



INSTITUTE OF
ELECTRONICS AND
COMPUTER SCIENCE

NATIONAL
DEVELOPMENT
PLAN 2020



EUROPEAN UNION

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Eiropas Reģionālās attīstības fonda līdzfinansēts projekts Nr.1.1.1.1/16/A/174
„Laika sinhronizācija ar augstu precizitāti
sadalītai zinātnisku mērījumu sistēmai (DaLaS)”.

Taimera izstrāde JUNO projekta vajadzībām un tā parametru novērtēšana



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Jevgeņijs Buls Taimera izstrāde JUNO projekta vajadzībām un tā parametru novērtēšana

Architecture and operational principles of the TET

TET implementation and housing

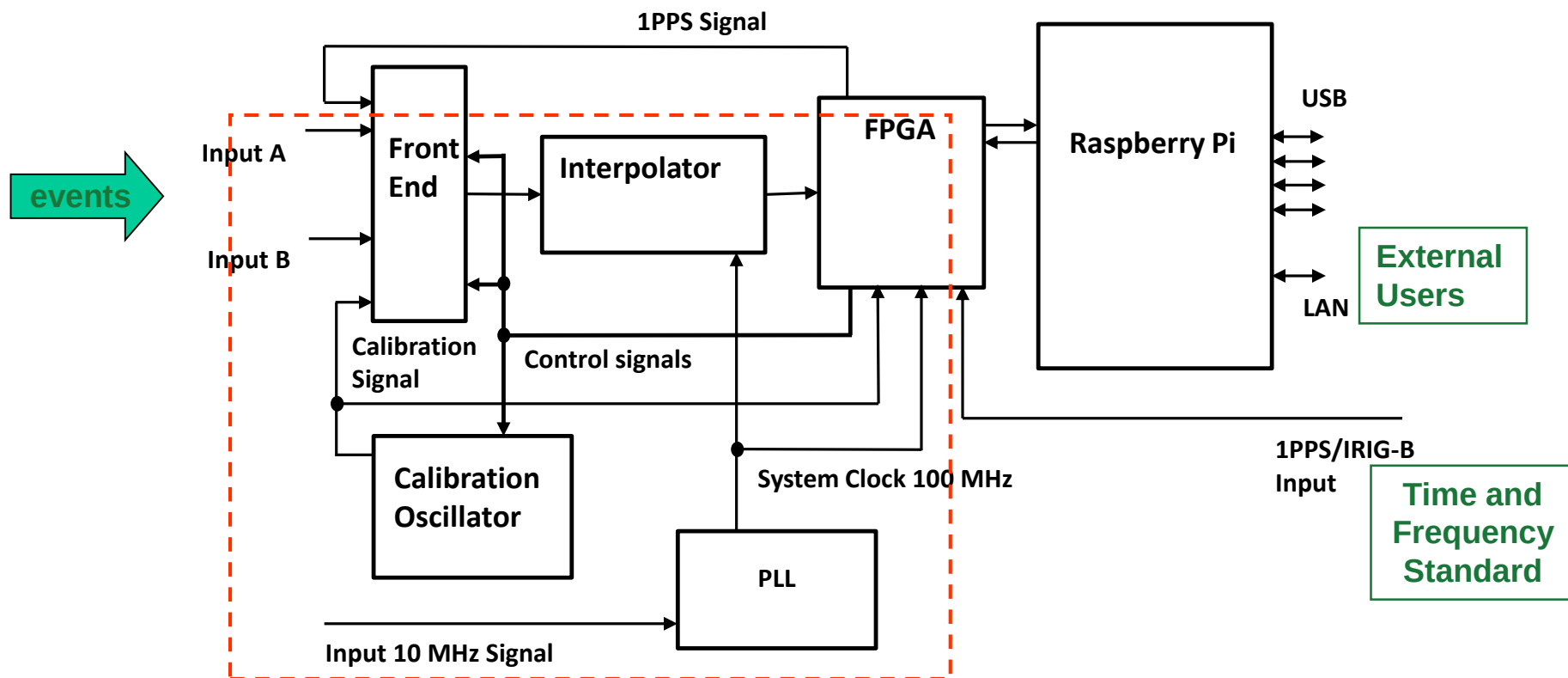
An example of application software for the TET

Estimation of the TET performance parameters:

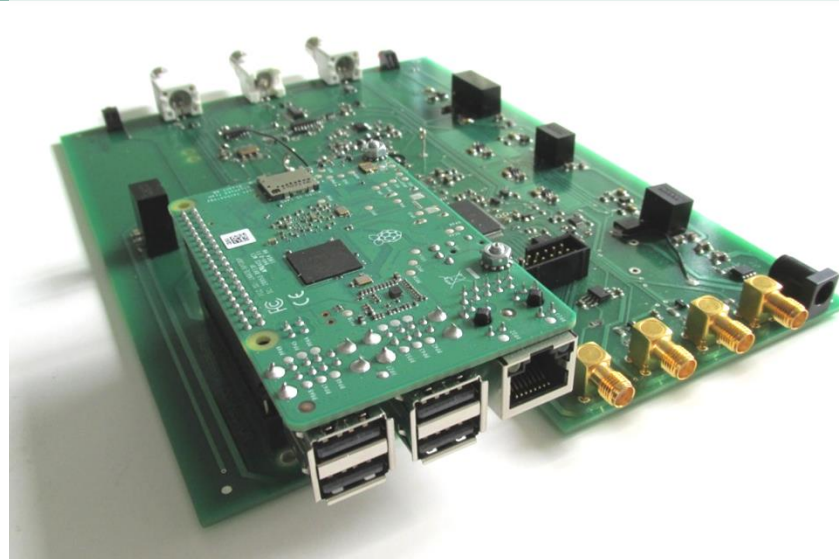
- Interval non-linearity errors
- Interpolator nonlinearity estimation
- Measurement uncertainty for short and long intervals
- TET precision dependence on temperature without calibration
- TET precision stability in temperature with recalibration
- ADC values deviation in temperature
- Input to input offset drift in temperature
- Single-input offset drift in temperature

TET full specification

Block diagram of the True Event Timer (TET)



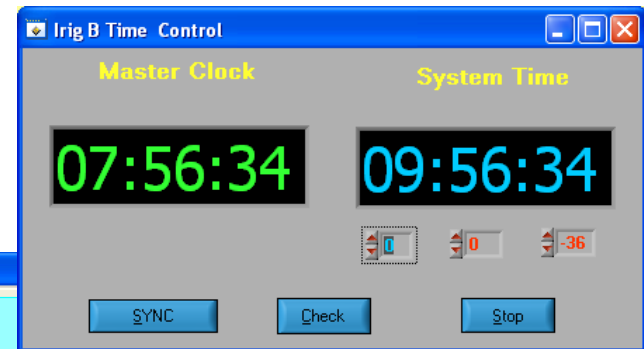
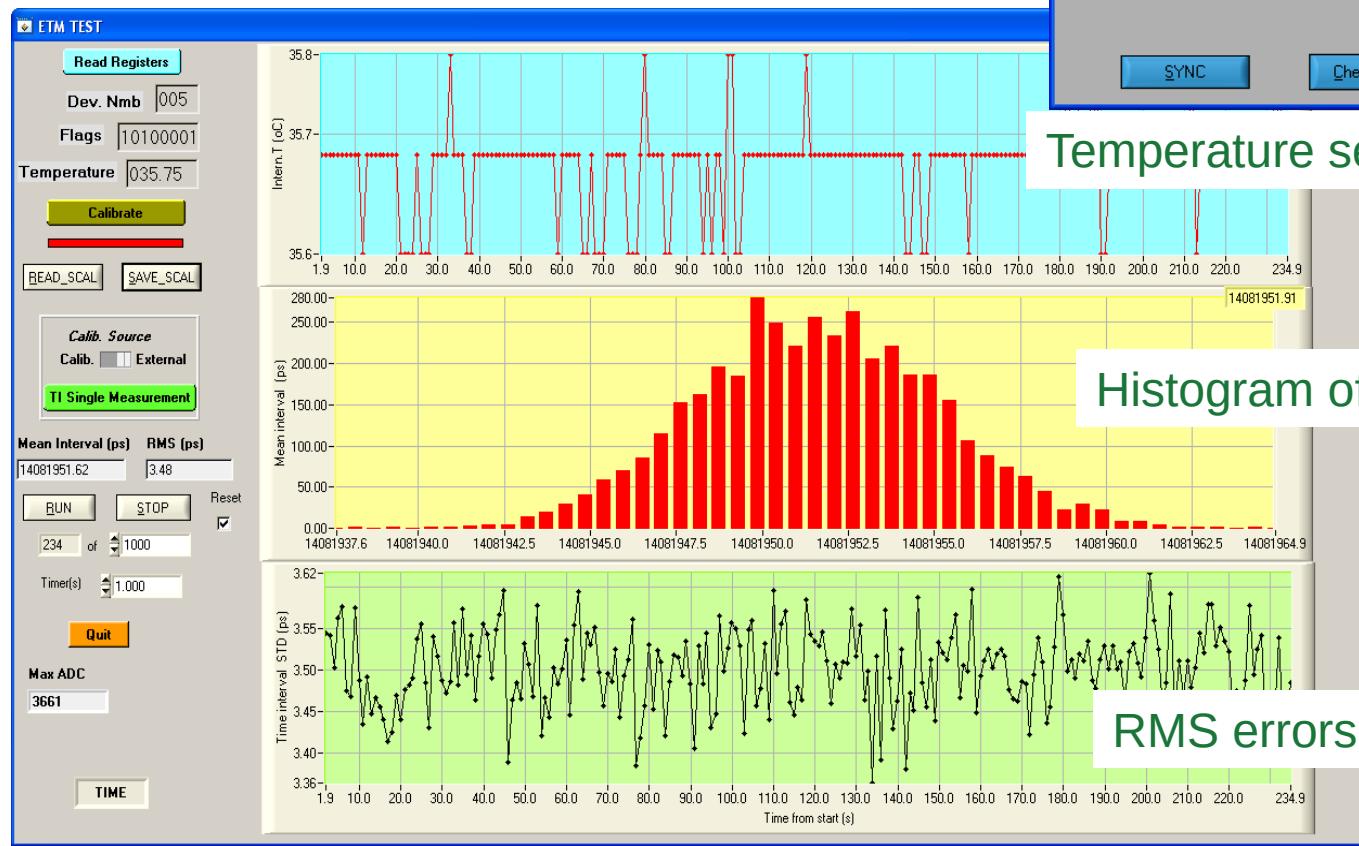
The timing module board
with on-board computer
Raspberry



Assembled True Event Timer in the Hammond enclosure

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Sample program for TET applications



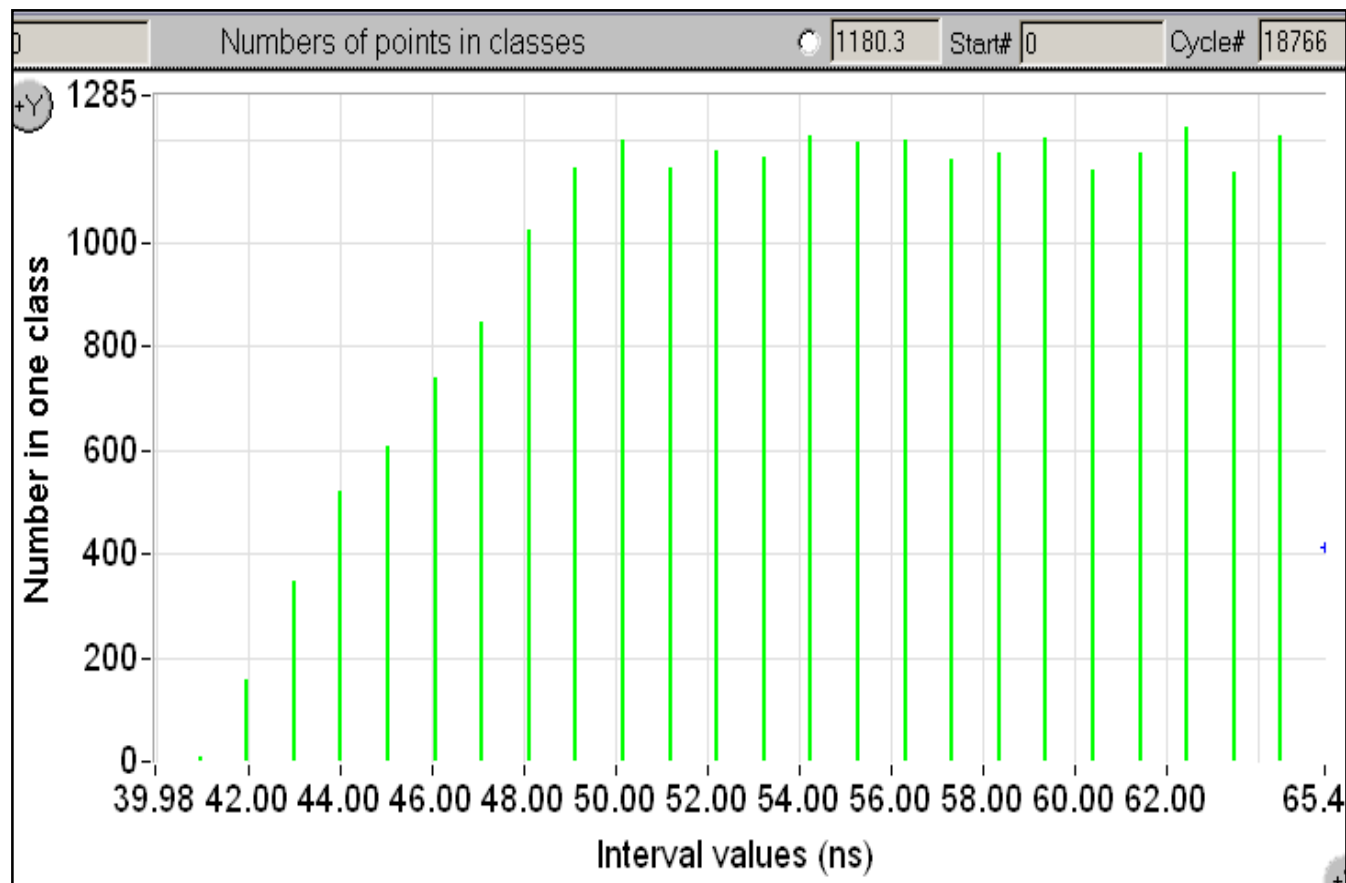
Temperature sensor readings

Histogram of 4K intervals

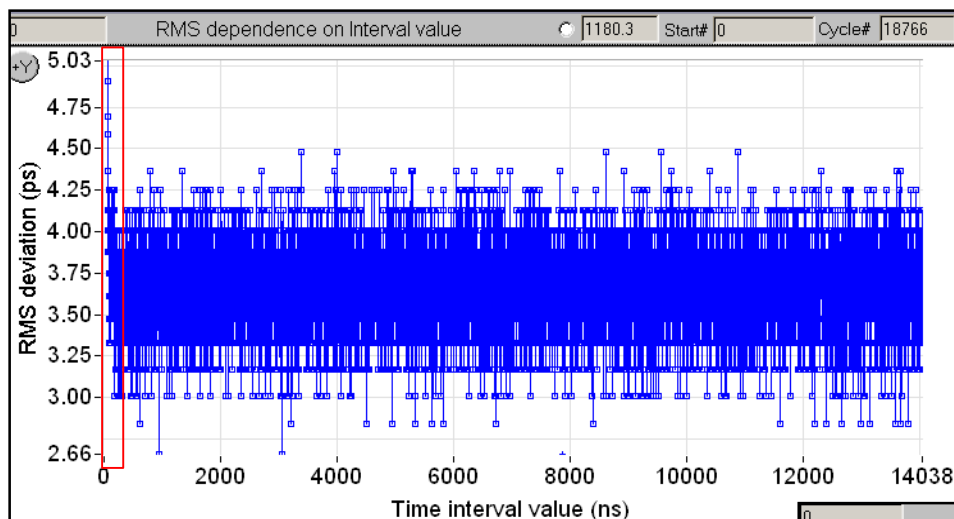
RMS errors for 4K intervals

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Dead-time estimation

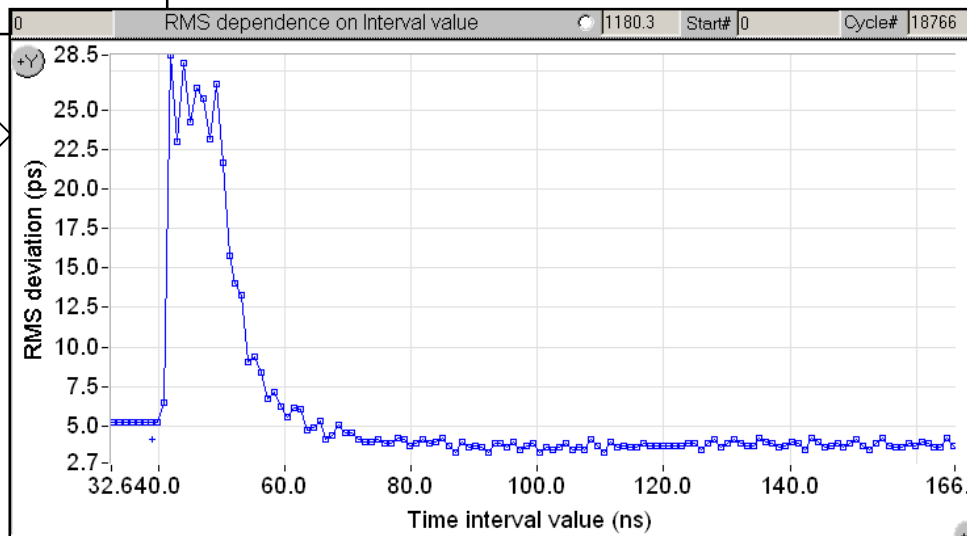


Measurement uncertainty dependence on interval value

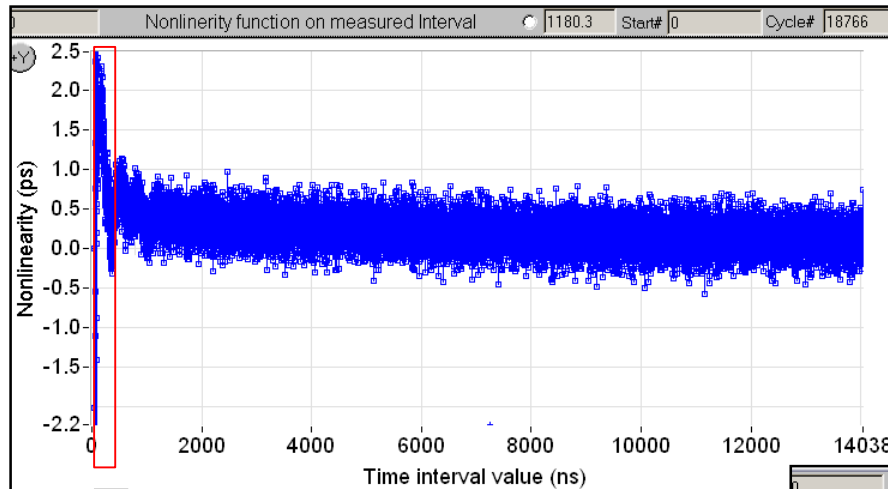


For events after 150 ns the measurement uncertainty is less than 4.5 ps

Measurement uncertainty for events close to the “dead time”

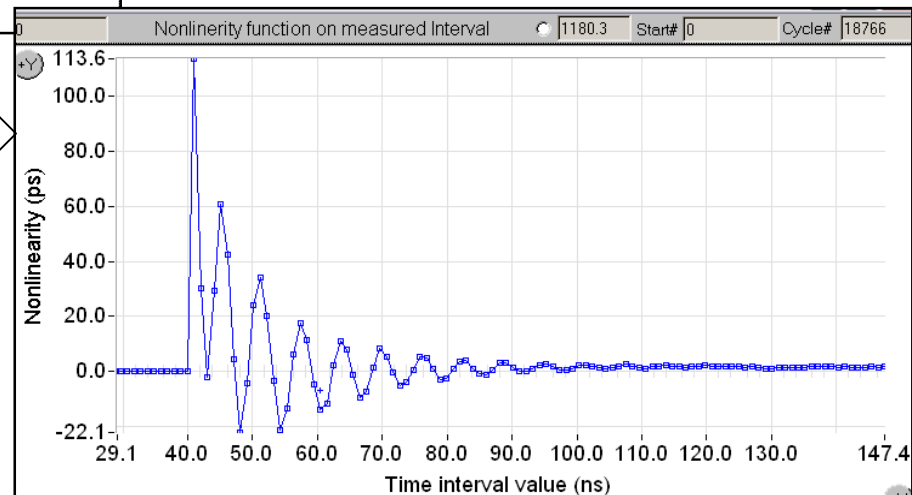


Interval non-linearity estimation

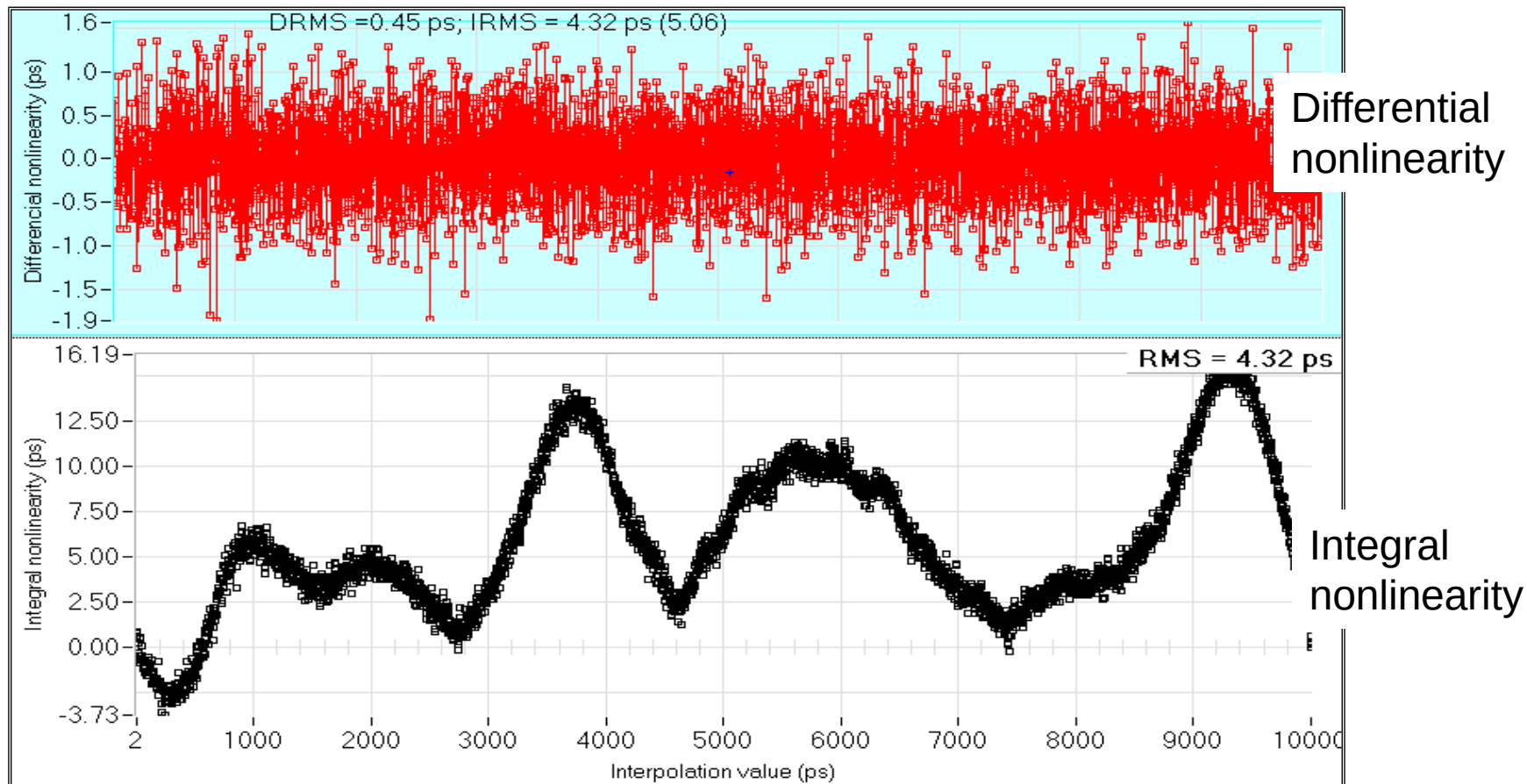


Interval nonlinearity for events after 150 ns is less than 1 ps

Interval nonlinearity for events close to the “dead time”

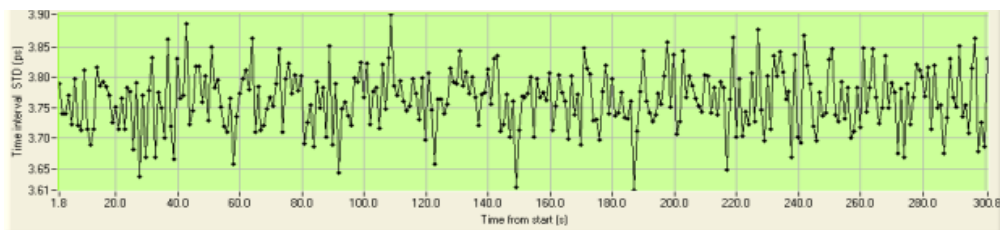


Differential and integral nonlinearities statistical estimation

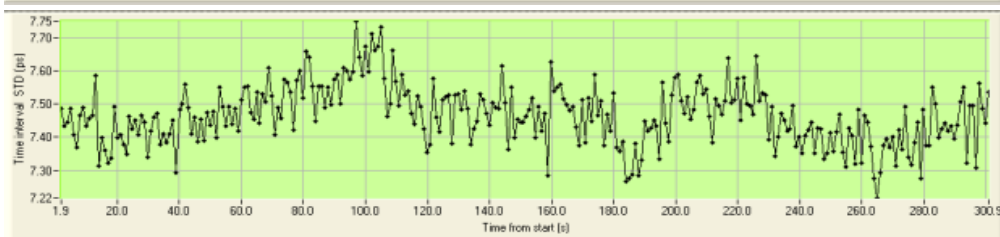


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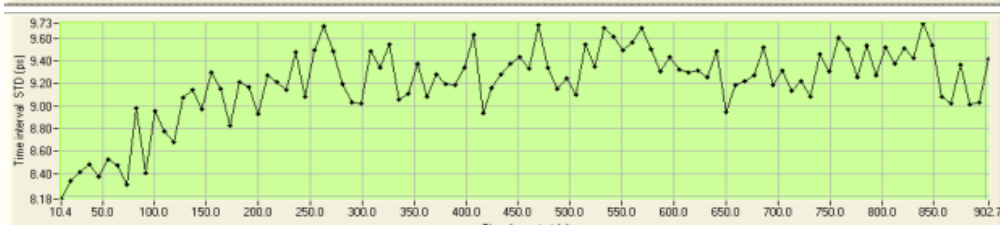
Measurement uncertainty depending on intervals (asynch)



T=199.97 ns
RMS = 3.8 ps

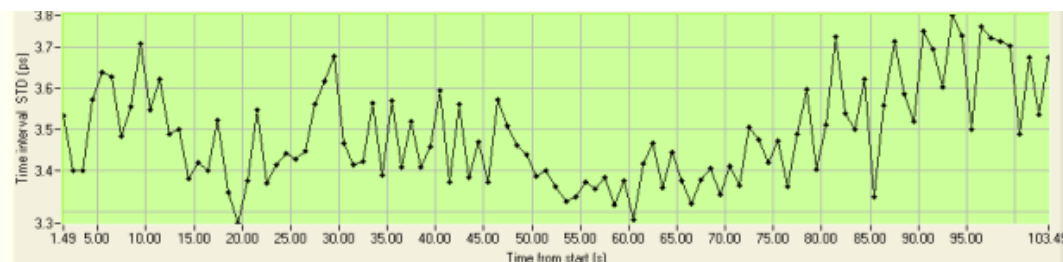


T=19996.95 ns
RMS = 7.5 ps

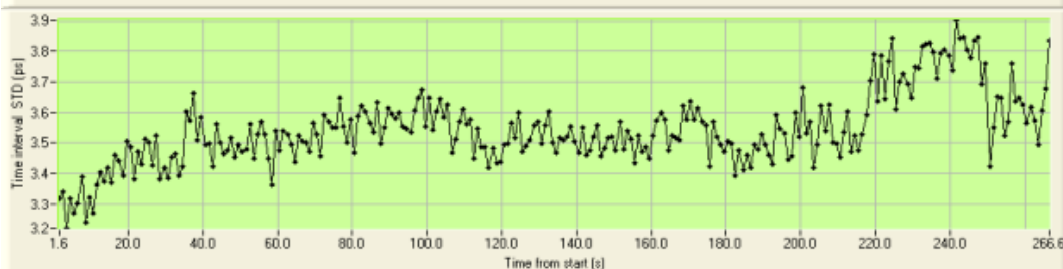


T=1999694.69 ns
RMS = 9.3 ps

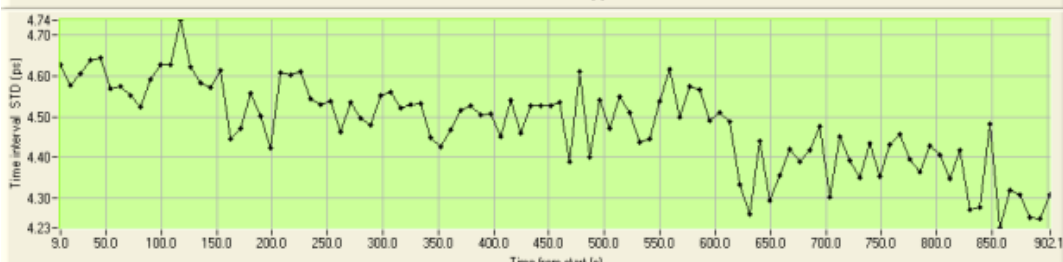
Measurement uncertainty depending on intervals (synch)



T=200.00 ns
RMS = 3.5 ps

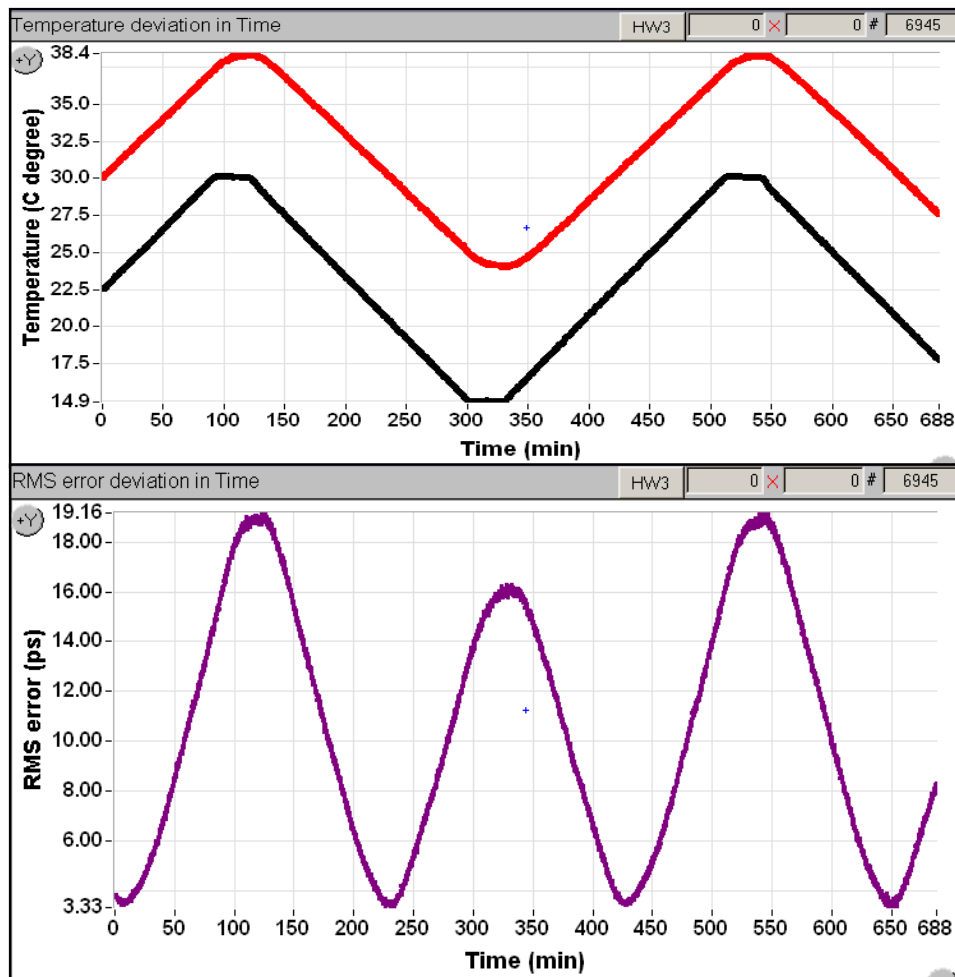


T=20000.00 ns
RMS = 3.6 ps



T=2000000.00 ns
RMS = 4.5 ps

Measurement uncertainty changes together with change of temperature (without recalibration)



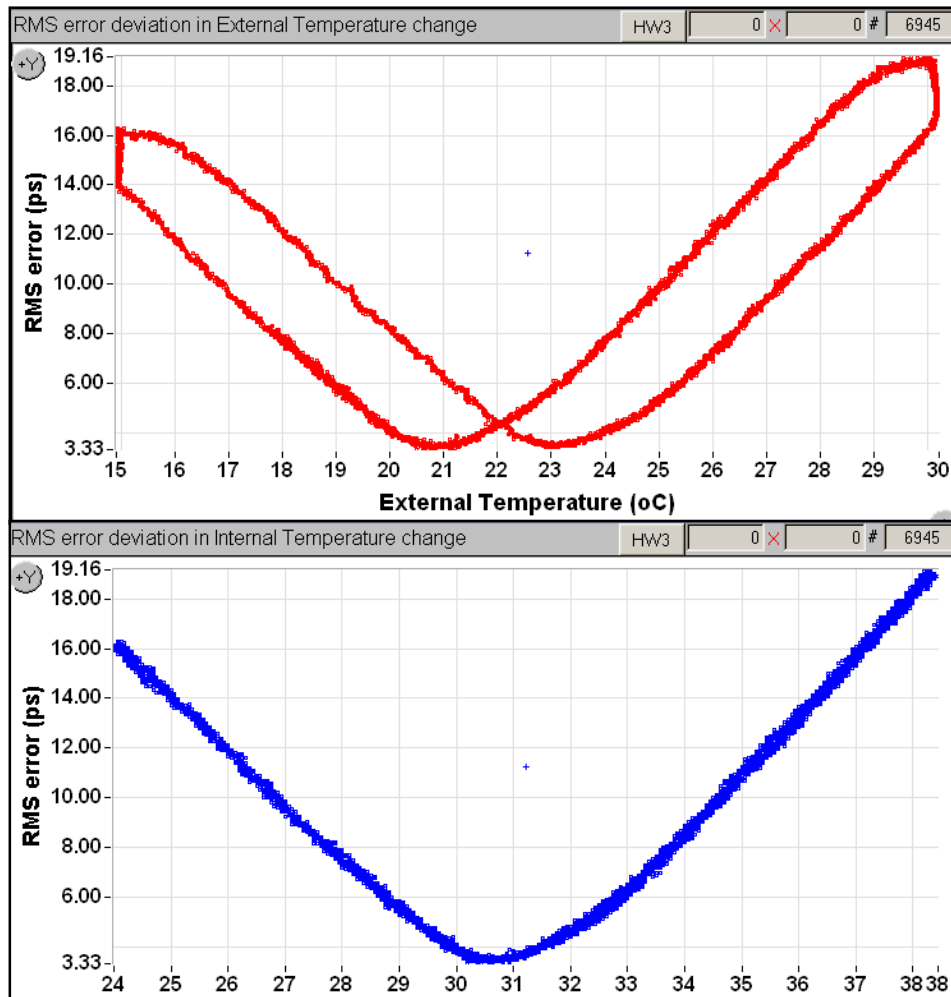
Internal temperature

External temperature

Measurement uncertainty

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Measurement uncertainty dependence on temperature without recalibration

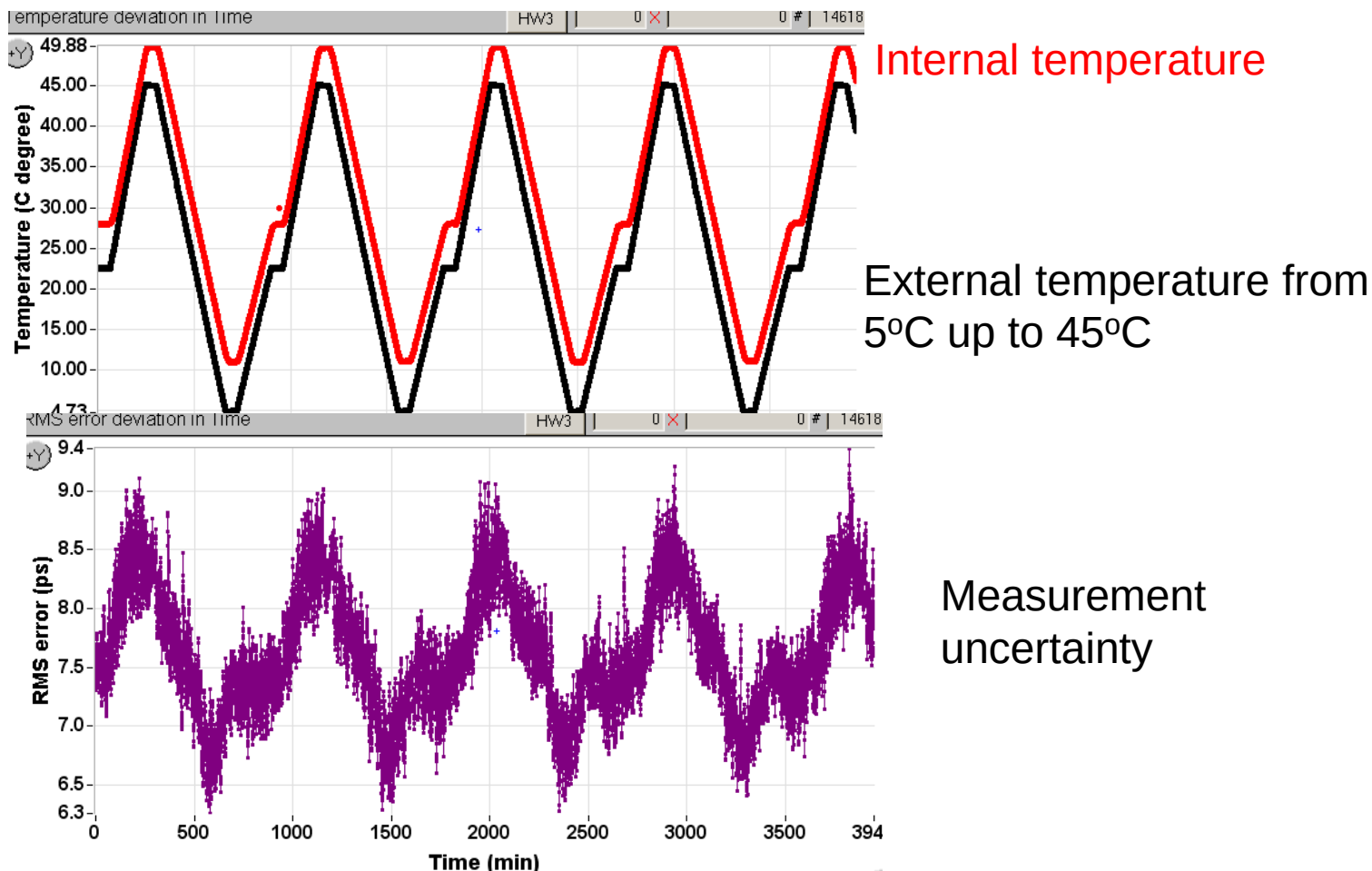


Uncertainty as function of the external temperature

Uncertainty as function of the internal temperature

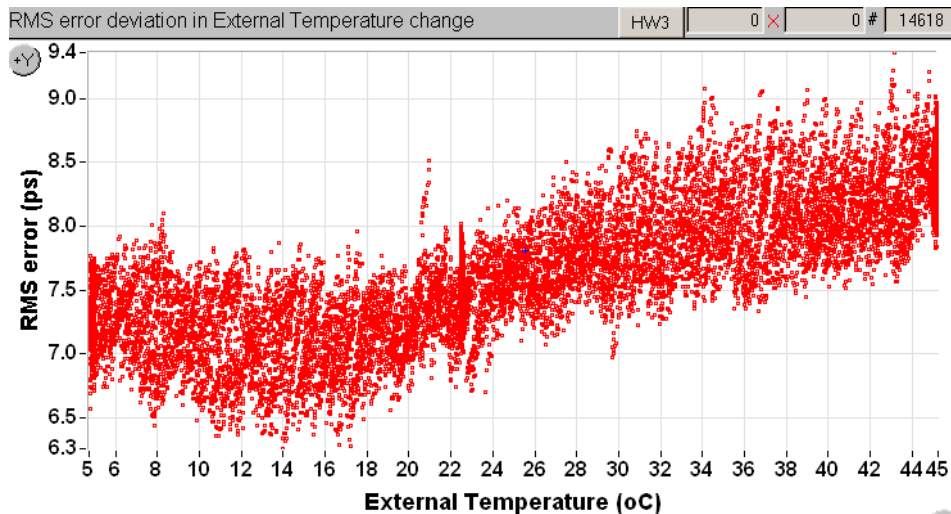
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Measurement uncertainty change together with change of temperature with regular recalibration

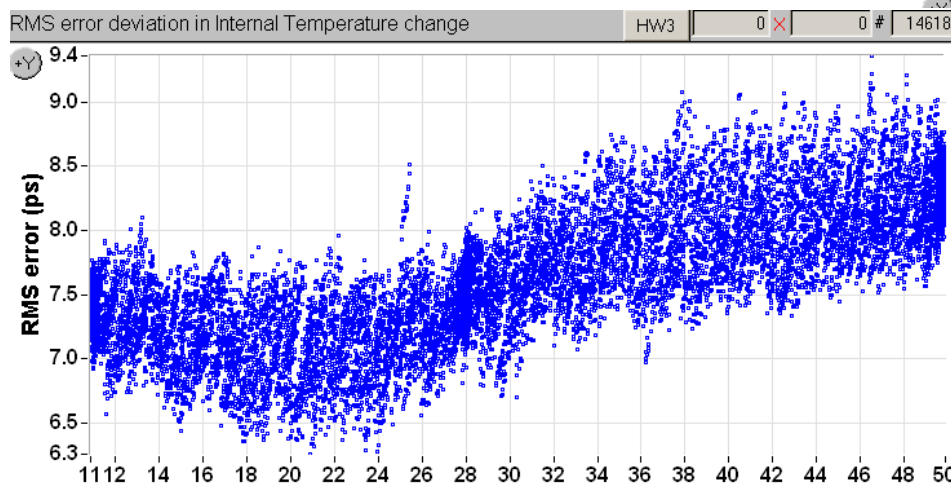


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Measurement uncertainty dependence on temperature with regular recalibration



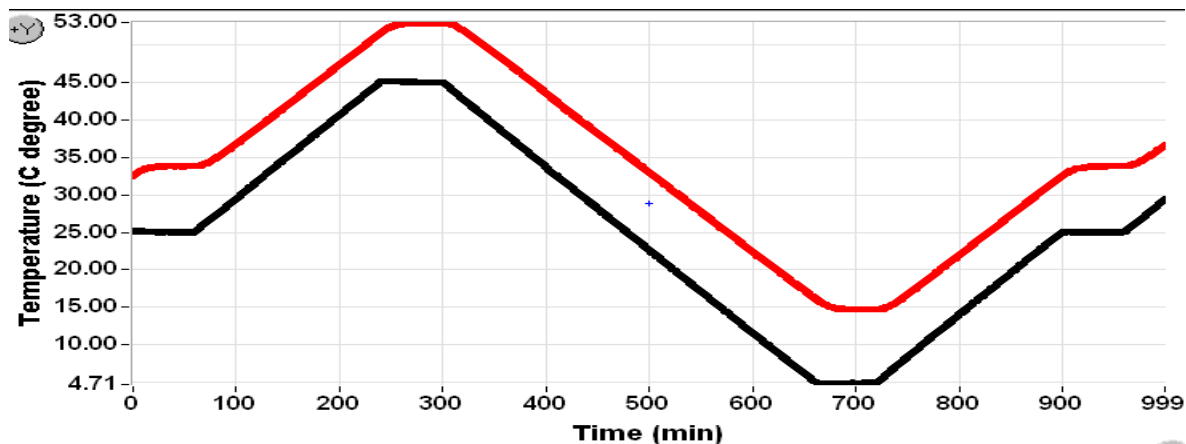
Uncertainty as function of the external temperature



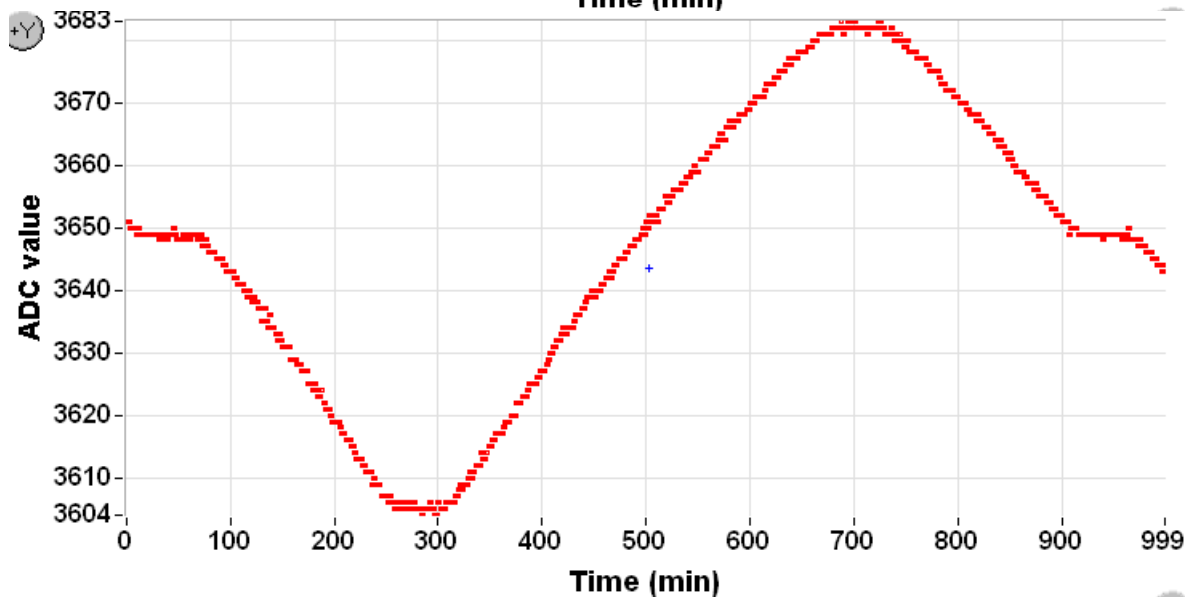
Uncertainty as function of the internal temperature

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Changes in temperature of ADC maximal values

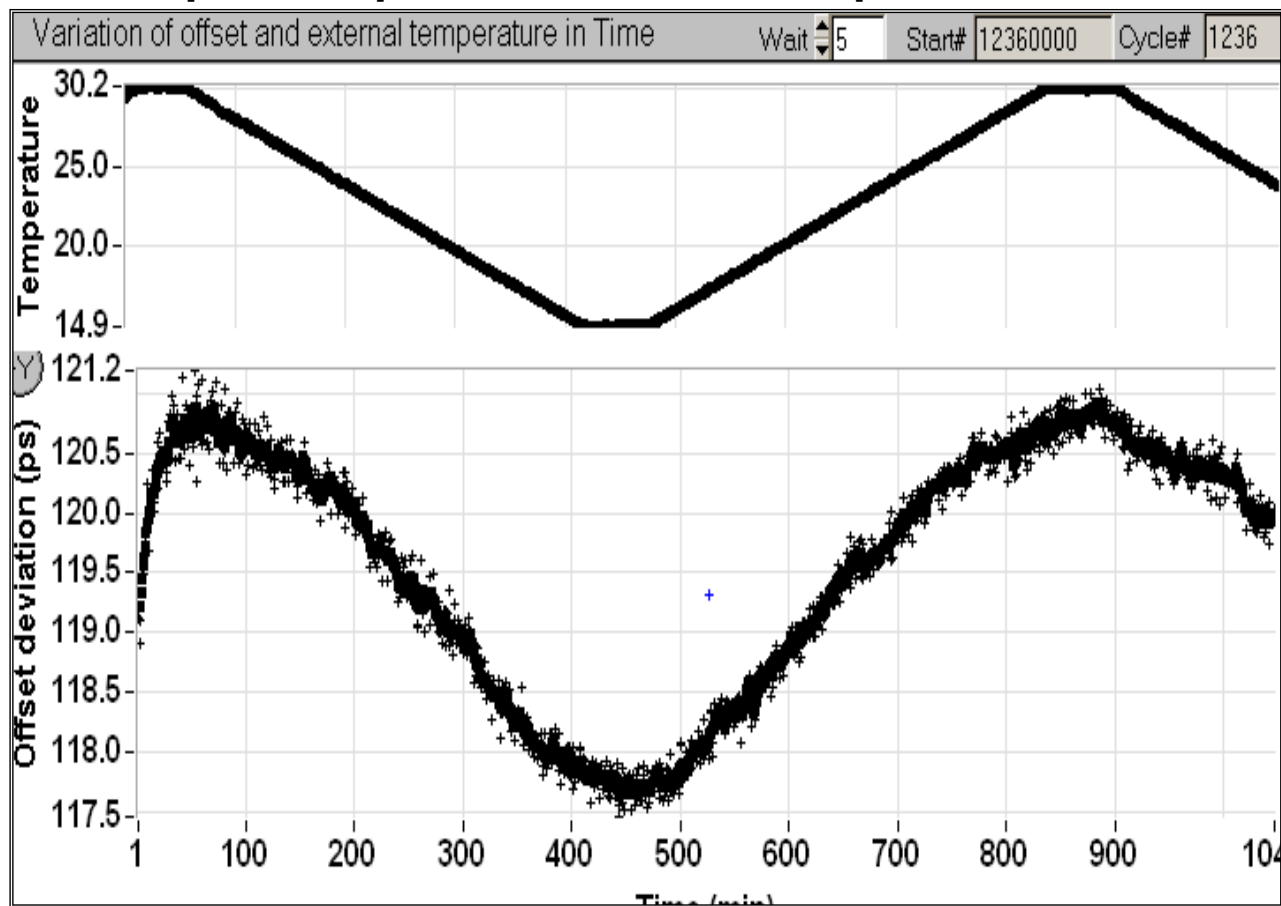


External temperature changes in the range from 5°C up to 45°C



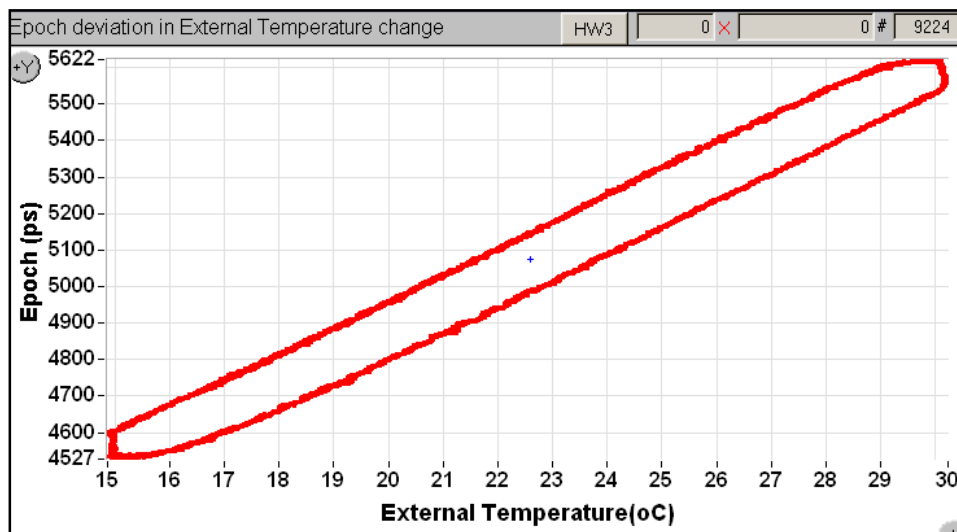
ADC values range changes in the range from 3683 down to 3604

Input to input offset drift in temperature

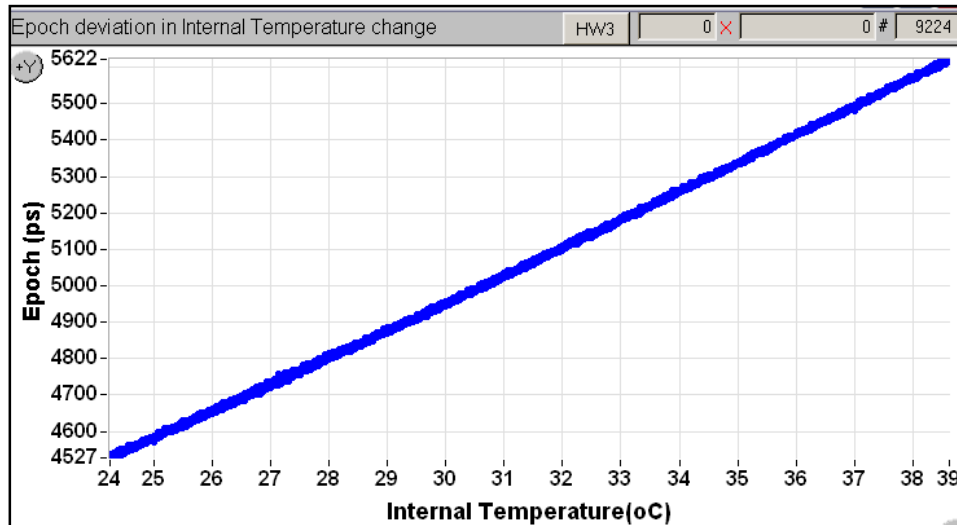


For temperature change from 15 °C up to 30 °C
the input-to-input drift is about 3 ps or 0.2 ps/°C

Single-input drift in temperature



Epoch value as a function of the external temperature



Epoch value as a function of the internal temperature

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Specification parameters of the True Event Timer

Specification parameters of the True Event Timer		
Circuit defined parameters:		Comments
time measurement range:	from 49 ns up to unlimited	Timing module has upper limit 343.6 s and can be increased.
least significant bit	2.5 ps	
dead-time	50 ns	
buffer memory (time-tags)	4K	
Precision specifying parameters:		
Measurement uncertainty for intervals: including:	9.3 ps	To be eliminated
Integral nonlinearity	4.3 ps	To be eliminated
Interval nonlinearity	< 1 ps	For intervals > 200 ns
Result dependence on temperature:		
Input-to-input offset drift	0.2 ps/°C	To be eliminated
Single input deviation	73 ps/°C	