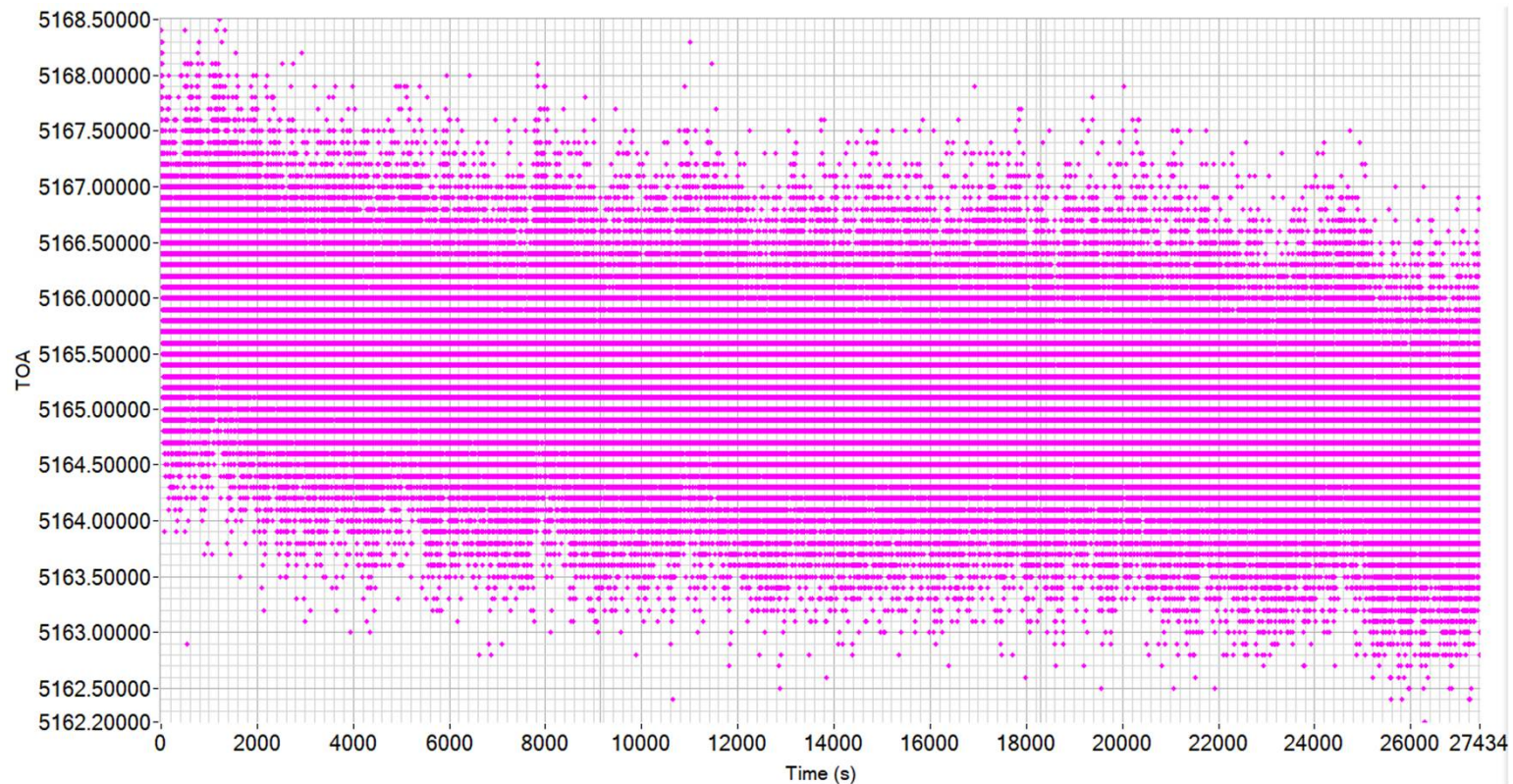
AUX signal position in the time scale of the ET





# Estimation of the synchronization output of the A040-ET

Using of A040-ET output AUX for time scales synchronization

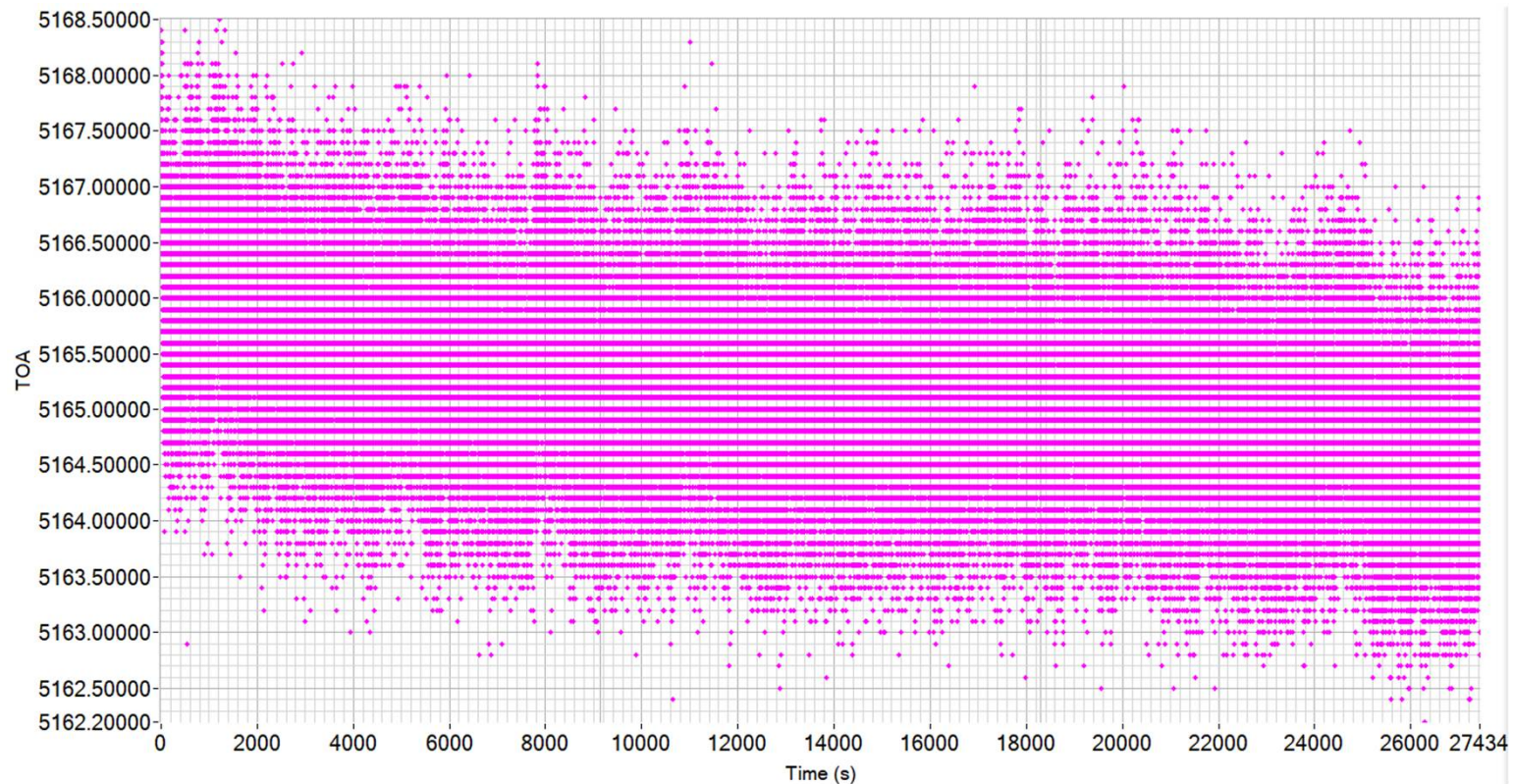


Averaging of the AUX signal position on 10 values



# Estimation of the synchronization output of the A040-ET

Using of A040-ET output AUX for time scales synchronization

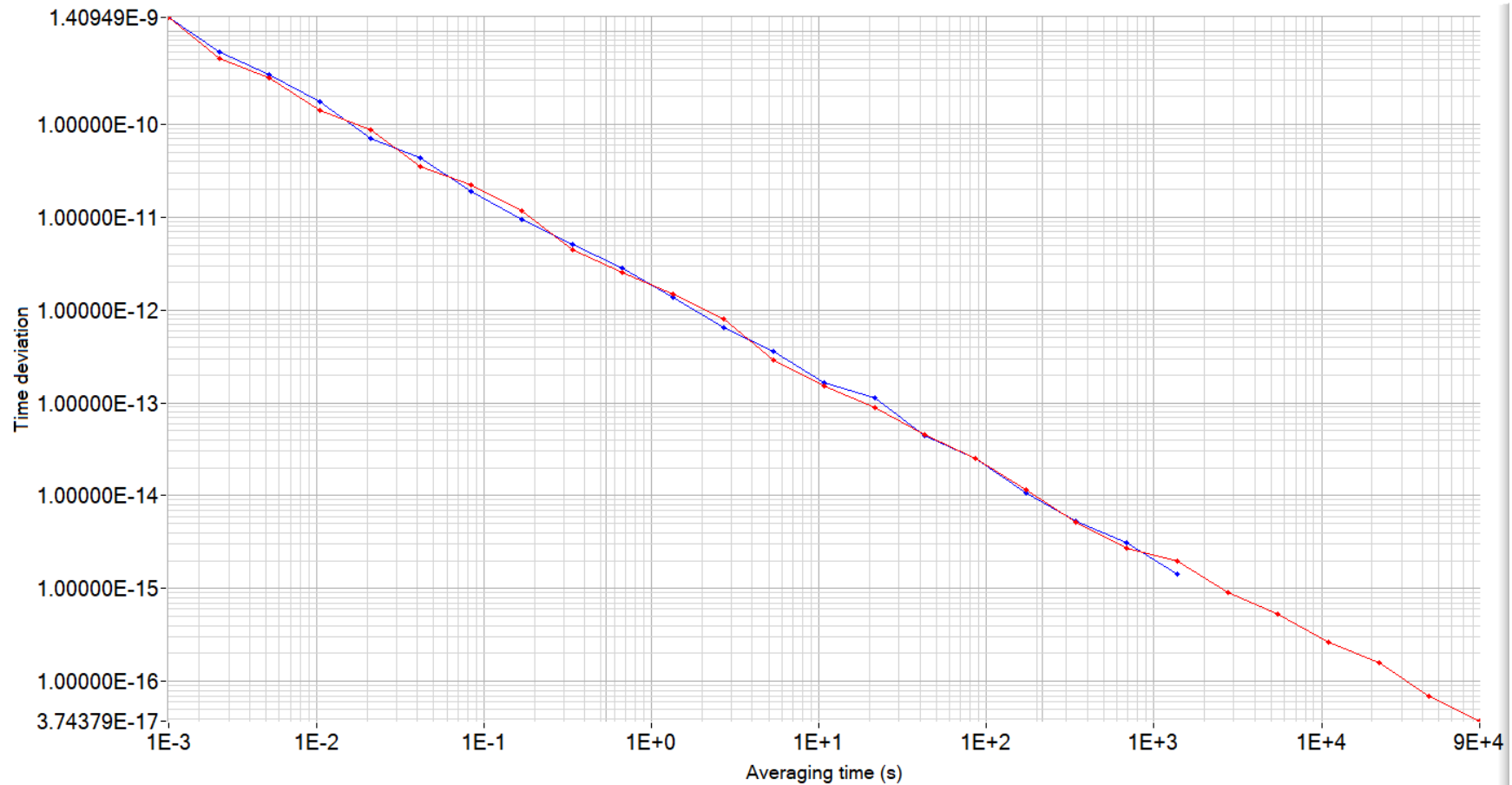


Averaging of the AUX signal position on 10 values



## Estimation of the synchronization output of the A040-ET

### Stability of the A040-ET synchronization output AUX



Alan deviation (blue - classic; red – with overlapping) for signal with period = 1310610 ns)





## *Estimation of the accuracy and precision of the ETBS*

Estimations of the accuracy and precision of the time-scale synchronization

| Timing system synchronization based on: | Accuracy, ps | Precision, ps |
|-----------------------------------------|--------------|---------------|
| A040-ET                                 | 28.6         | 6.2           |
| TET                                     | 77.4         | 10.6          |
| MTET                                    | 760          | 11.6          |
| MTET with T-correction                  | ≈100         | ≈6            |
| WR network                              | 495          | 36            |

